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MICROCOMPUTER-BASED PNEUMATIC CONTROLLER FOR NEUTRON ACTIVATION ANALYSIS

J. S. BYRD and R. J. SAND



**SAVANNAH RIVER LABORATORY
AIKEN, SOUTH CAROLINA 29801**

PREPARED FOR THE U.S. ENERGY RESEARCH AND DEVELOPMENT ADMINISTRATION UNDER CONTRACT AT(07-2)-1

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by

J. S. Byrd and R. J. Sand

Approved by

D. Baker, Manager
Laboratory Operations and Services

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**E. I. DU PONT DE NEMOURS AND COMPANY
SAVANNAH RIVER LABORATORY
AIKEN, SOUTH CAROLINA 29801**

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ABSTRACT

A microcomputer-based pneumatic controller for neutron activation analysis was designed and built at the Savannah River Laboratory. In this system, commercially available microcomputer logic modules are used to transport sample capsules through a network of pressurized air lines. The logic modules are interfaced to pneumatic valves, solenoids, and photo-optical detectors. The system operates from programs stored in firmware (permanent software). It also commands a minicomputer and a hard-wired pulse height analyzer for data collection and bookkeeping tasks. The advantage of the system is that major system changes can be implemented in the firmware with no hardware changes. This report describes the hardware, firmware, and software for the electronics system.

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MICROCOMPUTER-BASED PNEUMATIC CONTROLLER FOR NEUTRON ACTIVATION ANALYSIS

INTRODUCTION

The National Uranium Resource Evaluation (NURE) is a program by the United States Energy Research and Development Administration to locate potential supplies of uranium ore to supply the future needs of the country. Under this program, large numbers of geologic samples are acquired from the entire country, and the samples subsequently are analyzed by radiochemical spectral techniques. The Savannah River Laboratory is responsible for the NURE program in the eastern United States.

A pilot-scale neutron activation facility has been developed by Savannah River Laboratory to analyze the NURE samples with minimal manual operations. The NURE Activation Facility¹ consists of a control center module (CCM) trailer, a pneumatic transport system, and a reactor irradiation chamber (RIC). The CCM houses the pneumatic control system, detectors and spectra acquisition equipment, and half of the pneumatic system valving. The reactor irradiation chamber is mounted against the moderator tank wall of a production reactor at the Savannah River Plant. The other half of the pneumatic system valving is in the reactor tank service area near the RIC. The CCM is located immediately outside the reactor building and is connected to RIC pneumatic piping. The transport time of sample rabbits (or between the CCM and RIC) is approximately 1-1/2 seconds. Samples are contained in devices called rabbits for rapid movement into and out of an irradiation field.

An electronic control system was required to control the transportation of sample rabbits from a loading port, through a series of irradiation cycles in several reactor tubes, through counting intervals at one of two counting ports (D1 and D2), and to an unloading port at the end of the tests (Figure 1). Four activation regimes are defined in Table 1. Figure 2 shows a photograph of the controller. Design criteria for the controller were:

- The system could operate all necessary control valves to transport the rabbits through a schedule of radiation-count cycles defined in Table 1. The regime schedule of any given sample rabbit could be modified based on analysis results of some previous cycle.

- The system could trace a rabbit through various cycles, identify its location at any time, inform the operator if a rabbit fails to reach a programmed destination, and identify the present location.
- Two analyzer systems, a PDP-9 minicomputer system and a Canberra 8100 multichannel analyzer, could be controlled by hand-shaking techniques.

TABLE 1

Definition of Regimes

<i>Regime</i>	<i>Description</i>
A	One short irradiation and one short gross activity measurement. When gross activity exceeds limits, the sample is prevented from receiving further analysis.
B	Several cycles of short irradiation and short counts.
C	One long irradiation and one intermediate-length count.
D	No irradiation, but one intermediate-length count for each rabbit not rejected in Regime A. Counting is done in off hours separately from analyses of Regimes A, B, and C.

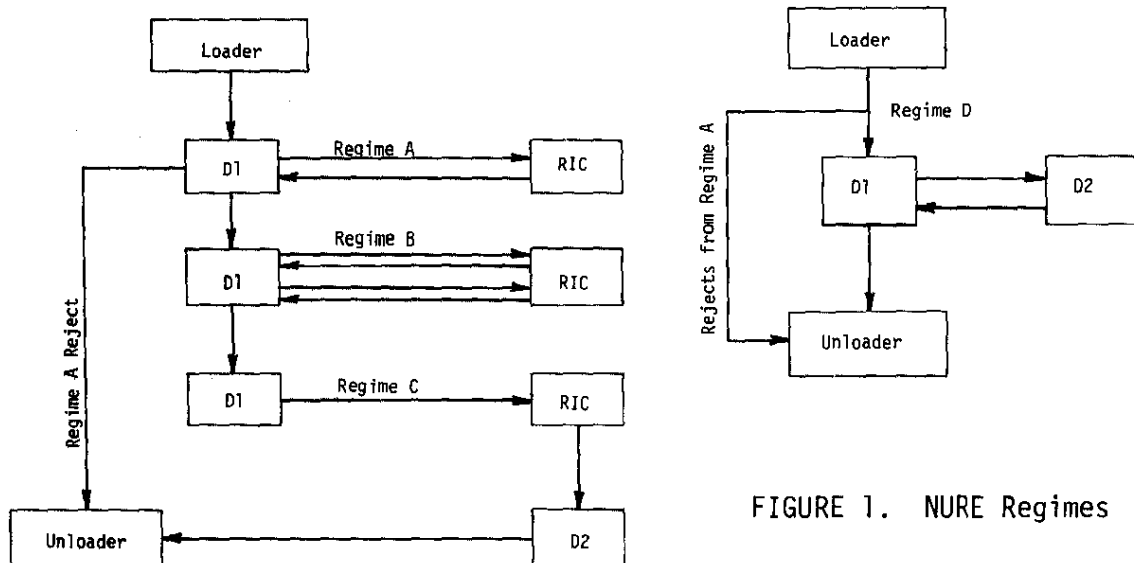


FIGURE 1. NURE Regimes

A digital system incorporating state-of-the-art technology was designed for the electronic control system, called the NURE Rabbit Controller. The base for the programmable electronic controller is a commercially available modular microcomputer system.² These modules include a second-generation microprocessor, the Intel 8080,³ as its central processor. This central processor is a large-scale-integration integrated-circuit component that contains the central processing circuitry found in a small, 8-bit parallel computer. A digital interface connects the microcomputer to various input and output devices associated with the NURE pneumatic and analysis equipment. Operating programs for the NURE Rabbit Controller are stored in erasable programmable read-only memories (EPROMs) that constitute the system firmware.

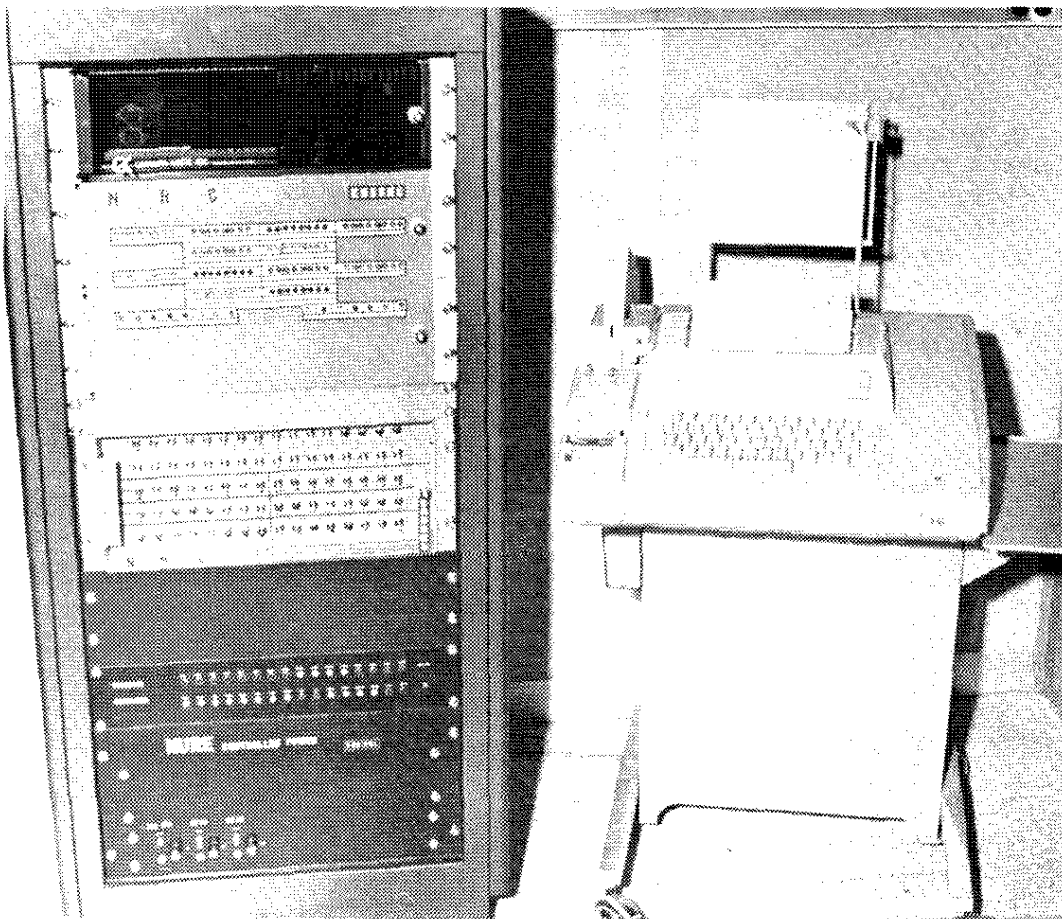


FIGURE 2. NURE Rabbit Controller

SYSTEM DESCRIPTION

Hardware

A block diagram of the major hardware components for the NURE Rabbit Controller is shown in Figure 3. M-Series logic modules from Control Logic, Inc. (plug-in, printed circuit cards) were used in designing the microcomputer (Table 2). The basic commercial system was modified to provide additional signals at the input/output (I/O) connector. The I/O terminal is an ASR-33 *Teletype* (Registered trademark of Teletype Corp.) used for input commands and output messages to the operator. A 256 x 8-bit random access memory (RAM) provides temporary storage for the systems programs. A 3.5K x 8-bit EPROM contains the firmware for the NURE Rabbit Controller.

A digital interface was designed to connect the microcomputer to process peripherals of the NURE pneumatic rabbit system. Signals from the I/O connector (Table 3) were connected to binary hexi-decimal-to-decimal decoder modules to produce 16 system input signals, IN 20-IN37, and 32 system output signals, OUT 40-OUT 57 and OUT 100-OUT 117 (Figure 4). These I/O signals are used for the various operations required by the pneumatic rabbit controller, the PDP-9 computer, and the Canberra 8100 analyzer (Table 4).

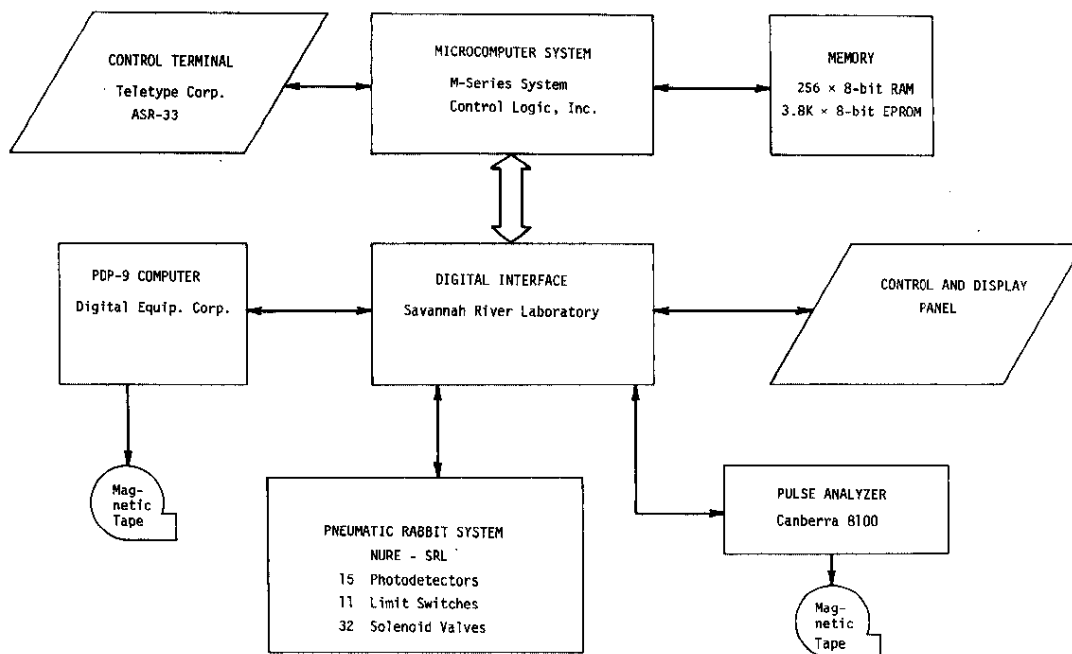


FIGURE 3. Block Diagram of Major Hardware for the NURE Rabbit Controller

TABLE 2

M-Series Logic Modules in Hardware for the NURE Rabbit Controller

<i>Quantity</i>	<i>Model</i>	<i>Description</i>
1	MCP-893	Central processing unit
1	MIM-894	Memory and input/output control
1	MDM-895	Data bus - multiplexer
1	MPI-810	Priority interrupt control
1	MCC-814	Console control
2	LDD-503	Device decoder
1	LTI-513	Teletypewriter interface
1	LRC-531	Real time clock
1	LRM-597	256-byte RAM
8	LRM-596	512-byte EPROM
5 ^a	LRM-598	1K-byte RAM
1	CGI-540	System instrument cage (powered)

a. Used only during system development. Not permanently installed.

TABLE 3

Microcomputer Signals

<i>Signal Name</i>	<i>Description</i>
A00 - A15	Address bus, 15 bits, 64K address
DI0 - DI7	Input data bus, 8 bits
I00 - I017	I/O select lines, 16 bits, each line to select a group of 16 I/O pulses
OUTS	Low pulse when output instruction is being executed
INS	Low pulse when input instruction is being executed
D0 - D7	Output data bus, 8 bits

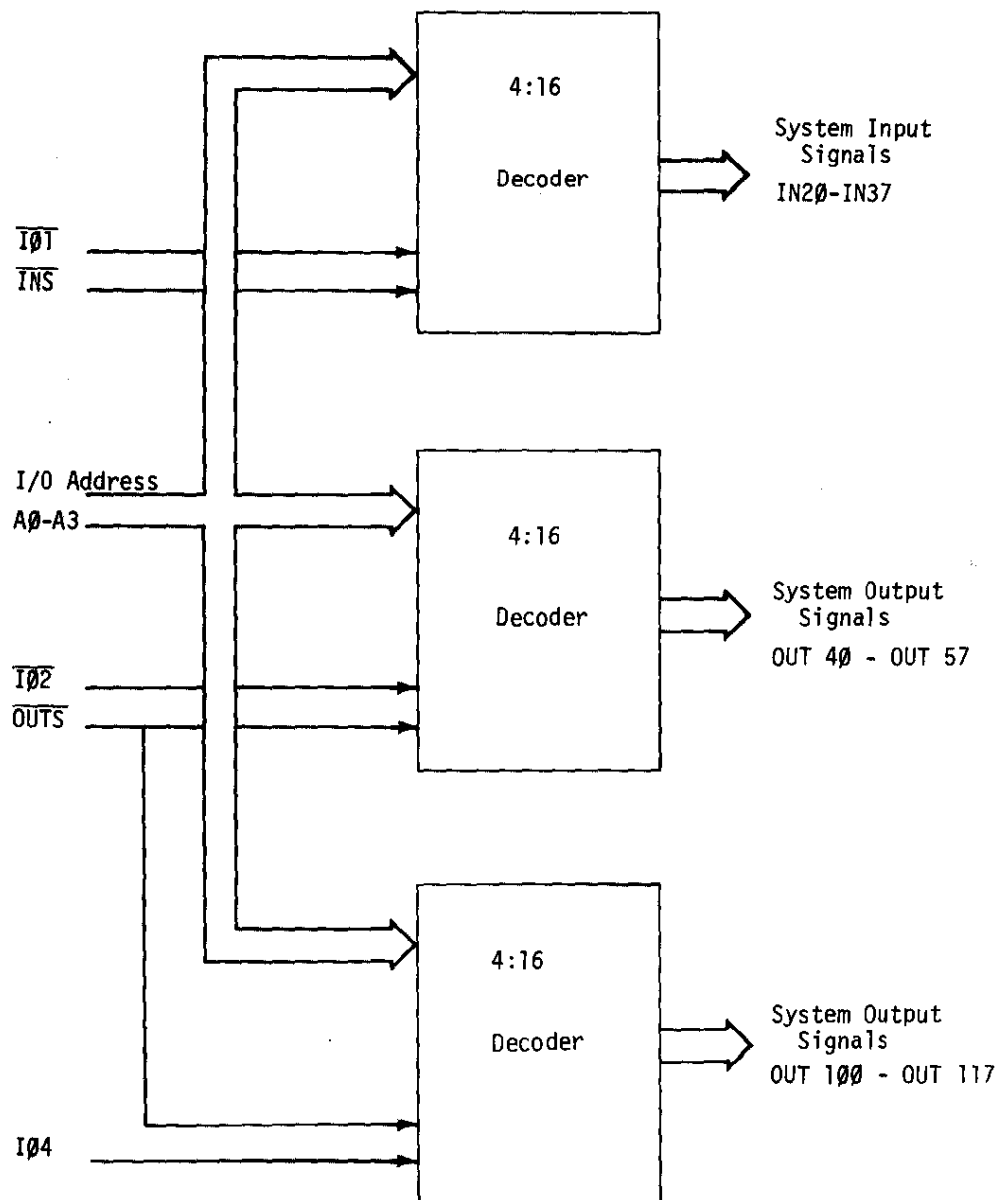


FIGURE 4. Input/Output Decoders

TABLE 4

Input/Output Commands

<i>Signal Name</i>	<i>Program Instruction Mnemonic</i>	<i>Description</i>
IN 20	IN 20	Inputs 8-bit word PD1 (photodetector status)
IN 21	IN 21	Inputs 8-bit word PD2 (photodetector status)
IN 22	IN 22	Inputs 8-bit status word, LS3 (status of limit switches for diverter valves)
IN 23	IN 23	Inputs 8-bit status word, LS4 (status of limit switches for loader and unloader)
IN 24	IN 24	Inputs 8-bit word STW5 (PDP-9 Canberra status)
IN 25	IN 25	Inputs 8-bit word PDT1 from PLA (photodetector test)
IN 26	IN 26	Inputs 8-bit word PDT2 from PLA (photodetector test)
IN 27	IN 27	Inputs 8-bit word TBL (abort status)
IN 30 - IN 37	-	Spare input pulses
OUT 40	OUT 40	Outputs pulse CLPD1 to clear PD1 status word
OUT 41	OUT 41	Outputs pulse CLPD2 to clear PD2 status word
OUT 42	OUT 42	Outputs pulse CLTBL to clear TBL status word
OUT 43	OUT 43	Outputs starting address to PLA register
OUT 44	OUT 44	Outputs pulses to solenoid driver latches
OUT 45 - OUT 46	-	Spare output pulses
OUT 47	OUT 47	Outputs PI (program interrupt) at D1 to PDP-9; PID1 pulse
OUT 50	OUT 50	Outputs PI at irradiation chamber to PDP-9; PIRIC pulse
OUT 51	OUT 51	Outputs PI to PDP-9 at the beginning of Regime C; PIC pulse
OUT 52	OUT 52	Outputs PI to PDP-9. Chamber full - PIF pulse
OUT 53	OUT 53	Auxiliary PI to PDP-9
OUT 54	OUT 54	Outputs pulse to panel light
OUT 55 - OUT 56	-	Spare output pulses
OUT 57	OUT 57	Outputs clear pulse to PDP-9 interrupt flags
OUT 100	OUT 100	Sets real time clock frequency
OUT 101	OUT 101	Outputs pulse SD2C to start D2 counter to collect
OUT 102	OUT 102	Outputs clear pulse CLD2 to D2 memory
OUT 103	OUT 103	Outputs pulse to panel wait indicator lamp
OUT 104	OUT 104	Outputs pulse SD2I0 to start D2 I/O mode
OUT 105	OUT 105	Outputs SD2DS to start D2 display mode

Transporting rabbits to various locations in the system required the activation of 32 pneumatic valves controlled by electrical solenoids. The firing order of the valves had to be easily programmable in the prototype system. Six 256 x 8-bit EPROMs were connected in a programmable logic array (PLA). The address input to the PLA is latched into an 8-bit register when the output instruction OUT 43 is executed by the microcomputer program (Figure 5). Output data from four EPROMs in the PLA provide central signals to 32 flip-flops that drive the solenoids. The solenoids are activated by an OUT 44 instruction in the program (Figure 6). The remaining two EPROMs of the PLA provide two 8-bit status words, PDT1 and PDT2, that are input to the microcomputer during the IN 25 and IN 26 instructions (Figure 7). These status words constitute a testing sequence to trace the rabbits through the system with photodetectors.

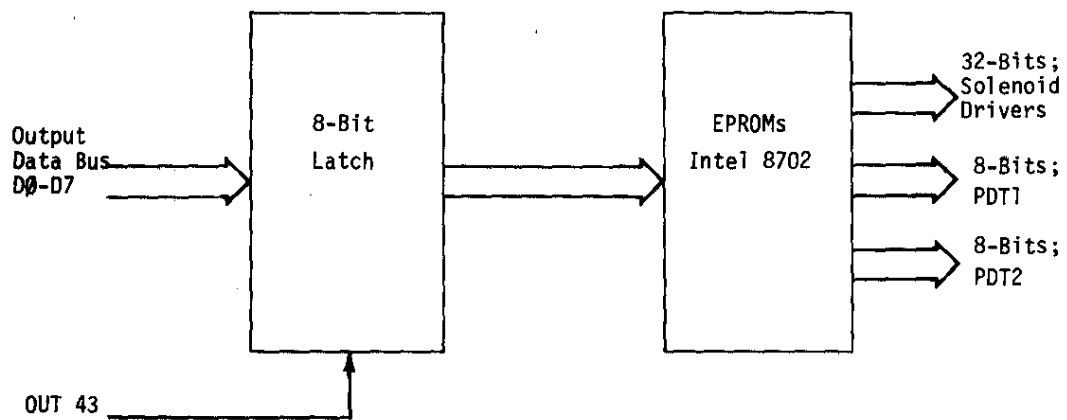


FIGURE 5. Programmable Logic Array

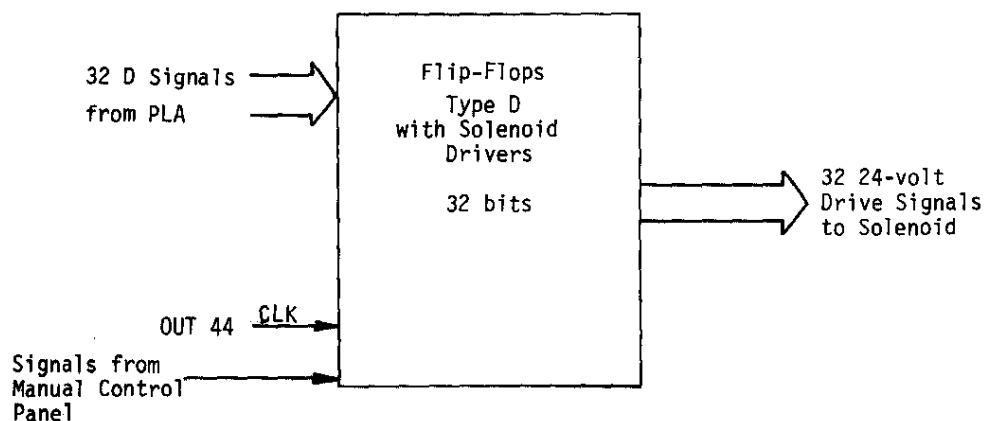


FIGURE 6. Output from Solenoid Drivers

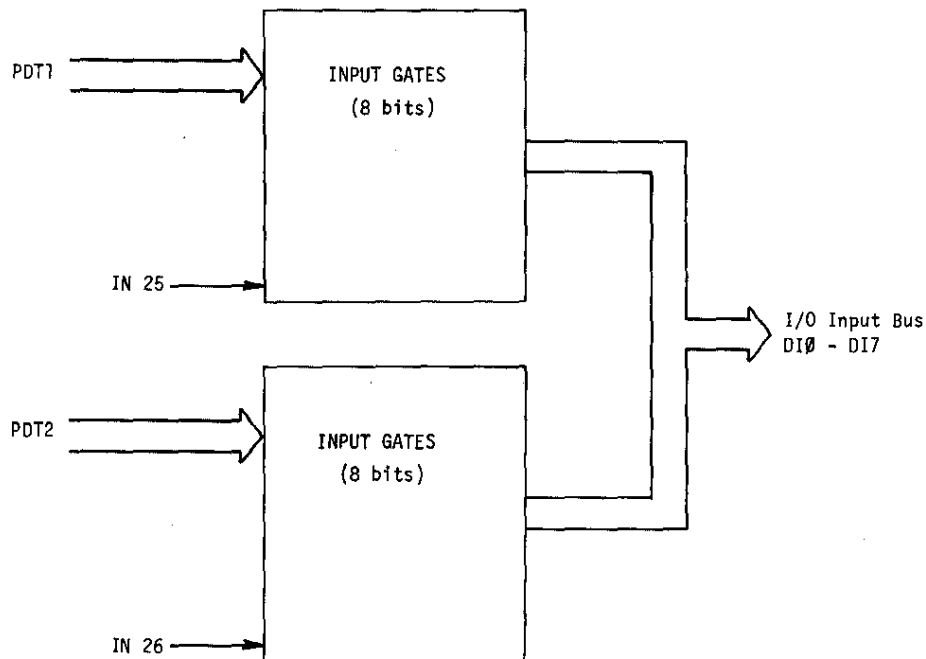


FIGURE 7. Input for the Photodetector Test

Two additional 8-bit input status words LS3 and LS4 are read by the microcomputer during instructions IN 22 and IN 23; they indicate the positions of pneumatic switches in two diverter boxes (Figure 8). As the rabbit is transported through the tubes, photodetectors transmit pulses that are latched in two 8-bit flip-flop registers (Figure 9). The photodetector status words PD1 and PD2 are read by IN 20 and IN 21 instructions; the registers may be cleared by OUT 40 and OUT 41 instructions.

Several conditions in the process — low air pressure, loss of power, high temperature, etc. — call for an abort operation. An 8-bit status word TBL is read by the program with IN 27 instructions. The TBL latches may be cleared with OUT 42 instructions (Figure 10).

The NURE Rabbit Controller was interfaced to the PDP-9 computer that functions primarily as an analyzer at detector position D1 in the pneumatic process. Also, control signals were connected to a Canberra 8100 analyzer at detector position D2. An 8-bit status work STW5 is read by IN 24 and cleared by OUT 57 (Figure 11). The microcomputer sends four program interrupt requests to the PDP-9; these must be acknowledged by the PDP-9 before the controller can continue its logical sequence (Figure 12). Four output signals command the modes of the Canberra analyzer (Figure 13); its status is tested by the microcomputer in STW5.

A manual control panel overrides the automatic functions in the NURE Rabbit Controller (Figure 14). Status indicator lamps aid in troubleshooting faults in the system.

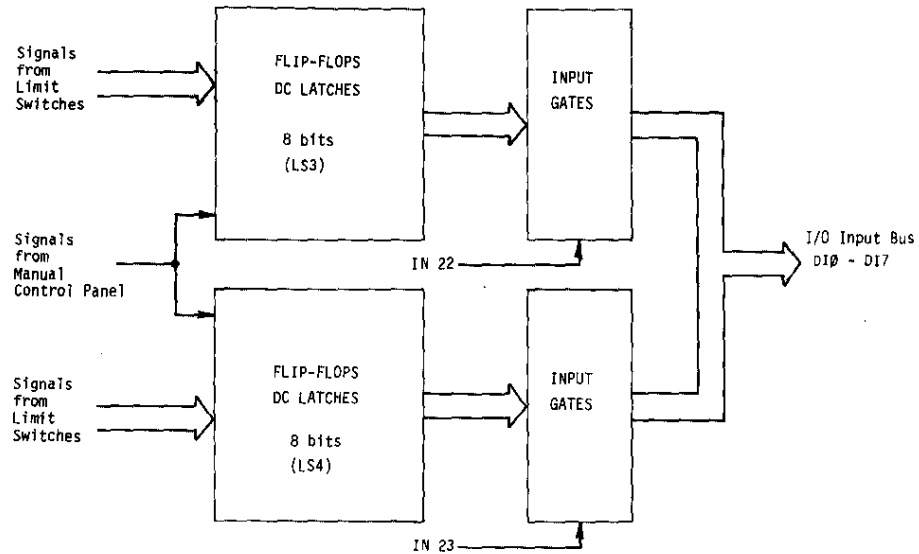


FIGURE 8. Input for Limit Switches

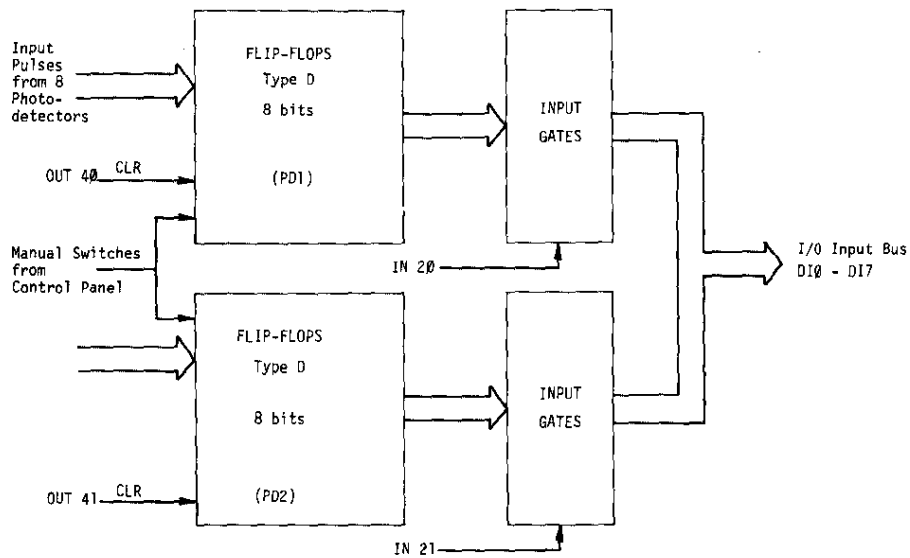


FIGURE 9. Input for Photodetectors

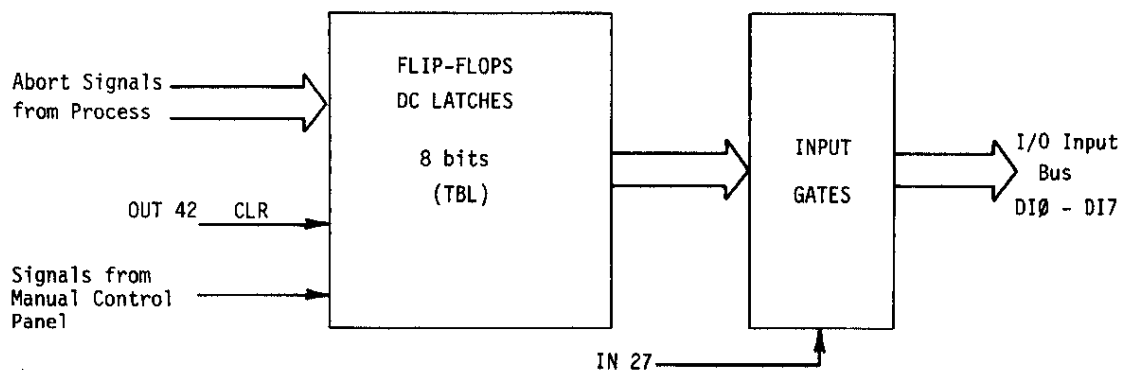


FIGURE 10. Input for Abort Status

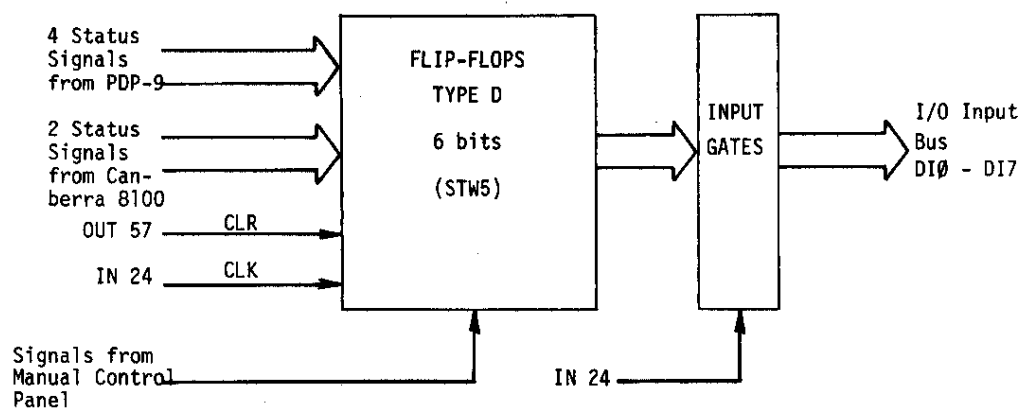


FIGURE 11. Status Input from PDP-9 Computer and Canberra 8100 Analyzer

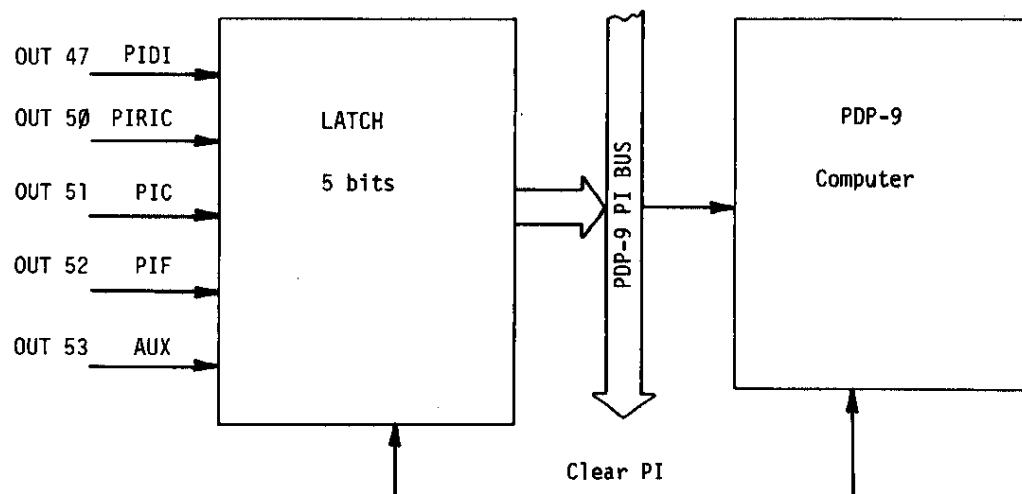


FIGURE 12. Program Interrupt Connections to PDP-9 Computer

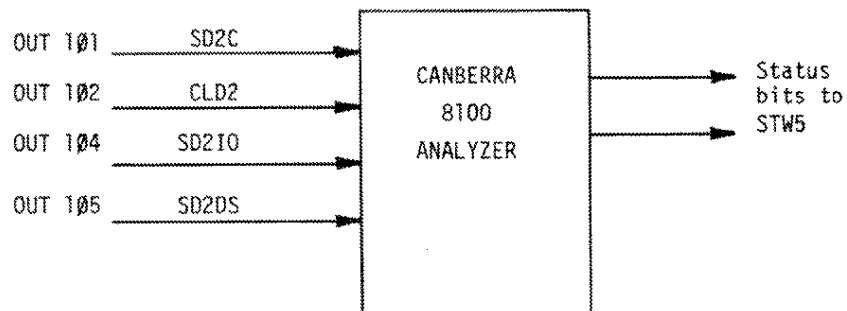


FIGURE 13. Connections to Canberra 8100 Analyzer

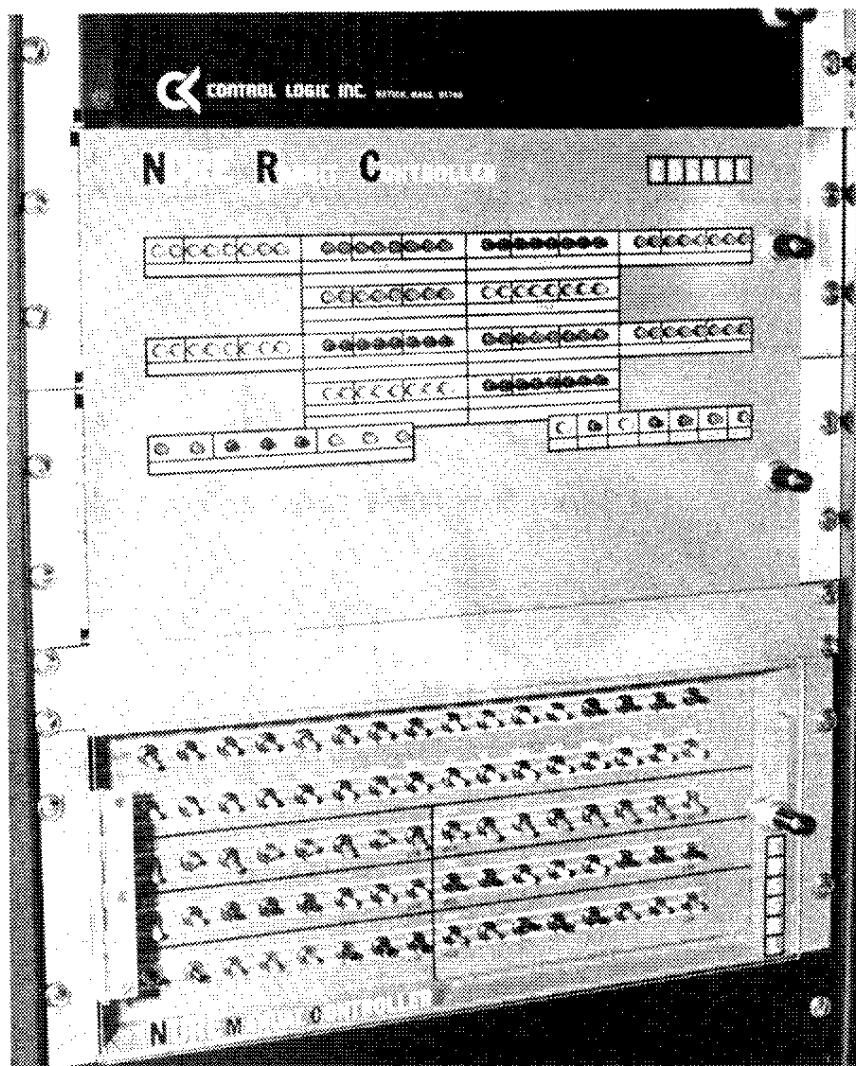


FIGURE 14. Control and Indicator Panels on NURE Rabbit Controller

Firmware

The M-series microprocessor that forms the hardware of the NURE Rabbit Controller operates from programmed instructions in the form of either software or firmware. For full operation, the controller must operate from firmware to prevent power failure or unintentional operator commands from inadvertently altering instructions.

In the controller firmware program (Appendices A and B), subroutines perform basic operations such as checking photodetectors for sample rabbit passage or accelerating or decelerating a rabbit. These basic operations are called by more specific subroutines (such as moving a rabbit from one location to another). These subroutines are ultimately called by the main program, which provides for a particular type of analysis.

Because the mechanical and pneumatic aspects of the system require much more operating time than do the electronics of the controller, program tests of limit switches and photodetectors acknowledge that mechanical motions have been completed. However, if some operation should fail to complete within a certain time, the action is assumed to be incomplete. Timing sequences in the program provide for malfunction messages, status registers, and pointers if the system should fail.

The time base in the system is changed under program control to be compatible with the use, whether the program is timing a mechanical motion or waiting for irradiation times to elapse.

The NURE Rabbit Controller, when started, identifies itself and enters a Wait routine which identifies itself as shown below:

NURE RABBIT CONTROLLER

WAITING

004 012

The numbers on the third line show the location within the program from which the Wait subroutine was called. With a program listing, the operator can determine the location of the next instruction to be executed if the Wait subroutine should execute a normal return instruction. In this case, the instruction would be page 48 location 128. These numbers are obtained by a stack dump subroutine (SPD) which extracts the information from the processor pointer stack. Because the pointer SPD is also a subroutine, it must go back two subroutine pointers in the stack to obtain useful information. It uses global *Teletype* handlers to output the information.

The message routine which types the word messages on the *Teletype* is a general-purpose routine which requires only the location in memory where the message is stored. As the routine types the message, it searches for an end character to terminate the operation.

The Wait routine is a general-purpose routine which forms the operating system of the NURE Rabbit Controller. With it, parameters for system operation are set, working registers are zeroed, and the various operating modes of the controller are executed. Parameters, such as number of samples and cycles in an analysis sequence, are entered as decimal numbers after the parameter to be entered is identified with a one or two character command.

One function of the Wait routine is to specify which irradiation tubes are being used. The reactor irradiation chamber has six irradiation tubes. The control center module is designed to be connected to any four of these tubes. The NURE rabbit controller program also permits the use of any number of the four tubes to which it is connected; therefore, the system can continue operation if some of the tubes are not functioning.

The subroutine BCD (binary coded decimal) converts decimal numbers entered as parameters to binary numbers as used in the controller. BCD will convert any decimal integer up to 9999 to a 2-byte binary number (8 bits/byte). Once entered, this subroutine will attempt to load a decimal number until a valid number is loaded. That is, if an illegal character, such as a letter, or too many numbers such as 5 digits, are entered, that load is aborted. A question mark is typed, and the subroutine starts over to await the correct number.

The main subprograms of the NURE Rabbit Controller are:

- Regimes A, B, and C
- Regime D
- Examine Tubes
- Examine Counters
- Single Sample Irradiation and Count

Regime A generally controls the movement of the sample, including loading a sample from the loader tube, moving it to the reactor for a short irradiation, and returning it from the reactor to determine the presence of an undesirable high radioactivity level (Figure 1). The PDP-9 MOSES system (Monitoring Online System for Elemental Separations) determines radioactive content of samples. The PDP-9 then notifies the NURE Rabbit Controller to

either reject the sample as too radioactive or continue the analysis with Regime B. A radioactive sample is immediately discharged to the unloader where it is shielded from operating personnel.

Regime B consists of longer irradiation times and shorter count times repeated for a number of cycles. The PDP-9 computer determines radioactive content of samples. At the end of Regime B, the sample rabbit is returned to the reactor for a prolonged irradiation of Regime C. The irradiation time is governed by operating parameters such as number of cycles in Regime B and the number of tubes in use. This results from the rabbit being left in the reactor until all tubes have been used, a rabbit has been deposited in each, and the need to use the tube again arises. Regime C is terminated by moving the rabbit to a Canberra 8100 multichannel analyzer and leaving the rabbit there to be counted while the next new rabbit is started through its analysis. When the Canberra is again needed, the rabbit is unloaded, and the next one is placed in the Canberra analyzer.

After Regimes A, B, and C, Regime D is separately executed for long counts on the previously analyzed rabbits. The radioactive samples from Regime A are in the unloader tube with the other rabbits, and the operator does not sort the samples.

Regime D is capable of operating either or both detector stations. Before this regime can begin, information is required concerning which detectors will be used and how many samples will be analyzed. The regime then operates with the PDP-9 to transport rabbits and operate the Canberra analyzer, as programmed. The Canberra must have the appropriate count time preset before Regime D can begin. If a sample was too radioactive to complete Regimes A, B, and C, the PDP-9 notifies the NURE Rabbit Controller to immediately unload the sample rabbit.

The program to examine the tubes is designed to test all parts of the system by moving a rabbit to and from all points in the system. The NURE Rabbit Controller completely controls this operation.

During the program to examine the counters, a known source rabbit is moved from the loader to the PDP-9; it is counted and then moved to the Canberra analyzer. The Canberra analyzer determines the radioactive level in the standard source, and the rabbit is unloaded.

The single sample irradiation and count program is structured to determine irradiation capabilities of the system. Known rabbit samples are irradiated for operator-determined intervals and counted by either the PDP-9 or the Canberra analyzer. These rabbits are then unloaded.

At the end of each of the main programs, control is returned to the operating system WAIT of the NURE Rabbit Controller from which any program can be executed or any parameter can be changed.

The octal debugging technique program supplied by Control Logic, Inc., also resides in the firmware. Some of its general handlers are used by the NURE Rabbit Controller, and the octal debugging technique itself is used to troubleshoot any program changes and some hardware problems.

Basic Operating Principles

The following basic criteria were used in designating the NURE Rabbit Controller: all valves will, in their normal position, provide for proper cooling of the system without undue expenditures of compressed air. Dual photodetectors are used in the transport of rabbits to and from the reactor to ensure detection and to allow operation after the failure of one of the pair. The actual transport of the rabbit consists of a primary firing action to move the rabbit from its origin to the photodetectors at its destination. The photodetectors are positioned a short distance from the end of the tubes. When the rabbit passes these photodetectors, a braking action slows the rabbit to cushion its impact at the end of the tube. After a preset time, all transport valves are returned to their normal position to complete the four-step transport cycle. This cycle includes a step to position diverter paths.

Photodetector check points are used to determine rabbit position. At the reactor irradiation chamber and at the PDP-9 detector station D1, photodetectors are dual assemblies. All other points are single assemblies. The routines PDK1 (reactor irradiation chamber) and PDK2 (central control module) use the programmed logic array to determine the proper detectors to be checked. The routine then checks the photodetector register for a nonzero condition which shows whether a rabbit has passed a photodetector. If this does not occur within 5 seconds after the routine is entered, the system assumes a failure, dumps all photodetectors and limit switch registers.

If the nonzero condition does occur within 5 seconds, the routines must determine whether the proper photodetectors were triggered. Because the photodetectors are constructed in line with the transit tubes, the rabbit takes a period of time between passing the first and second one. The detector routines must allow for this time lapse before determining whether the rabbit position is correct. If the photodetectors are not all correct, the condition of the photodetector at the time of departure from the routine is stored to be dumped at the end of the rabbit transit.

Transport subroutines are used to handle the actual movement of the rabbits by the NURE Rabbit Controller. The system has two basic areas: the RIC and the CCM. Three basic paths exist for rabbit movement:

CCM → RIC	T21
RIC → CCM	T12
CCM → CCM	T22

The CCM → CCM path is handled by Subroutine T22. This subroutine is used for loading rabbits, moving rabbits to counters, or unloading rabbits. A transport sequence consists of four steps for valve actuation: position, start, cushion, and stop. The transport routine obtains sequence address locations, clears the photodetector register, and activates the first valve sequence. The first sequence positions the diverter path and verifies the diverter positions. The second sequence moves the rabbit. The routine then verifies departure of the rabbit by calling the appropriate photodetector routine. After departure is verified, the routine must allow the trailing end of the rabbit to clear the photodetector assembly before further action is taken. Then, the photodetector register is cleared to await arrival of another rabbit, the transport sequence address is incremented to set valves to be actuated for braking, and the photodetector routine is called to watch for the rabbit. When the rabbit arrives, the braking is initiated, and the rest of the sequencing is concluded. After the rabbit is halted, the transport routine checks the photodetector error registers and, if an error has occurred, dumps error information in the following form:

DP1	PD2 ₁	PD2 ₂
XXX	XXX	XXX

where XXX is the octal representation of the 8-bit photodetector register.

PD1 is the photodetector register made up of photodetectors in the RIC. PD2 is made up of photodetectors in the CCM. PD2₁ indicates the first time in the CCM, and PD2₂ indicates the second. For example, with Subroutine T22, PD2₁ is the departure and PD2₂ is the arrival.

Transport Subroutine T21 is used to transport rabbits from the CCM to the RIC. In this case, PD1 is arrival and PD2₁ is departure. Likewise, in Subroutine T12 (RIC → CCM), PD1 is departure and PD2₁ is arrival. Any register which was correct for the trip is indicated by a zero register.

The T12 and T21 subroutine in the reactor irradiation chamber automatically notify the PDP-9 of a rabbit entering or leaving the RIC. The program interrupt PIRIC is issued after the rabbit passes the RIC photodetectors.

Tables for Determining State of NURE Rabbit Controller

The following tables are useful for determining the state of NURE Rabbit Controller from the front panel.

Table 5: Operation Table. STAD, the mnemonic for the PLA address register, identifies the operation being attempted or most recently completed. STAD numbers in the table are the octal representation of the 8-bit register on the controller panel. The format of the table and PLA is such that for a given address the state of all solenoids is defined. Usually in blocks of four states each, the table can be interpreted as follows: STAD 27. Address 27 provides information to position the diverters for a path from reactor irradiation chamber tube W to GeLi detector D1. EA is the path for diverter one as specified in the vendor documentation; EC is the path for diverter two. The state of the diverter limit switches is identified by PLA word 5. STAD 30 identifies which solenoids must be activated so that the rabbit can be moved. PLA word 5 now identifies the photodetectors which should actuate. STAD 31 identifies solenoids to operate for cushioning after the photodetectors formatted in PLA 6 are activated. STAD 32 returns all solenoids to their normal positions to stop the rabbit propulsion.

Table 6: PLA Bit States. Table 6 is the actual bit specifications to achieve the proper solenoid operation. Table 6C also determines whether PLA words 5 and 6 are to be used as test words with limit switches or photodetectors. Table 6D specifies (in octal) the coding for the internal PLA EPROMs.

Table 7: Status Word Bit Descriptions. The status word bit descriptions are listed in Table 7. PD is an acronym for photodetectors, LS is for limit switches, and PS is for pressure switches.

Table 8: Status Words and Program Interrupts in External Electronics. Table 8 lists the input signals from the PDP-9 and Canberra analyzers which are input with STW5. The program interrupts to the PDP-9 are also listed.

Table 9: Canberra Communications. The microprocessor signals to and from the Canberra are listed in Table 9.

Table 10: Input/Output Commands. Input/output commands, as added to Control Logic M-Series processor, are listed in Table 10. Acronyms used in the program listing comments are identified.

Table 11: L596 Card Jumpers. Table 11 identifies firmware PROM cards as to where pages are located.

Table 12: Reactor Irradiation Chamber Cross Reference. Table 12 is a cross reference between the 6 reactor tubes and the 4 tubes that the NURE Rabbit Controller handles. Any one of the reactor tubes can be used for any one of the 4 controller tubes. This permits spare tubes to be connected to the needed positions.

Table 12 allows correlation between identification W, X, Y, and Z from the NURE Rabbit Controller to the reactor irradiation chamber and identification of RT1, RT2, RT4, RT5, and RT6 from the actual hardware tube.

Table 13: Manual Operations. Table 13 is a chart to permit manual operation of the pneumatic system. Each four-way diverter has two solenoids. In this table, the solenoid states for a desired path are shown, the function of necessary valves are defined, and the necessary valve states to move a sample rabbit along the chosen path are given. Figure 15 is a layout diagram which will aid in selecting the proper sequences.

TABLE 5

Operation Table

STAD	Operation	Path	Path for Diverter One	Path for Diverter Two
0	Normal position of all solenoids		X	X
1	Load loader		X	ED
2	Unused		X	X
3	Position diverters	L → D1	X	ED
4	Send	L → D1	X	ED
5	Cushion	L → D1	X	ED
6	Stop	L → D1	X	ED
7	Position	D1 → RICW	EA	EC
10	Send	D1 → RICW	EA	EC
11	Cushion	D1 → RICW	EA	EC
12	Stop	D1 → RICW	EA	EC
13	Position	D1 → RICX	EB	EC
14	Send	D1 → RICX	EB	EC
15	Cushion	D1 → RICX	EB	EC
16	Stop	D1 → RICX	EB	EC
17	Position	D1 → RICY	EC	EC
20	Send	D1 → RICY	EC	EC

(continued)

TABLE 5, continued

<i>STAD</i>	<i>Operation</i>	<i>Path</i>	<i>Path for Diverter One</i>	<i>Path for Diverter Two</i>
21	Cushion	D1 → RICY	EC	EC
22	Stop	D1 → RICY	EC	EC
23	Position	D1 → RICZ	ED	EC
24	Send	D1 → RICZ	ED	EC
25	Cushion	D1 → RICZ	ED	EC
26	Stop	D1 → RICZ	ED	EC
27	Position	RICW → D1	EA	EC
30	Send	RICW → D1	EA	EC
31	Cushion	RICW → D1	EA	EC
32	Stop	RICW → D1	EA	EC
33	Position	RICX → D1	EB	EC
34	Send	RICX → D1	EB	EC
35	Cushion	RICX → D1	EB	EC
36	Stop	RICX → D1	EB	EC
37	Position	RICY → D1	EC	EC
40	Send	RICY → D1	EC	EC
41	Cushion	RICY → D1	EC	EC
42	Stop	RICY → D1	EC	EC
43	Position	RICZ → D1	ED	EC
44	Send	RICZ → D1	ED	EC
45	Cushion	RICZ → D1	ED	EC
46	Stop	RICZ → D1	ED	EC
47	Position	D1 → D2	X	EA
50	Send	D1 → D2	X	EA
51	Cushion	D1 → D2	X	EA
52	Stop	D1 → D2	X	EA
53	Position	D2 → D1	X	EA
54	Send	D2 → D1	X	EA
55	Cushion	D2 → D1	X	EA
56	Stop	D2 → D1	X	EA
57	Position	D1 → U	X	EB
60	Send	D1 → U	X	EB
61	Cushion	D1 → U	X	EB
62	Stop	D1 → U	X	EB
63	Open	UNLOADER	X	EB
64	Close	UNLOADER	X	EB

TABLE 6A

PLA Bit States

STAD	PLA 1								PLA 2							
	31	32	33	34	35	36	37	38	WA	WB	WC	WD	XA	XB	XC	XD
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
2	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
3	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
4	0	0	1	0	0	0	0	1	0	0	0	0	0	0	0	0
5	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0
6	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
7	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
10	1	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0
11	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
12	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
13	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
14	1	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0
15	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
16	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
17	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
20	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
21	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
22	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
23	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
24	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
25	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
26	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
27	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
30	0	0	1	0	0	0	0	0	1	0	0	0	0	0	0	0
31	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0
32	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
33	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
34	0	0	1	0	0	0	0	0	0	0	0	0	1	0	0	0
35	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0
36	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
37	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
40	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0
41	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0
42	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
43	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
44	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0
45	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0
46	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
47	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
50	1	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0
51	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
52	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
53	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
54	0	0	1	0	1	1	0	0	0	0	0	0	0	0	0	0
55	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0
56	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
57	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
60	1	0	0	0	0	0	1	0	1	0	0	0	0	0	0	0
61	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
62	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
63	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
64	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

TABLE 6B

PLA Bit States

STAD	PLA 3								PLA 4							
	YA	YB	YC	YD	ZA	ZB	ZC	ZD	U	L	D1A	D1B	D2A	D2B	SPR1	SRP2
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	0	0	0	0	0	0	0	0	0	1	0	0	1	1	0	0
2	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
3	0	0	0	0	0	0	0	0	0	1	0	0	1	1	0	0
4	0	0	0	0	0	0	0	0	0	1	0	0	1	1	1	0
5	0	0	0	0	0	0	0	0	0	1	0	0	1	1	0	0
6	0	0	0	0	0	0	0	0	0	0	0	0	1	1	0	0
7	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0
10	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0
11	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0
12	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0
13	0	0	0	0	0	0	0	0	0	0	1	0	0	1	0	0
14	0	0	0	0	0	0	0	0	0	0	1	0	0	1	0	0
15	0	0	0	0	0	0	0	0	0	0	1	0	0	1	0	0
16	0	0	0	0	0	0	0	0	0	0	1	0	0	1	0	0
17	0	0	0	0	0	0	0	0	0	0	0	1	0	1	0	0
20	0	1	0	0	0	0	0	0	0	0	0	1	0	1	0	0
21	0	0	0	0	0	0	0	0	0	0	0	1	0	1	0	0
22	0	0	0	0	0	0	0	0	0	0	0	1	0	1	0	0
23	0	0	0	0	0	0	0	0	0	0	1	1	0	1	0	0
24	0	0	0	0	0	1	0	0	0	0	1	1	0	1	0	0
25	0	0	0	0	0	0	0	0	0	0	1	1	0	1	0	0
26	0	0	0	0	0	0	0	0	0	0	1	1	0	1	0	0
27	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0
30	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0
31	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0
32	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0
33	0	0	0	0	0	0	0	0	0	0	1	0	0	1	0	0
34	0	0	0	0	0	0	0	0	0	0	1	0	0	1	0	0
35	0	0	0	0	0	0	0	0	0	0	1	0	0	1	0	0
36	0	0	0	0	0	0	0	0	0	0	1	0	0	1	0	0
37	0	0	0	0	0	0	0	0	0	0	0	1	0	1	0	0
40	1	0	0	0	0	0	0	0	0	0	0	1	0	1	0	0
41	0	0	0	0	0	0	0	0	0	0	0	1	0	1	0	0
42	0	0	0	0	0	0	0	0	0	0	0	1	0	1	0	0
43	0	0	0	0	0	0	0	0	0	0	1	1	0	1	0	0
44	0	0	0	0	1	0	0	0	0	0	1	1	0	1	0	0
45	0	0	0	0	0	0	0	0	0	0	1	1	0	1	0	0
46	0	0	0	0	0	0	0	0	0	0	1	1	0	1	0	0
47	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
50	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
51	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
52	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
53	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
54	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
55	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
56	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
57	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0
60	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0
61	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0
62	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0
63	0	0	0	0	0	0	0	0	1	0	0	0	1	0	0	0
64	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0

TABLE 6C

PLA Bit States

STAD	PLA 6 Test Word One								Compared With P = Photodetector L = Limit Switch X = Not Used			PLA 6 Test Word Two							
	7	6	5	4	3	2	1	0				7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	0	0	+	X	L	+	0	0	0	0	0	1	0
1	0	0	0	0	0	0	0	0		X	L		0	0	0	0	0	0	1
2	0	0	0	0	0	0	0	0		X	X		0	0	0	0	0	0	0
3	0	1	0	1	1	0	1	0		L	X		0	0	0	0	0	0	0
4	0	0	0	0	0	0	0	0		X	P		0	0	0	1	0	0	0
5	0	0	0	0	0	0	0	0		X	P		0	0	0	0	0	0	1
6	0	0	0	0	0	0	0	0		X	X		0	0	0	0	0	0	0
7	0	1	1	0	1	0	1	0		L	X		0	0	0	0	0	0	0
10	0	0	0	0	0	0	0	0		X	P		0	0	0	0	0	0	1
11	0	0	0	0	0	0	1	1		P	X		0	0	0	0	0	0	0
12	0	0	0	0	0	0	0	0		X	X		0	0	0	0	0	0	0
13	0	1	1	0	1	0	0	1		L	X		0	0	0	0	0	0	0
14	0	0	0	0	0	0	0	0		X	P		0	0	0	0	0	0	1
15	0	0	0	0	1	1	0	0		P	X		0	0	0	0	0	0	0
16	0	0	0	0	0	0	0	0		X	X		0	0	0	0	0	0	0
17	0	1	1	0	0	1	1	0		L	X		0	0	0	0	0	0	0
20	0	0	0	0	0	0	0	0		X	P		0	0	0	0	0	0	1
21	0	0	1	1	0	0	0	0		P	X		0	0	0	0	0	0	0
22	0	0	0	0	0	0	0	0		X	X		0	0	0	0	0	0	0
23	0	1	1	0	0	1	0	1		L	X		0	0	0	0	0	0	0
24	0	0	0	0	0	0	0	0		X	P		0	0	0	0	0	0	1
25	1	1	0	0	0	0	0	0		P	X		0	0	0	0	0	0	0
26	0	0	0	0	0	0	0	0		X	X		0	0	0	0	0	0	0
27	0	1	1	0	1	0	1	0		L	X		0	0	0	0	0	0	0
30	0	0	0	0	0	0	1	1		P	X		0	0	0	0	0	0	0
31	0	0	0	0	0	0	0	0		X	P		0	0	0	0	0	0	1
32	0	0	0	0	0	0	0	0		X	X		0	0	0	0	0	0	0
33	0	1	1	0	1	0	0	1		L	X		0	0	0	0	0	0	0
34	0	0	0	0	1	1	0	0		P	X		0	0	0	0	0	0	0
35	0	0	0	0	0	0	0	0		X	P		0	0	0	0	0	0	1
36	0	0	0	0	0	0	0	0		X	X		0	0	0	0	0	0	0
37	0	1	1	0	0	1	1	0		L	X		0	0	0	0	0	0	0
40	0	0	1	1	0	0	0	0		P	X		0	0	0	0	0	0	0
41	0	0	0	0	0	0	0	0		X	P		0	0	0	0	0	0	1
42	0	0	0	0	0	0	0	0		X	X		0	0	0	0	0	0	0
43	0	1	1	0	0	1	0	1		L	X		0	0	0	0	0	0	0
44	1	1	0	0	0	0	0	0		P	X		0	0	0	0	0	0	0
45	0	0	0	0	0	0	0	0		X	P		0	0	0	0	0	0	1
46	0	0	0	0	0	0	0	0		X	X		0	0	0	0	0	0	0
47	1	0	1	0	1	0	1	0		L	X		0	0	0	0	0	0	0
50	0	0	0	0	0	0	0	0		X	P		0	0	0	0	0	0	1
51	0	0	0	0	0	0	0	0		X	P		0	0	0	0	0	1	0
52	0	0	0	0	0	0	0	0		X	X		0	0	0	0	0	0	0
53	1	0	1	0	1	0	1	0		L	X		0	0	0	0	0	0	0
54	0	0	0	0	0	0	0	0		X	P		0	0	0	0	0	1	0
55	0	0	0	0	0	0	0	0		X	P		0	0	0	0	0	0	1
56	0	0	0	0	0	0	0	0		X	X		0	0	0	0	0	0	0
57	1	0	0	1	1	0	1	0		L	X		0	0	0	0	0	0	0
60	0	0	0	0	0	0	0	0		X	P		0	0	0	0	0	0	1
61	0	0	0	0	0	0	0	0		X	P		0	0	0	0	1	0	0
62	0	0	0	0	0	0	0	0		X	X		0	0	0	0	0	0	0
63	0	0	0	0	0	0	0	0		X	L		0	0	0	0	0	1	0
64	0	0	0	0	0	0	0	0		X	P		0	1	0	0	0	0	0

TABLE 6D
Prom Coding

STAD	PLA					
	1	2	3	4	5	6
0	0	0	0	0	0	4
1	0	0	0	114	0	2
2	0	0	0	0	0	0
3	0	0	0	114	132	0
4	41	0	0	116	0	20
5	40	0	0	114	0	3
6	0	0	0	14	0	0
7	0	0	0	4	152	0
10	200	100	0	4	0	3
11	200	0	0	4	3	0
12	0	0	0	4	0	0
13	0	0	0	44	151	0
14	200	4	0	44	0	3
15	200	0	0	44	14	0
16	0	0	0	44	0	0
17	0	0	0	24	146	0
20	200	0	100	24	0	3
21	200	0	0	24	60	0
22	0	0	0	24	0	0
23	0	0	0	64	145	0
24	200	0	4	64	0	3
25	200	0	0	64	300	0
26	0	0	0	64	0	0
27	0	0	0	4	152	0
30	40	200	0	4	3	0
31	40	0	0	4	0	3
32	0	0	0	4	0	0
33	0	0	0	44	151	0
34	40	10	0	44	14	0
35	40	0	0	44	0	3
36	0	0	0	44	0	0
37	0	0	0	24	146	0
40	40	0	200	24	60	0
41	40	0	0	24	0	3
42	0	0	0	24	0	0
43	0	0	0	64	145	0
44	40	0	10	64	300	0
45	40	0	0	64	0	3
46	0	0	0	64	0	0
47	0	0	0	0	252	0
50	202	0	0	0	0	3
51	0	0	0	0	0	4
52	0	0	0	0	0	0
53	0	0	0	0	252	0
54	54	0	0	0	0	4
55	40	0	0	0	0	3
56	0	0	0	0	0	0
57	0	0	0	10	232	0
60	202	0	0	10	0	3
61	0	0	0	10	0	10
62	0	0	0	10	0	0
63	0	0	0	210	0	4
64	0	0	0	10	0	100
370					1	1
371					3	3
372					7	7
373					17	17
374					37	37
375					77	77
376					177	177
377					377	377

TABLE 7

Status Word Bit Descriptions

<i>Status Word</i>	<i>Test Word</i>	<i>Word Bit Number</i>	<i>Description</i>
PD1	1	PDW1 0	Reactor irradiation chamber photodetector tube W
		PDW2 1	Reactor irradiation chamber photodetector tube W
		PDX1 2	Reactor irradiation chamber photodetector tube X
		PDX2 3	Reactor irradiation chamber photodetector tube X
		DPY1 4	Reactor irradiation chamber photodetector tube Y
		PDY2 5	Reactor irradiation chamber photodetector tube Y
		PDZ1 6	Reactor irradiation chamber photodetector tube Z
		PDZ2 7	Reactor irradiation chamber photodetector tube Z
PD2	2	PD13 0	GeLi D1 photodetector
		PD14 1	GeLi D1 photodetector
		PD15 2	GeLi D2 photodetector
		PD16 3	Unloader entrance photodetector
		PD17 4	Loader exit photodetector
		PD18 5	Loader entrance photodetector
		PD19 6	Unloader exit photodetector
		7	Unused
LS3	1	LS1 0	CCM Diverter 1 limit switch DLS1
		LS2 1	CCM Diverter 1 limit switch DLS2
		LS3 2	CCM Diverter 1 limit switch DLS3
		LS4 3	CCM Diverter 1 limit switch DLS4
		LS5 4	Reactor Diverter 2 limit switch DLS1
		LS6 5	Reactor Diverter 2 limit switch DLS2
		LS7 6	Reactor Diverter 2 limit switch DLS3
		LS8 7	Reactor Diverter 2 limit switch DLS4
LS4	2	LS9 0	Loader limit switch L1
		LS10 1	Loader limit switch L2
		PS11 2	Unloader pressure switch U1
		3	Unused
		4	Unused
		5	Unused
		6	Unused
		7	Unused

TABLE 8

Status Words and Program Interrupts in External Electronics

<i>Status Word</i>	<i>Bit Acronyms</i>	<i>Word Bit Number</i>	<i>Description</i>
STW5	ST1	0	Start Regime B
	ST2	1	Reject sample. Start new Regime A.
	ST3	2	Continue Regime B subcycles
	ST4	3	Magtape OK
	CSA	4	Canberra Mode, Sense A
	CSB	5	Canberra Mode, Sense B
		6	Unused
		7	Unused
		<i>Hardware Pulse</i>	
	<i>Acronyms</i>		
PI	PIDI	OUT 47	PI to PDP-9. Rabbit at GeLi.
	PIRIC	OUT 50	PI to PDP-9. Rabbit passing RIC photodetectors.
	PIC	OUT 51	PI to PDP-9. Regime B ending, Regime C starting.
	PIF	OUT 52	PI to PDP-9. All tubes have Regime C rabbits in.

TABLE 9

Canberra Communications

<i>Canberra Signal</i>		<i>Microprocessor Signal</i>
Start Collect J103	Pin 1	SD2C OUT 101
Start Input/Output J103	Pin 2	SD2I0 OUT 104
Start Display J103	Pin 3	SD2DS OUT 105
Clear Memory J103	Pin 4	CLD2 OUT 102
Sense A J103	Pin 7	STW5 Bit 4 IN 24
Sense B J103	Pin 8	STW5 Bit 5 IN 24
Ground J103	Pin 5, 6	

TABLE 10

Input/Output Commands

<i>I/O Number</i>	<i>Acronym</i>	<i>Description</i>	<i>I/O Function</i>
20	PD1	Photodetector status word one	IN
21	PD2	Photodetector status word two	IN
22	LS3	Diverter limit switch status	
23	LS4	Loader limit switch, unloader pressure switch	IN
24	STW5	PDP-9 status word 5	IN
25	PDT1	Photodetector test word one	IN
26	PDT2	Photodetector test word two	
27	TBL	Trouble abort status	IN
40	CLPD1	Clear photodetectors one	OUT
41	CLPD2	Clear photodetectors two	OUT
42	CLTBL	Clear trouble word	OUT
43	STAD	PLA starting address	OUT
44	ACTV	Activate values	OUT
47	PID1	Program interrupt at D1 to PDP-9	OUT
50	PIRIC	Program interrupt reactor irradiation chamber to PDP-9	OUT
51	PIC	Program interrupt begin Regime C to PDP-9	OUT
52	PIF	Program interrupt full to PDP-9	OUT
53	AUX		OUT
54	SD2	NRC front panel light for detector D2	OUT
57	CLIF	Clear interrupt flags to PDP-9	OUT
100	FRQSL	Frequency select real time clock	OUT
101	SD2C	Start D2 counter collect	OUT
102	CLD2	Clear D2 memory	OUT
103		Wait light	OUT
104	SD2I0	Start D2 I/O	OUT
105	SD2DS	Start D2 display	OUT

TABLE 11
L596 Card Jumpers

<i>L596 Cards</i>	<i>Jumpers</i>	<i>Page Number</i>
#1	A-C	
	D-F	
	G-O	0
	H-4	4
#2	A-C	
	D-F	
	G-5	5
	H-6	6
#3	A-C	
	D-F	
	G-7	7
	H-10	10
#4	A-C	
	D-F	
	G-11	11
	H-12	12
#5	A-C	
	D-F	
	G-13	13
	H-14	14
#6	A-C	
	D-F	
	G-15	15
	H-16	16
#7	A-B	
	D-E	
	G-10	70
	H-14	74

TABLE 12
Reactor Irradiation Chamber Cross Reference

Controller Tube Components ^a	Reactor Tubes					
	RT1	RT2	RT3	RT4	RT5	RT6
__A	V1	V2	V3	V4	V5	V6
__B	V13	V14	V15	V16	V17	V18
__C	V7	V8	V9	V10	V11	V12
__D	V19	V20	V21	V22	V23	V24
DP __1	PD1	PD3	PD5	PD7	PD9	PD11
DP __2	PD2	PD4	PD6	PD8	PD10	PD12

a. Where __ = either W, X, Y, or Z, and any letter W, X, Y, or Z may represent any number RT1, RT2, RT3, RT4, RT5, or RT6.

RTx Physical reactor tube number
Vx Valve number
PDx Photodetector number
xA Controller fire valve
xB Controller exhaust valve
xC Controller cushion valve
xD Controller bleed valve

TABLE 13

Manual Operations

Four-way No. 1 Solenoid State

<u>Path</u>	<u>SD1A</u>	<u>SD1B</u>
W	0	0
X	1	0
Y	0	1
Z	1	1

Four-way No. 2

	<u>SD2A</u>	<u>SD2B</u>
D-2	0	0
4-Way 1	0	1
Unloader	1	0
Loader	1	1
V-35	D-2 Fire Valve	
V-36	D-2 Exhaust	
V-37	Unloader Exhaust	
V-38	Loader Fire Valve	
A	Fire Valve	
B	Exhaust	
C	Cushion	
D	Bleed	

Control Center Module: Valve States

	<u>V-31</u>	<u>V-32</u>	<u>V-33</u>	<u>V-34</u>
	<u>Fire</u>	<u>Cushion</u>	<u>Exhaust</u>	<u>Bleed</u>
SEND	0>1	1	0	1
STANDBY	0	0	0	0
RECEIVE	0	0	1	1

Reactor Irradiation Chamber Valve States

	<u>A</u>	<u>B</u>	<u>C</u>	<u>D</u>
	<u>Fire</u>	<u>Exhaust</u>	<u>Custion</u>	<u>Bleed</u>
SEND	0>1	0	1	1
STANDBY	0	0	0	0
RECEIVE	0	1	0	1

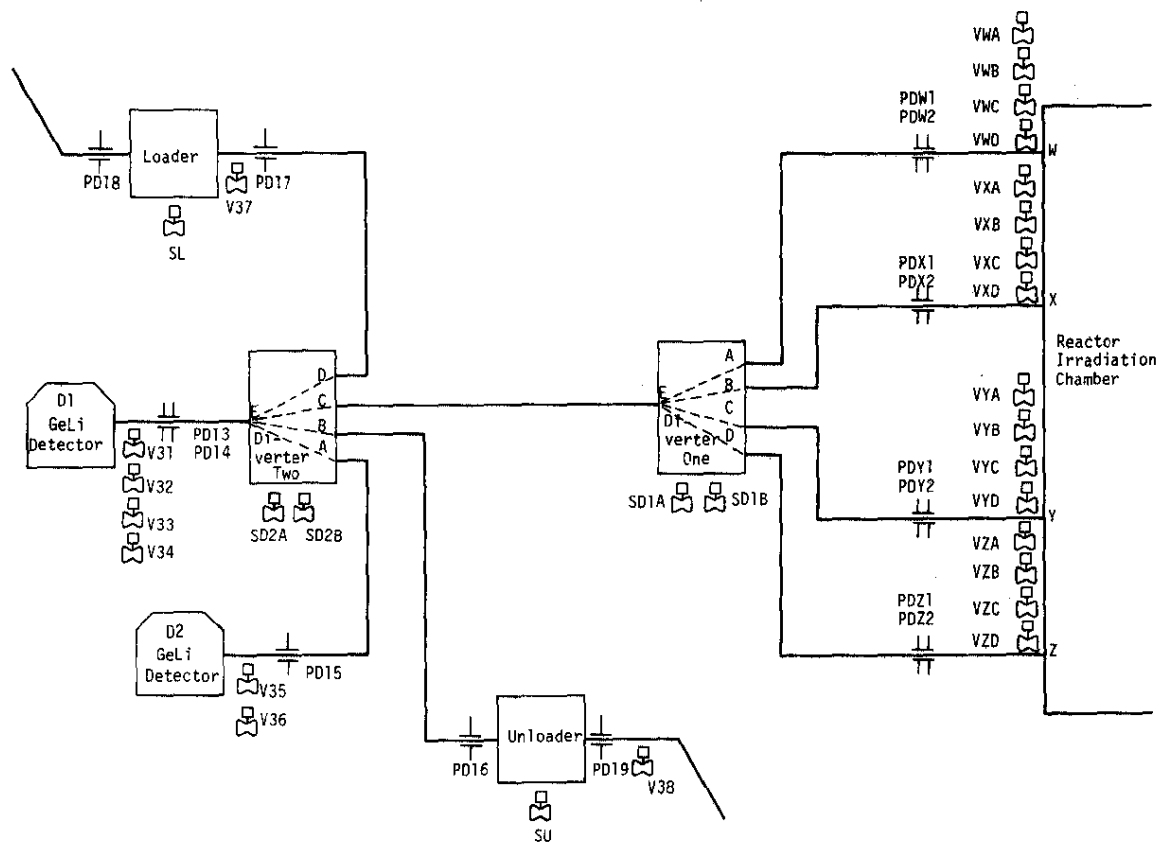


FIGURE 15. Layout Diagram of Rabbit System

NURE Commands

The commands used for the NURE Rabbit Controller are entered during the waiting portion of the program. However, the I command is used to signal the program, while it is running, that the operator wishes to gain control. The I, when typed, is not echoed.

All other commands are entered after the *Teletype* types WAITING and an address. Commands are either operation commands or number-entering commands.

Operation Commands

The operation command may be either one, two, or three characters; it requires no terminating character. Operating commands include:

A	Abort. Remove any rabbits in reactor to D1.
C	Continue at address from which the program exited.
D1Ø	Detector D1 out of use for Regime D.
D11	Detector D1 in use for Regime D.
D2Ø	Detector D2 out of use for Regime D.
D21	Detector D2 in use for Regime D.
G	Begin Regimes A, B, and C.
O	Jump to octal debugging techniques.
Ø	Zero all random access variables.
ET	Examine tubes. Run rabbit through all paths.
EC	Examine counters. Place standard in each counter.
ER1	Examine irradiation with D1. Irradiate standard and count.
ER2	Examine irradiation with D2. Irradiate standard and count.
R	Run Regime D.
W1	Set tube W in use.
WØ	Set tube W out of use.
X1	Set tube X in use.
XØ	Set tube X out of use.
Y1	Set tube Y in use.
YØ	Set tube Y out of use.

Z1 Set tube Z in use.
 Z0 Set tube Z out of use.

*Number Entry Commands**

The number-entering command can be either one or two characters followed by up to 4 decimal digits (9999_{10}) and by a terminating carriage return (CR). Number entry commands include:

Bnnnn(CR)	Number of cycles in Regime B
Snnnn(CR)	Number of samples to be run
TAnnnn(CR)	Number of seconds multiplied by 10 for Regime A irradiation**
TBnnnn(CR)	Number of seconds multiplied by 5 for Regime B irradiation**
TCnnnn(CR)	Number of seconds divided by 10 for Regime C final irradiation**
TDnnnn(CR)	Number of seconds multiplied by 1 for count time in D2
TSnnnn(CR)	Number of seconds multiplied by 1 for ER1 and ER2 irradiation

Information Required by Programs

- Single Sample Irradiation and Count

Number of seconds to be irradiated	(TS)
To execute program count in D1	ER1
To execute program count in D2	ER2
- Regime D

Number of samples to be analyzed	(S)
Detectors in use	(D1)
	(D2)
To execute program	R
- Examine Counters

None	
To execute program	EC

* Where n = Decimal Digit.

** Where nnnn - 255_{10} max.

- Examine Tubes
 - Tubes in use (W-Z)
 - To execute program ET
- Regimes A, B, and C
 - Number of samples to be analyzed (S)
 - Number of seconds to be irradiated in Regime A (TA)
 - Number of seconds to be irradiated in Regime B (TB)
 - Number of seconds to be irradiated for Regime C
 - final time (TC)
 - Number of cycles in Regime B (B)
 - Tubes in use (W-Z)
 - To execute program G

*Number Messages from the NURE Rabbit Controller**

<i>Page</i>	<i>Location</i>					<i>Meaning of Message</i>
XXX	XXX					Address to which program will return if continued
<i>PD1</i>	<i>PD2₁</i>	<i>PD2₂</i>				
XXX	XXX	XXX				Photodetector errors. Displays actual response which did not match desired response.
<i>PD1</i>	<i>PD2</i>	<i>LS3</i>	<i>LS4</i>	<i>STAD</i>		
XXX	XXX	XXX	XXX	XXX	Photodetector, limit switch, and PLA address status at time of failure to complete operation within specified time	

* Where XXX is the octal value for the implied register.

System Pointers

<i>Program Status^a</i>	<i>Program Pointer Page</i>	<i>Location</i>	<i>Pointer Meaning</i>
	4	12	System has been started from processor console card.
	4	112	Processor has received invalid status flag from PDP-9.
	4	265	Regimes A, B, and C have been completed.
C	7	154	Photodetectors in the reactor have not actuated within the allotted time.
C	7	210	An operation has exceeded the time limit set for it.
C	7	237	A diverter has not actuated within the allotted time.
C	10	20	The loader has not actuated within the allotted time.
C	10	130	Photodetectors in the CCM have not actuated within the allotted time.
C	10	160	The loader is empty for Regime A.
	11	0	Processor has received an invalid status flag from PDP-9.
C	13	50	Operator has requested control.
C	13	230	Loader is empty for Regime D.
C	13	336	Processor has received an invalid status flag from PDP-9.
C	14	202	Loader is empty for examining counters.
	14	303	Counters have been examined.
C	15	13	Loader is empty for examining tubes.
C	15	270	Pressure in line to unloader has not dropped to safe level for opening within the allotted time.
C	15	325	Rabbit has not exited unloader within the allotted time.
	16	210	Irradiation and count for a single sample have been completed.
C	16	277	Program requiring reactor tubes was started with no tubes specified.

^a. The letter "C" indicates that the program can be continued after the problem is corrected.

Software

Four programs are supplied by Control Logic, Inc., for program development on the M-Series logic system: editor, 3-pass assembler, EPROM programmer, and octal debugging techniques. The octal debugging techniques are supplied on three EPROMs and contain utility routines to read binary paper tape from the *Teletype*, punch paper tapes on *Teletype*, input/output *Teletype* characters, and modify memory locations. Many of these routines are called and executed from system firmware. The other three control logic programs may be executed by replacing system firmware modules with random access memory modules and operating the M-Series system via *Teletype*.

The only Control Logic software used for the development of system firmware was the EPROM programmer. Final object tapes for firmware programs were automatically transferred to EPROMs using the M-Series system.

The firmware programs were developed offline on a PDP-8E minicomputer with disk from an OS/8 operating system.⁴ A Control Logic L-Series cross-assembler for PDP-8, modified for OS/8 operation, was obtained from the University of South Carolina. It was modified at SRL to use the M-Series machine language codes.

ASCII (American Standard Code for Information Interchange) source disk files were generated by the OS/8 editor program. The source files were assembled as object (binary) disk files. Paper tapes of the object files were punched on a high-speed punch; these tapes were used to operate the M-Series logic microcomputer system.

ADVANTAGES OF THE SYSTEM

This system demonstrates the flexibility that can be attained in a complex digital system with a microcomputer. An effective hardware-software tradeoff reduces design effort and overall system cost. However, the flexibility of the programmed system could not be duplicated with a hardware-only system at any reasonable cost. Interfaces for peripherals can be designed and tested individually without a complicated hardware timing circuit. The microcomputer is programmed to handle the timing. To make minor changes in the system operation or to configure the system for an entirely different test, the firmware is altered with no major changes in the hardware. During this development, several major system changes were implemented by minimal firmware changes.

The firmware contains simple machine-language programs. That type of programming is generally done best by the design engineer who thoroughly understands the hardware. He must write simple input/output subroutines to test the hardware. Those subroutines can be called from a main program to generate the final software. After all, the programs essentially implement logical commands that the designer would normally realize with hardware. Very simple *Teletype* commands and responses were designed into the operating programs to reduce programming effort and memory requirements.

Microcomputers can be programmed to analyze results as well as collect data. This programming would involve a larger effort than normally would not be done by the design engineer. Higher-order programming languages and cross-assemblers for larger computers are available for some microcomputers. However, the system described in this report uses the microcomputer in its most cost-effective mode; that is, digital system timing and data-byte manipulations. With the microcomputer and with a mass storage output peripheral, such as the magnetic tape, the data can be analyzed efficiently offline with software on a large computer. In this system, magnetic tape outputs were generated by the Canberra analyzer and PDP-9 computer. The speed of low-cost microcomputers also limits their ability to perform all but simple real-time computations.

The hardware interface was built from standard transistor-transistor logic, integrated circuit modules plugged into a wire-wrapped sock array. We have proven that wire wrapping (Figure 16) provides the lowest cost in terms of components, fabrication, modification, and maintenance.

The system described has operated trouble-free for over six months. The microcomputer techniques described in this report apply to many other instruments for chemical controls and analysis.⁵

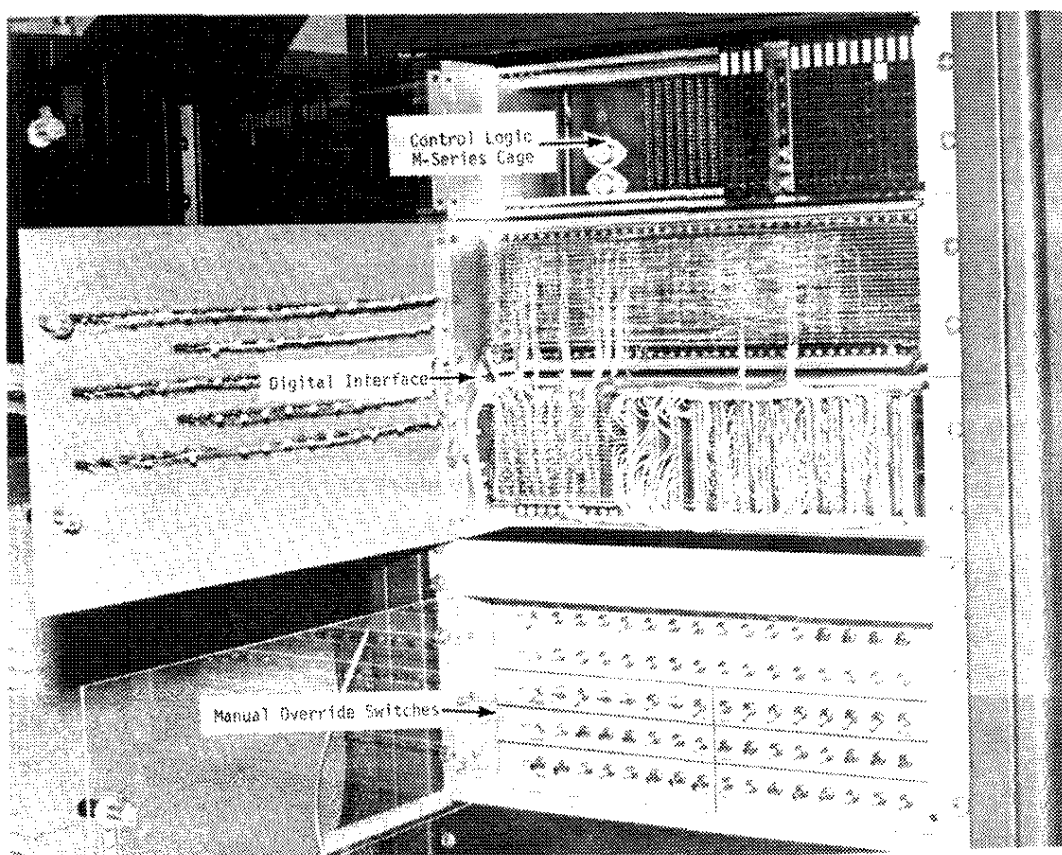


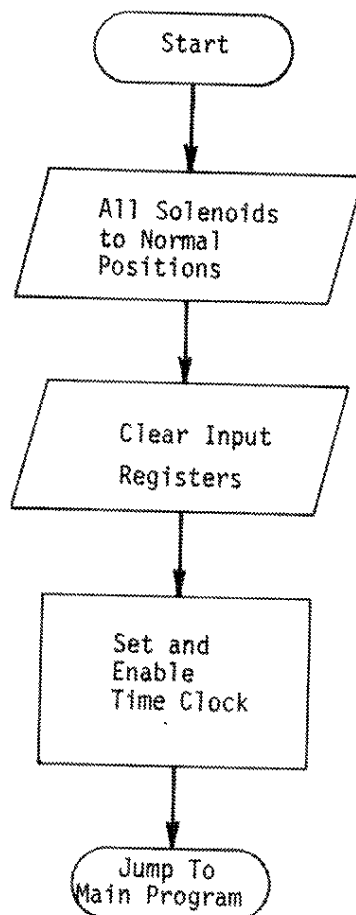
FIGURE 16. Wire Wrapping in Hardware for NURE Rabbit Controller

APPENDIX A
LOGIC OF THE PROGRAM FIRMWARE FOR THE NURE RABBIT CONTROLLER

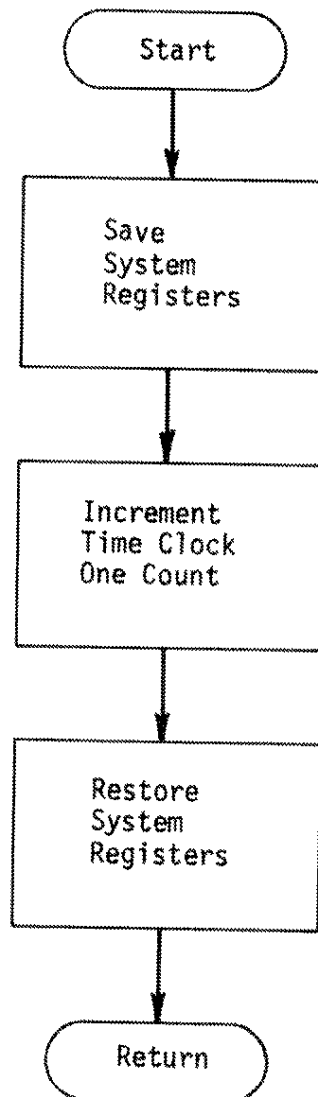
The following flowcharts show the logic of the program firmware for the NURE Rabbit Controller. The flowcharts are arranged in the order that the routines appear in the program listing (Appendix B).

ROUTINE SYSTEM STARTUP

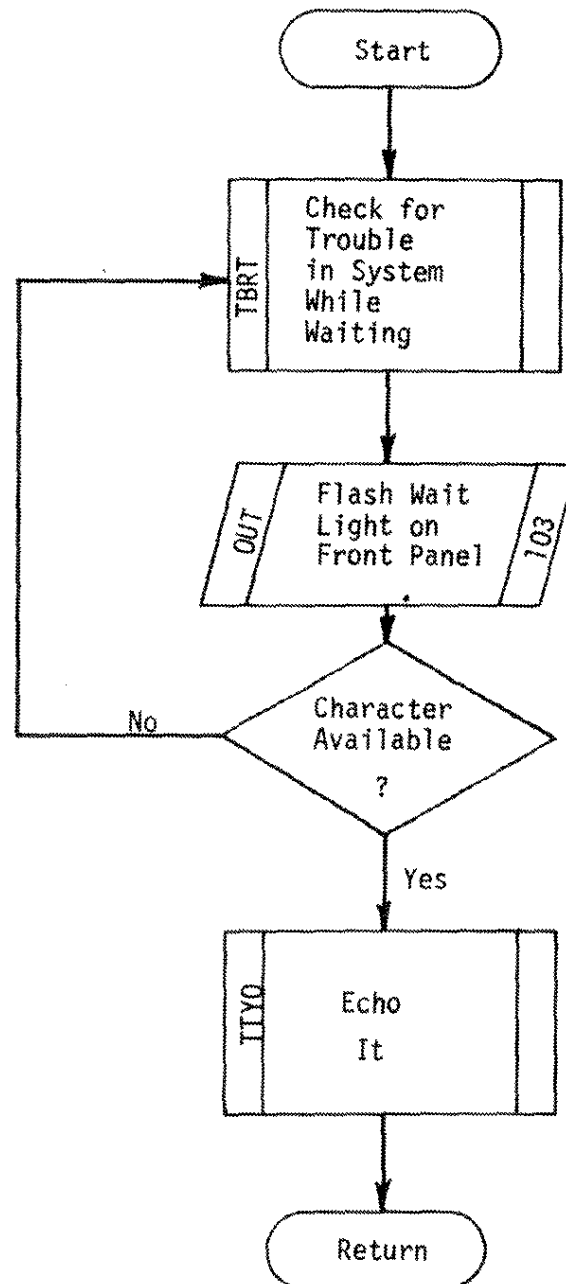
INITIALIZE SYSTEM



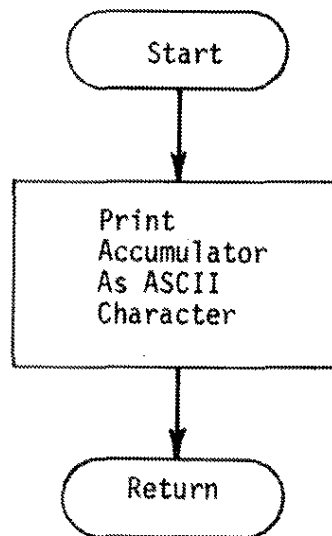
ROUTINE TIMER INTERRUPT
UPDATES TIME CLOCK REGISTERS



SUBROUTINE TTYI
INPUTS CHARACTER FROM TELETYPE

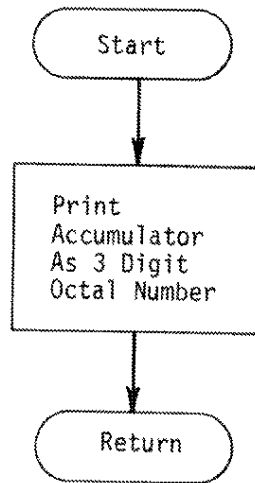


SUBROUTINE TTYO
PRINT ACCUMULATOR AS ASCII CHARACTER
(Resident in ODT)



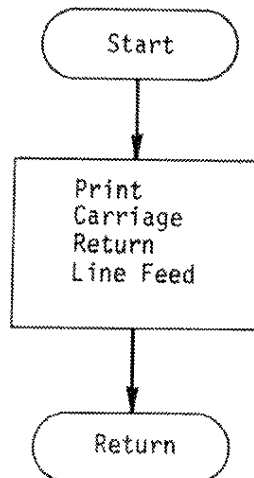
SUBROUTINE OCTO

PRINT ACCUMULATOR AS 3 DIGIT OCTAL NUMBER
(Resident in ODT)

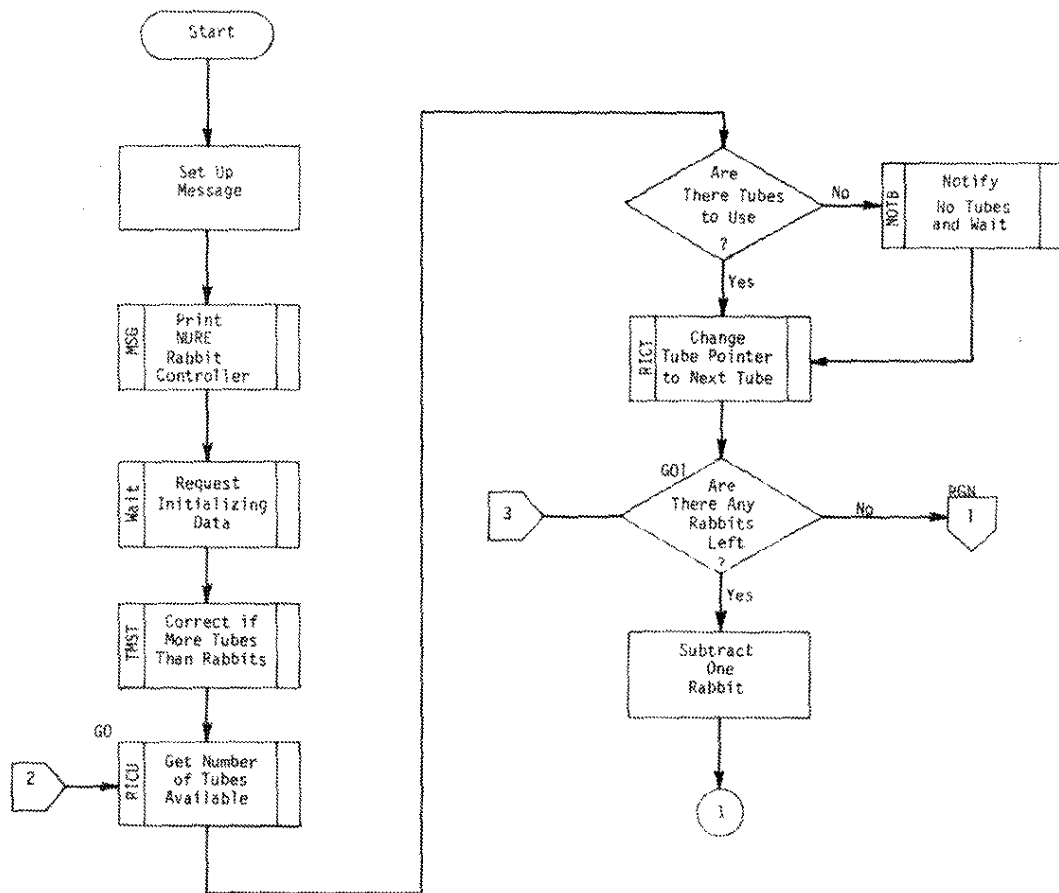


SUBROUTINE CRLF

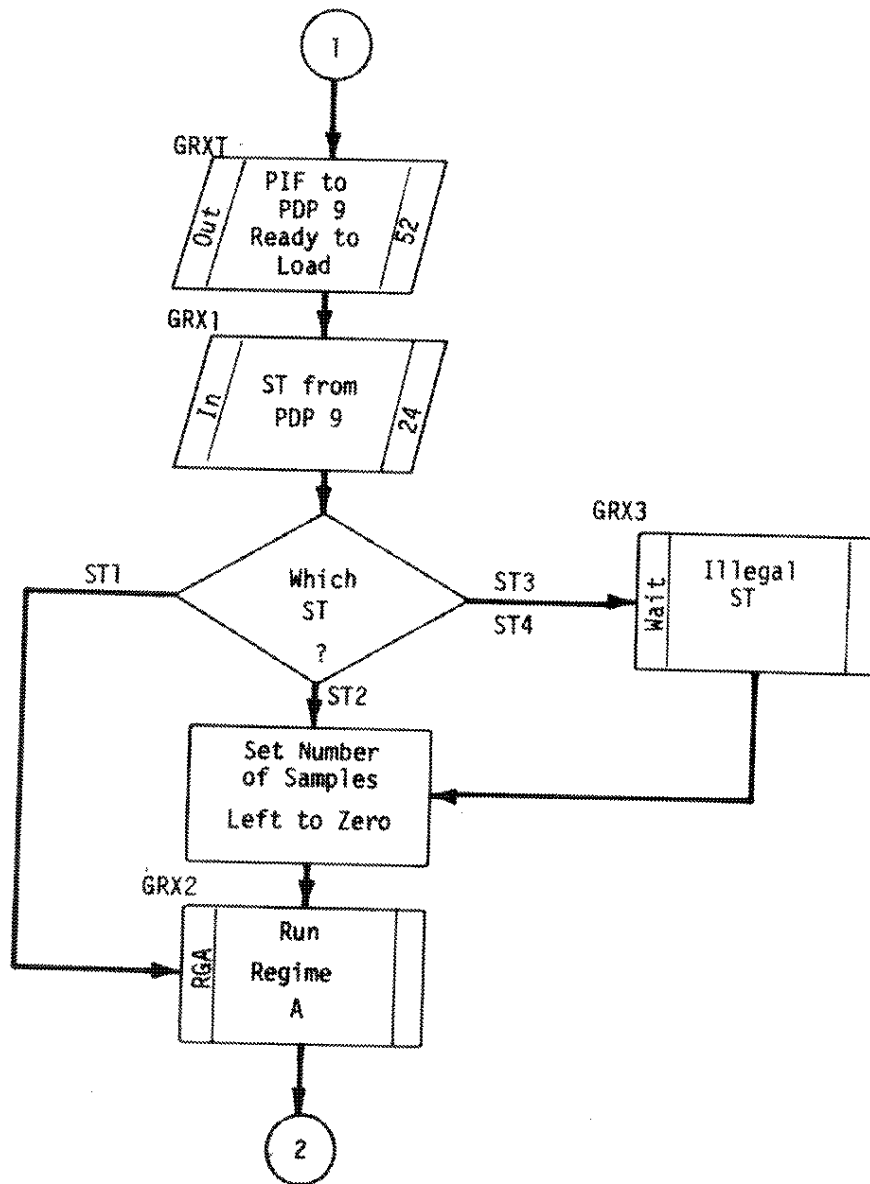
PRINT CARRIAGE RETURN LINE FEED
(Resident in ODT)



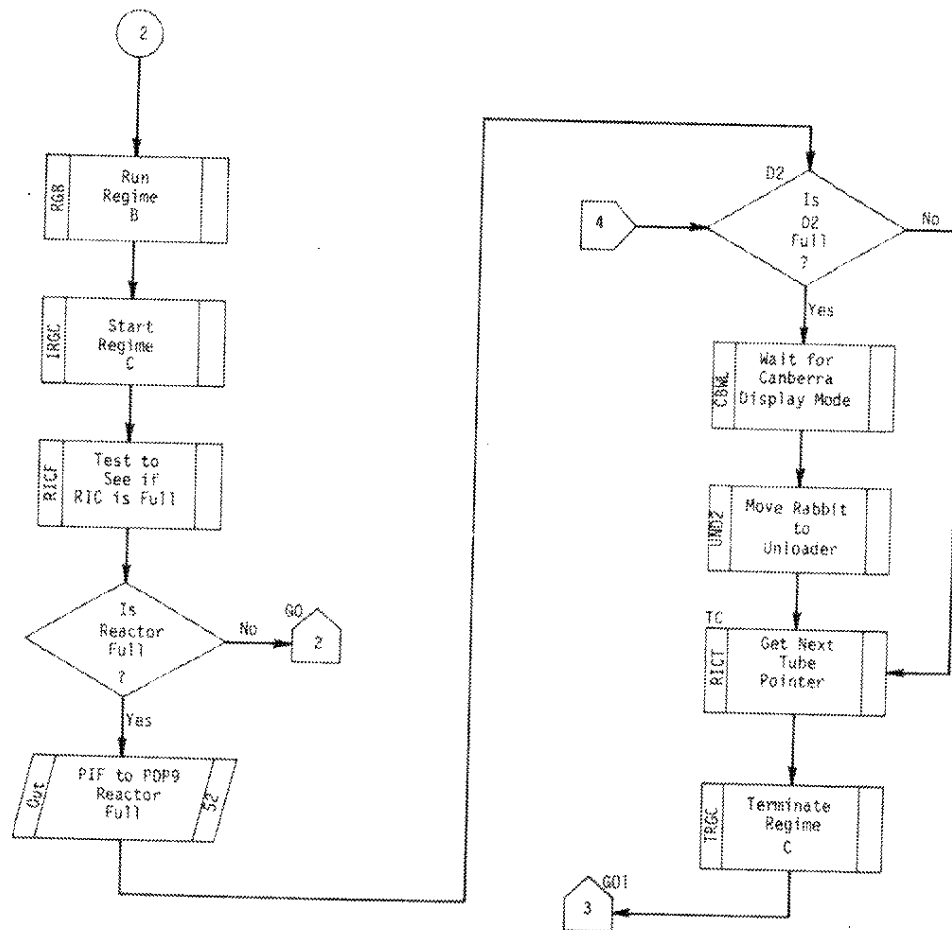
MAIN PROGRAM
Runs Combination of Regime A B C to Analyze Rabbits



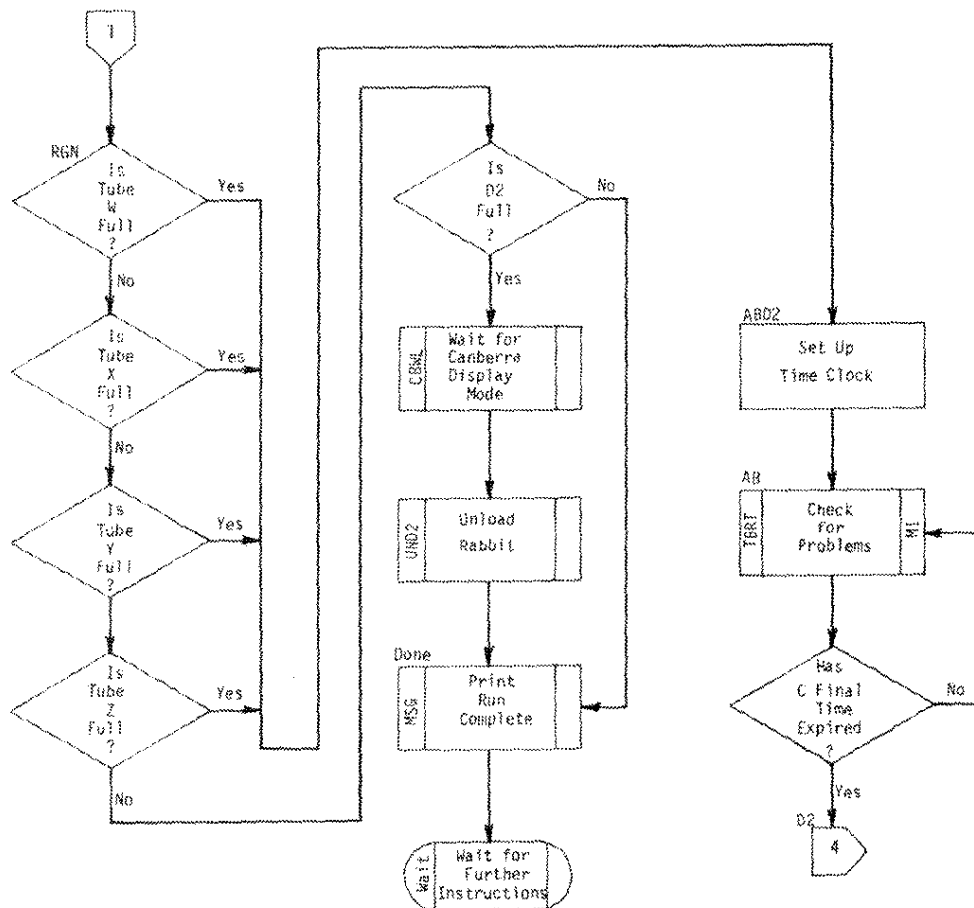
Main Program (Continuation)



Main Program (Continuation)

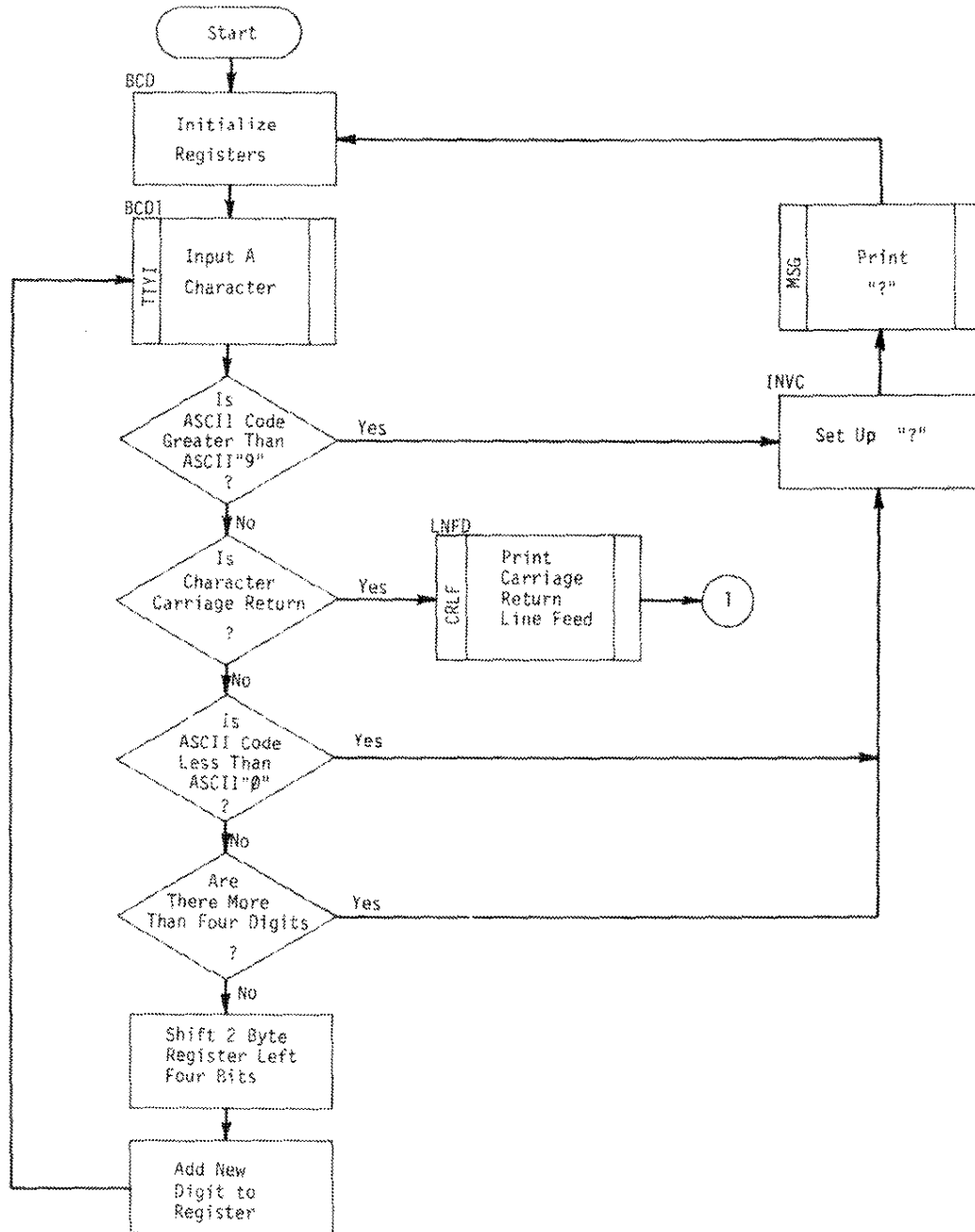


Main Program (Continuation)

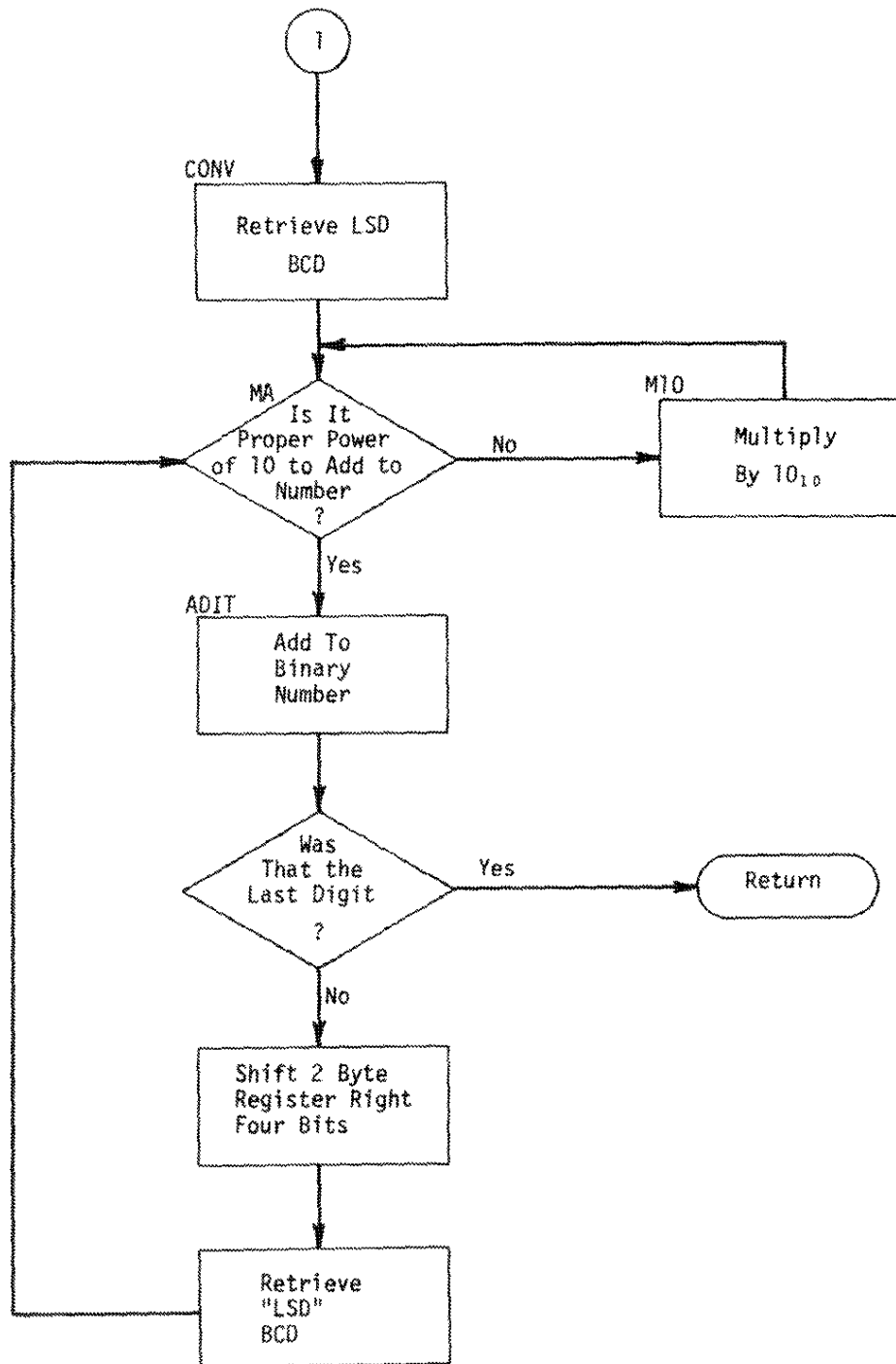


SUBROUTINE BCD

Input Up to Four Digit Decimal Number and Convert to Binary from BCD

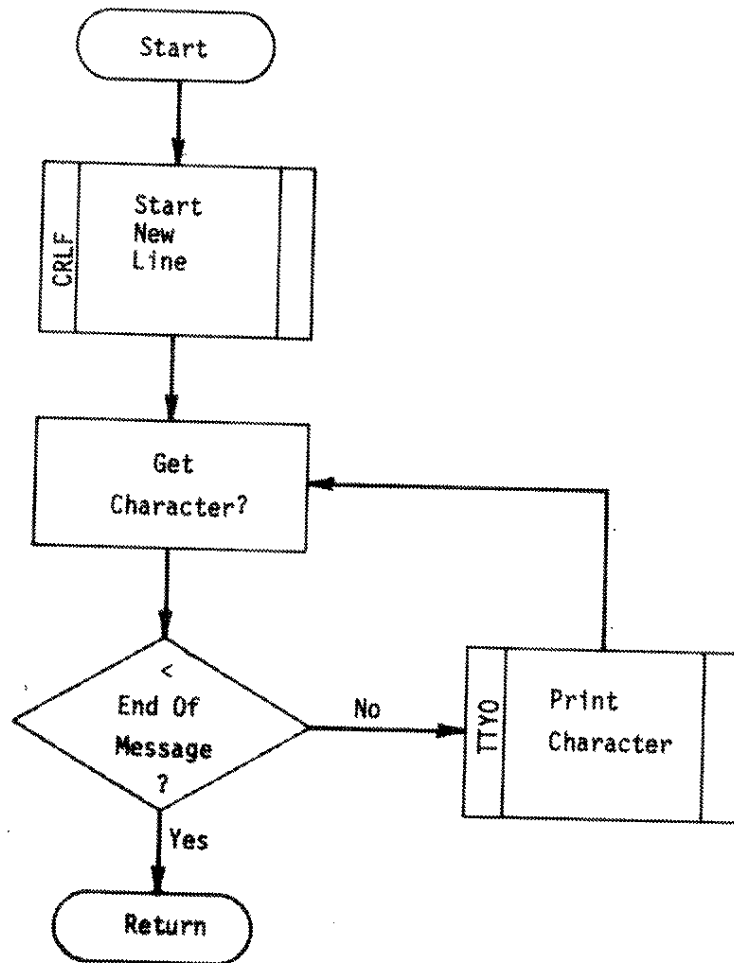


Subroutine BCD (Continuation)



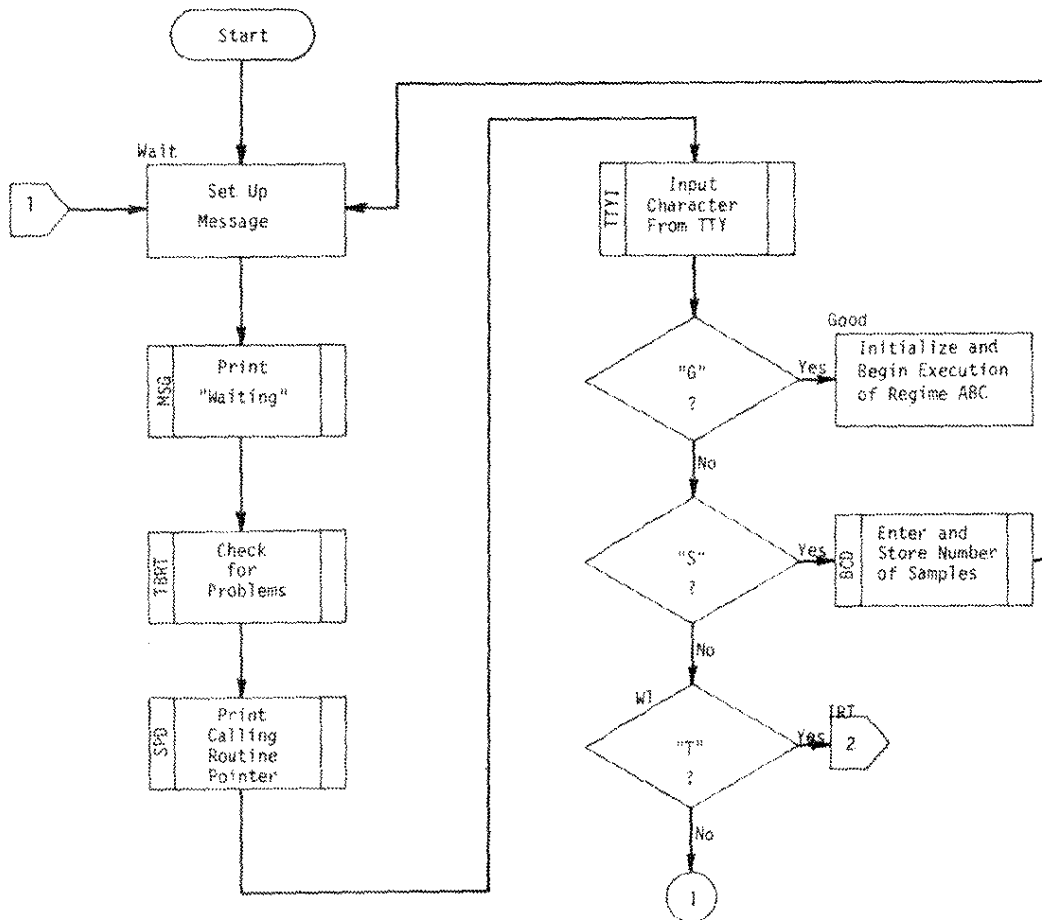
SUBROUTINE MSG

Print Message Beginning at Location Specified
by HL and Ending When "<" is Reached

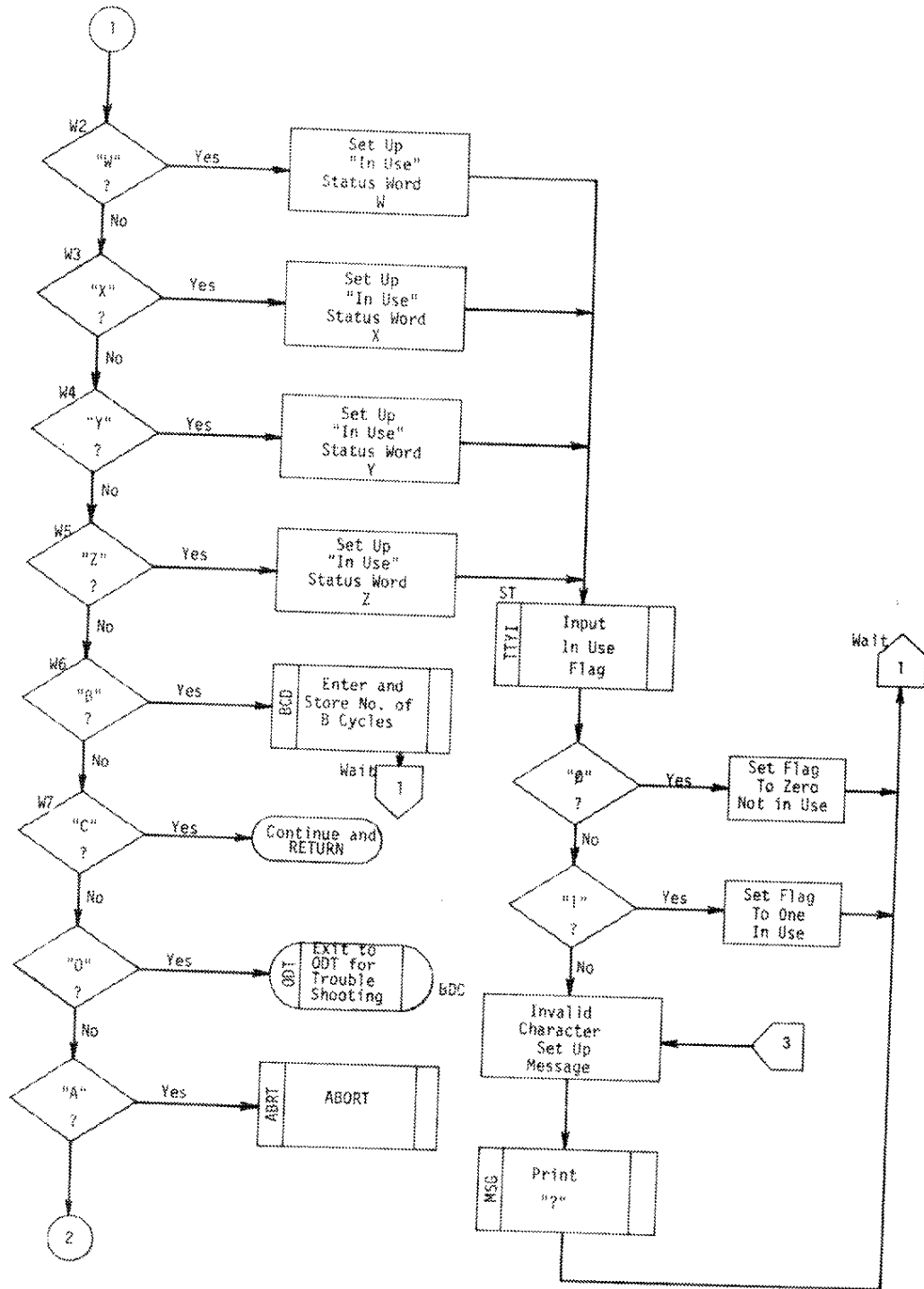


SUBROUTINE WAIT

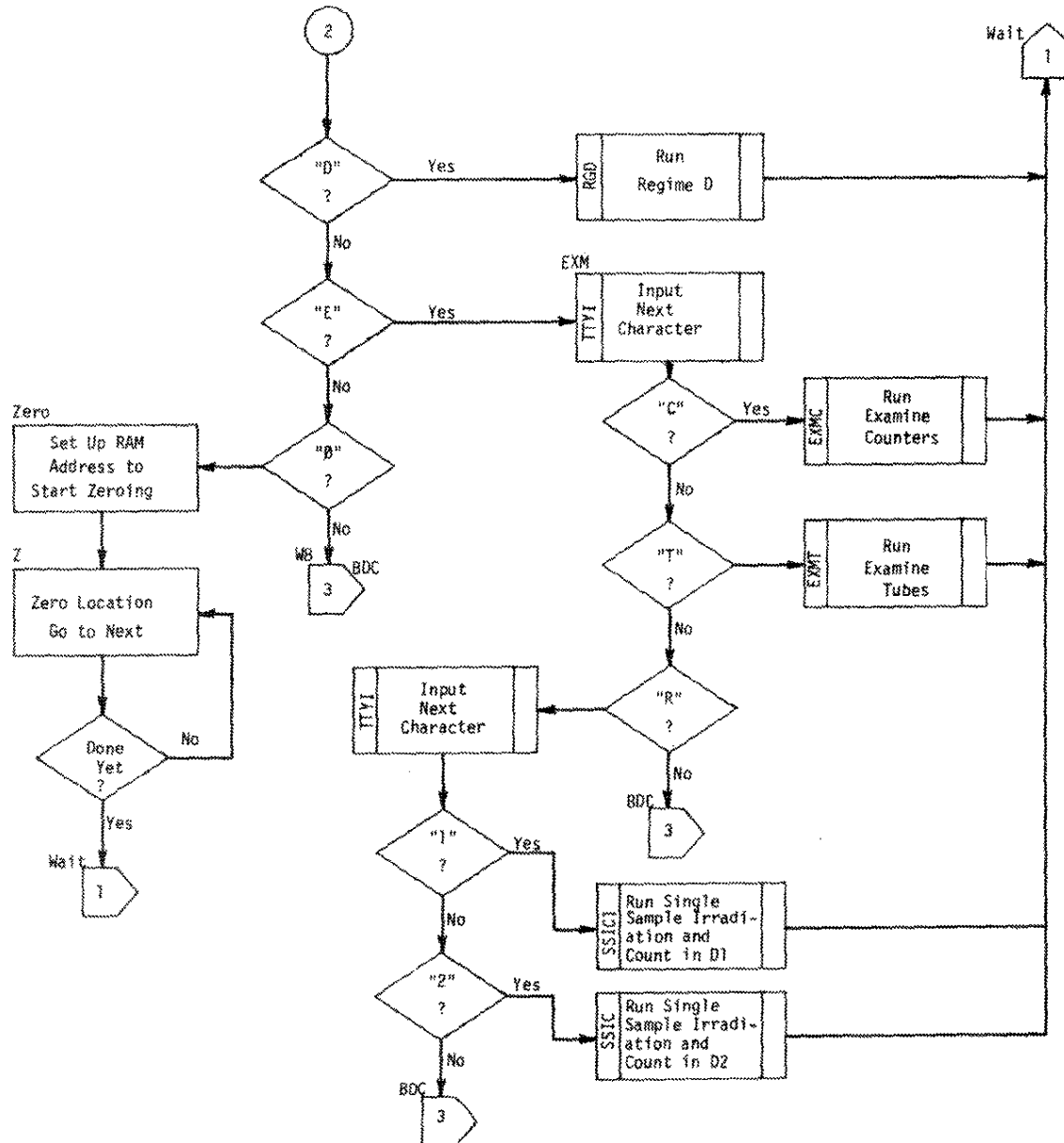
Act as Operating System of NRC. Enter or Clear Variable Parameters and Determine Operations to be Executed.



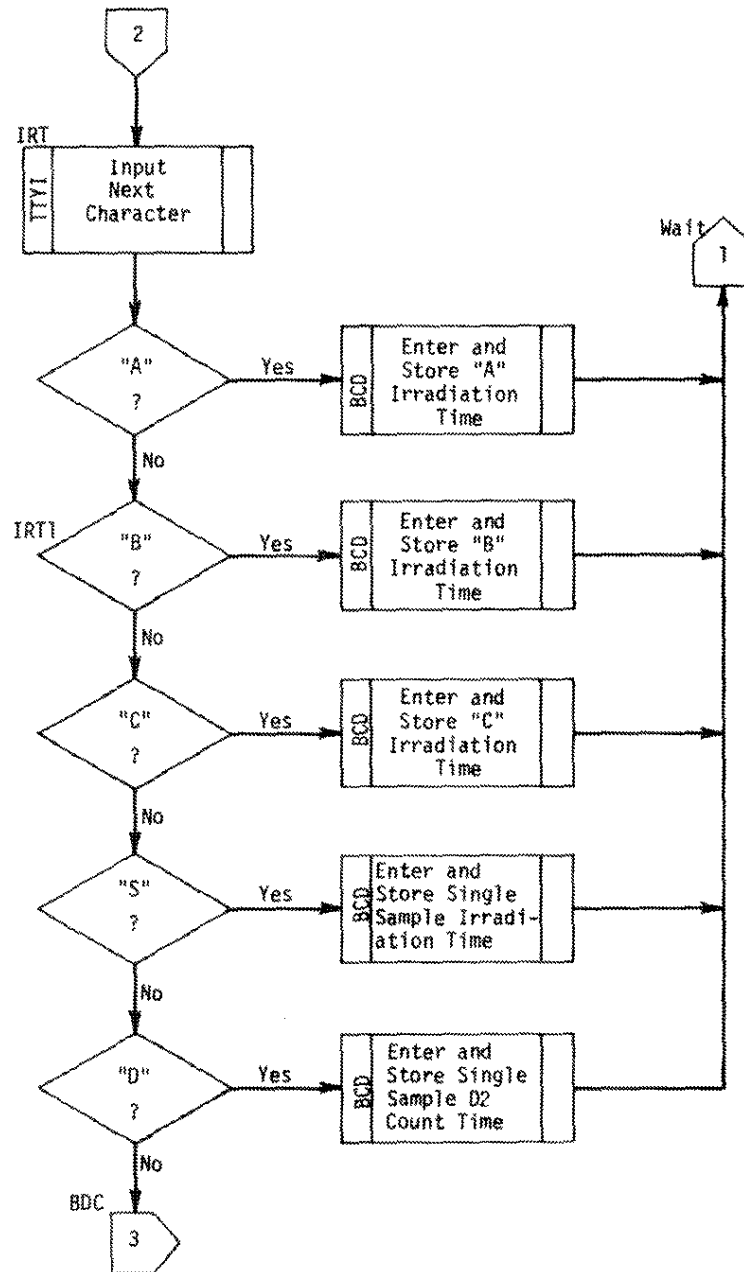
Subroutine Wait (Continuation)



Subroutine Wait (Continuation)

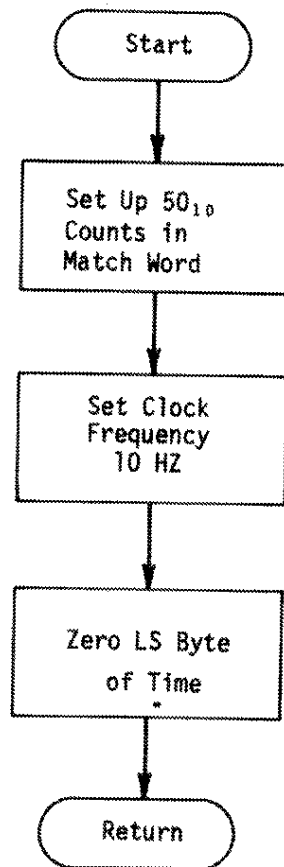


Subroutine Wait (Continuation)



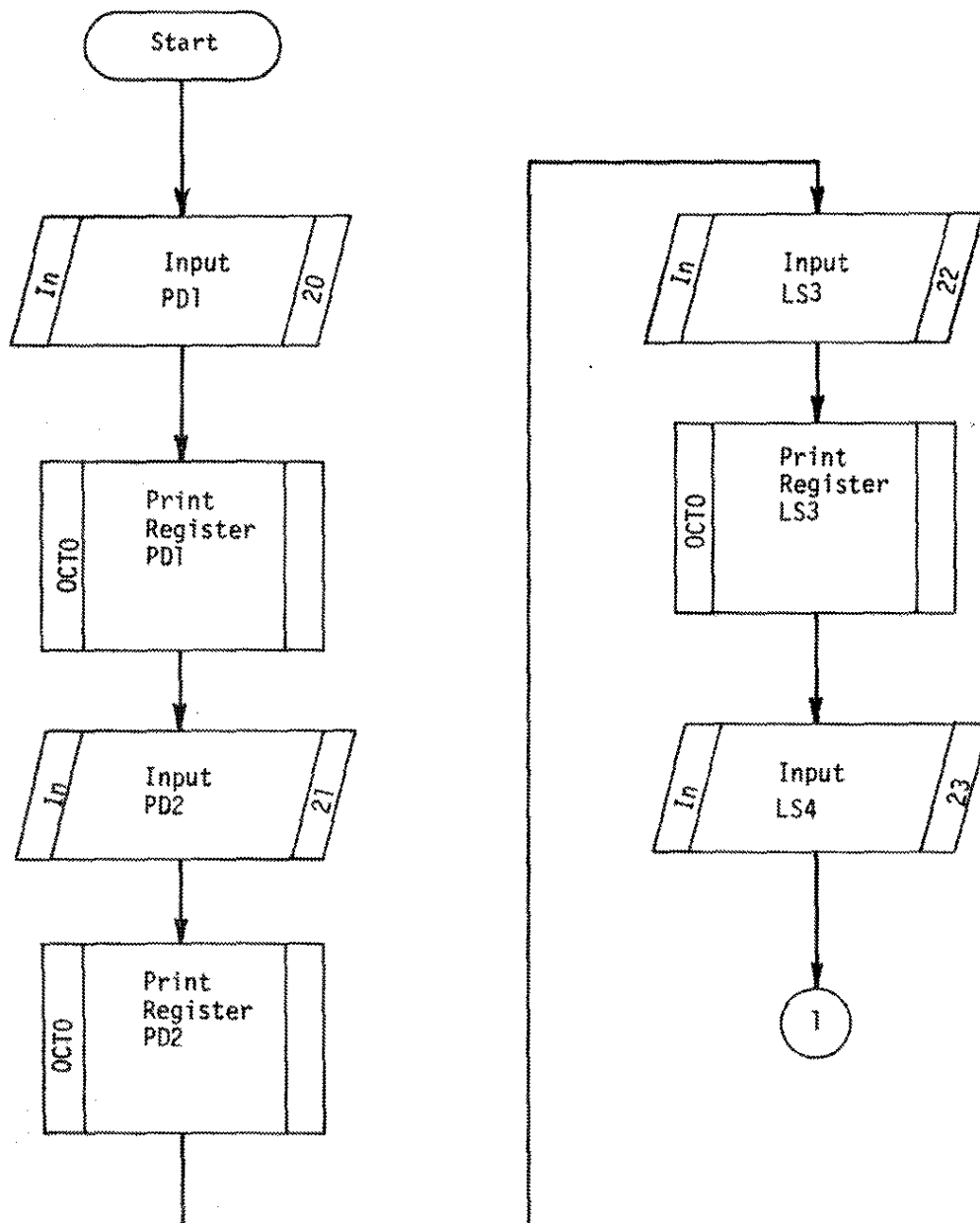
SUBROUTINE TM5

Start Time Clock and Set Up Time Check for Five Seconds

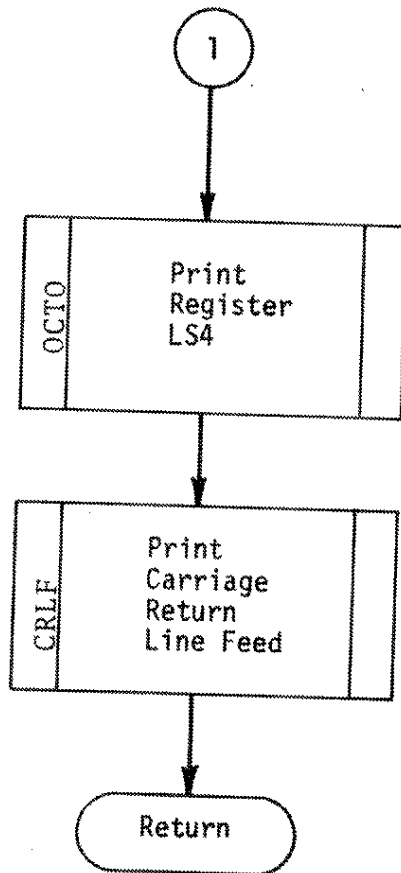


SUBROUTINE STDM

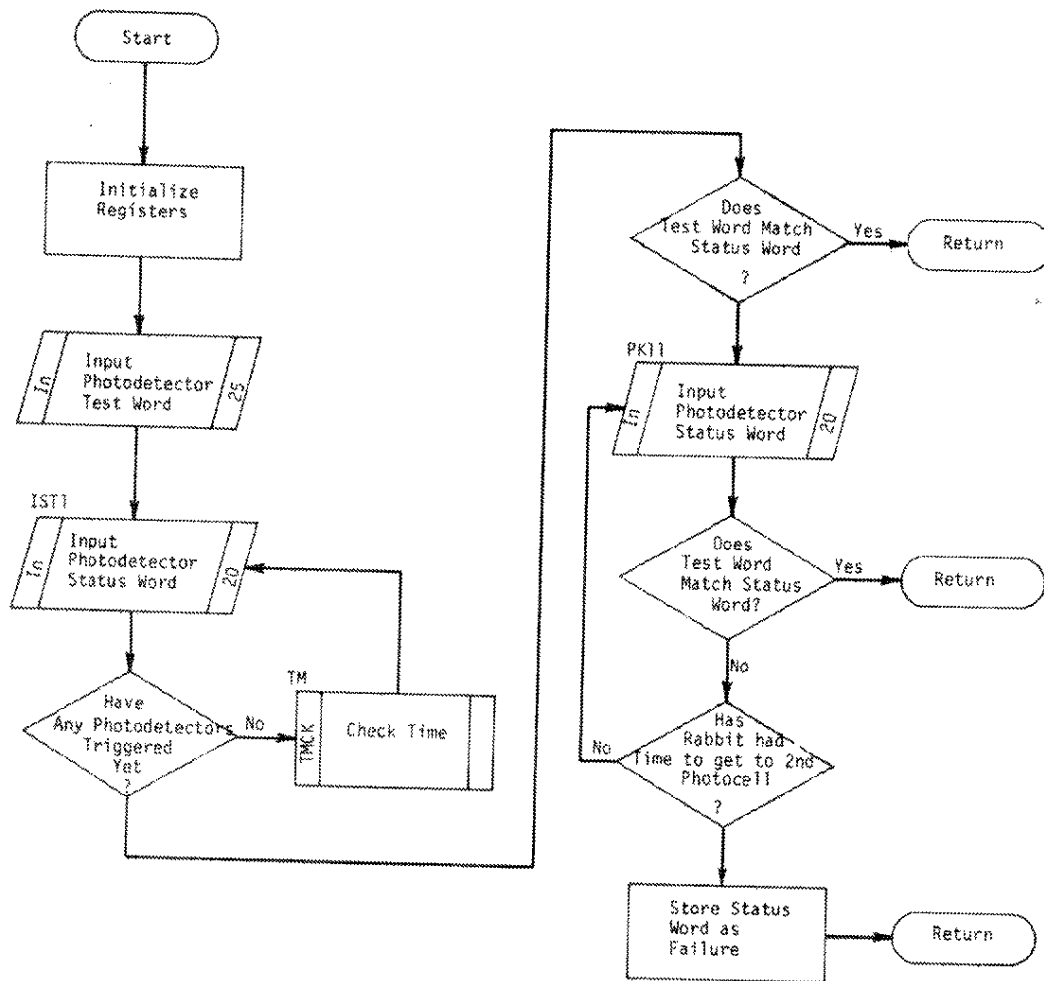
Dump Photodetector and Limit Switch Status Words



Subroutine STDM (Continuation)

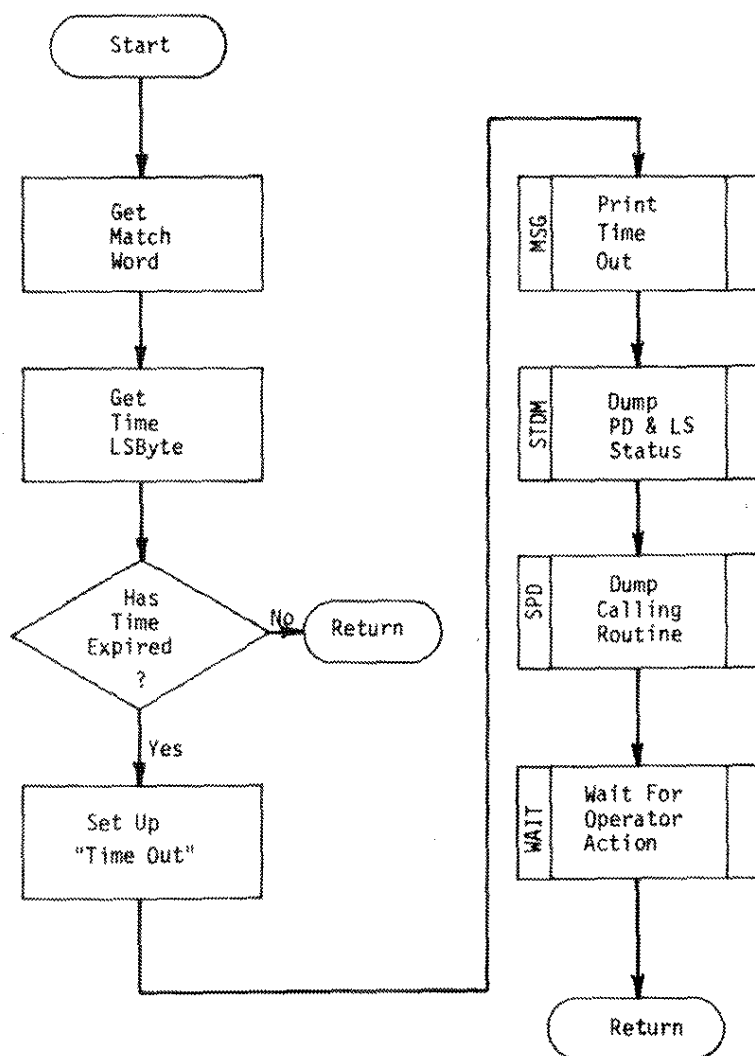


SUBROUTINE PDK1
Check Photodetectors at Reactor For Correct Actuation

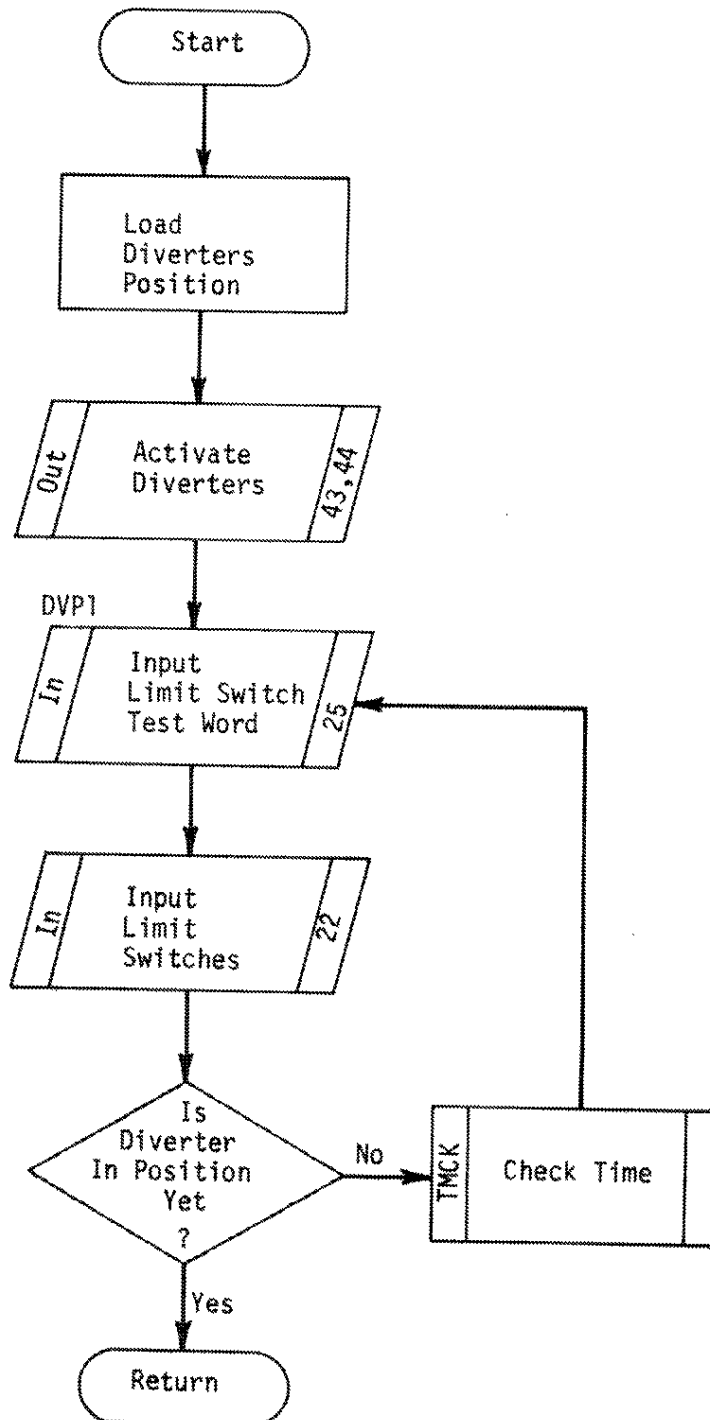


SUBROUTINE TMCK

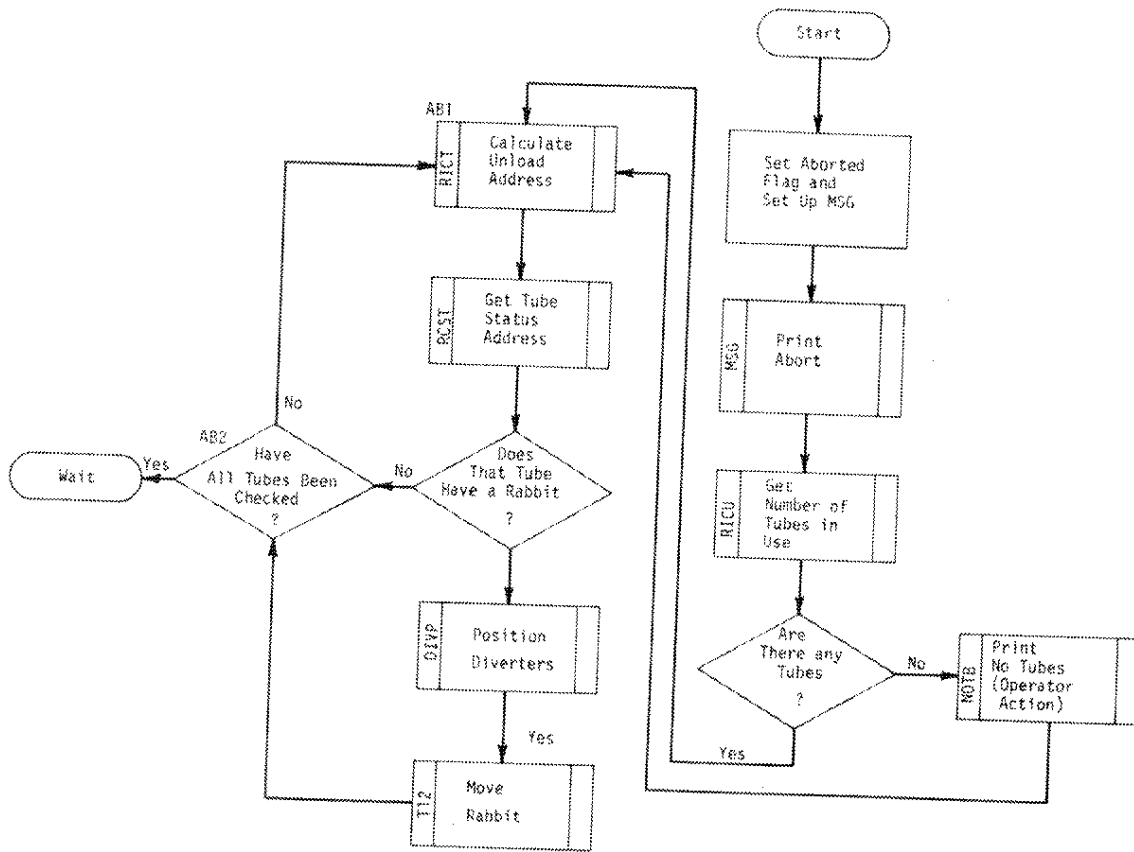
Compares Time Clock to a Match Word. If Time Has Not Expired, Routine Returns to Calling Routine. If Time Has Expired, Dumps Registers and Calls Wait. When Timed Out Operation Has Been Corrected the Program May Be Continued.



SUBROUTINE DIVP
Position Diverters

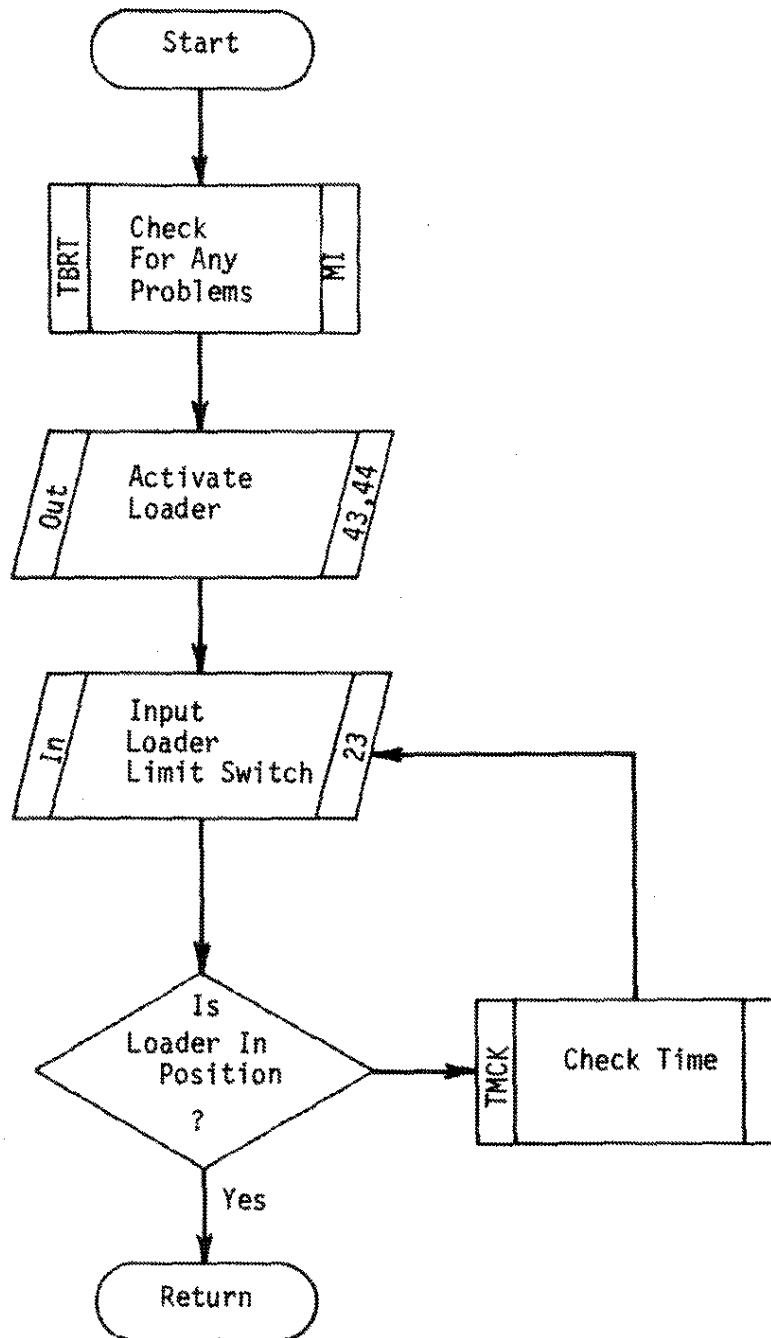


ROUTINE ABRT
Move All Rabbits in Reactor to D1



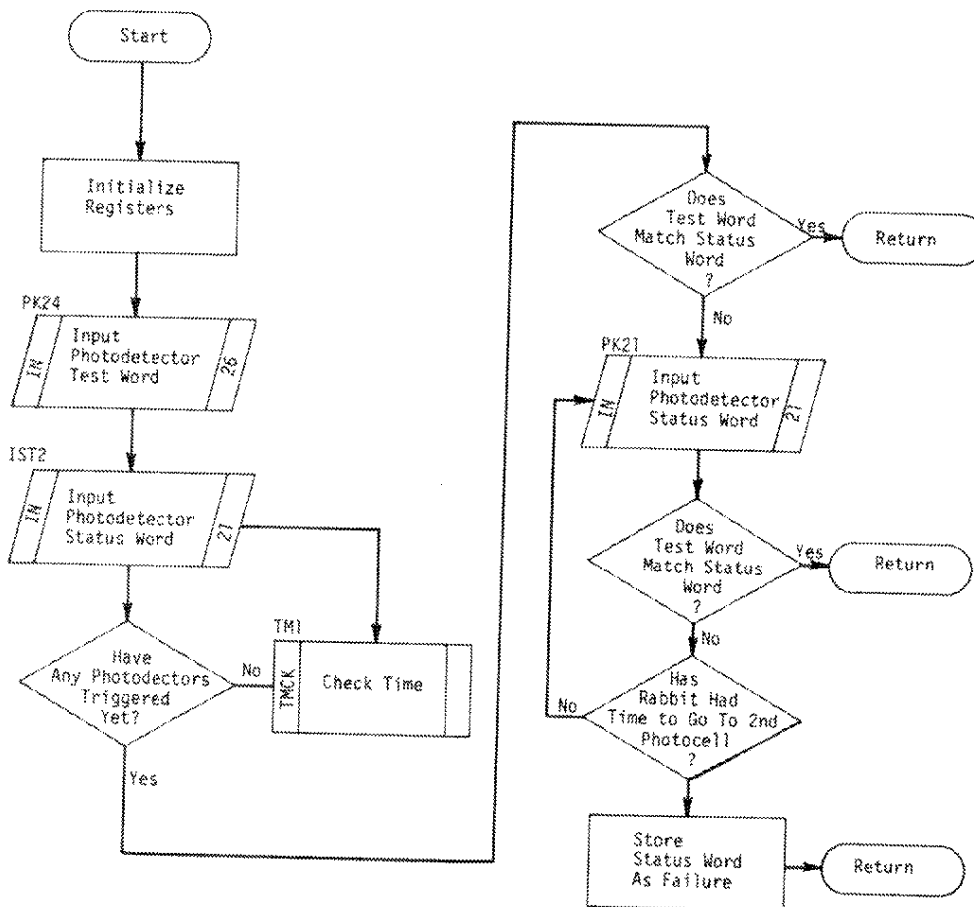
SUBROUTINE LDR

Set Up Loader to Put Rabbit in System

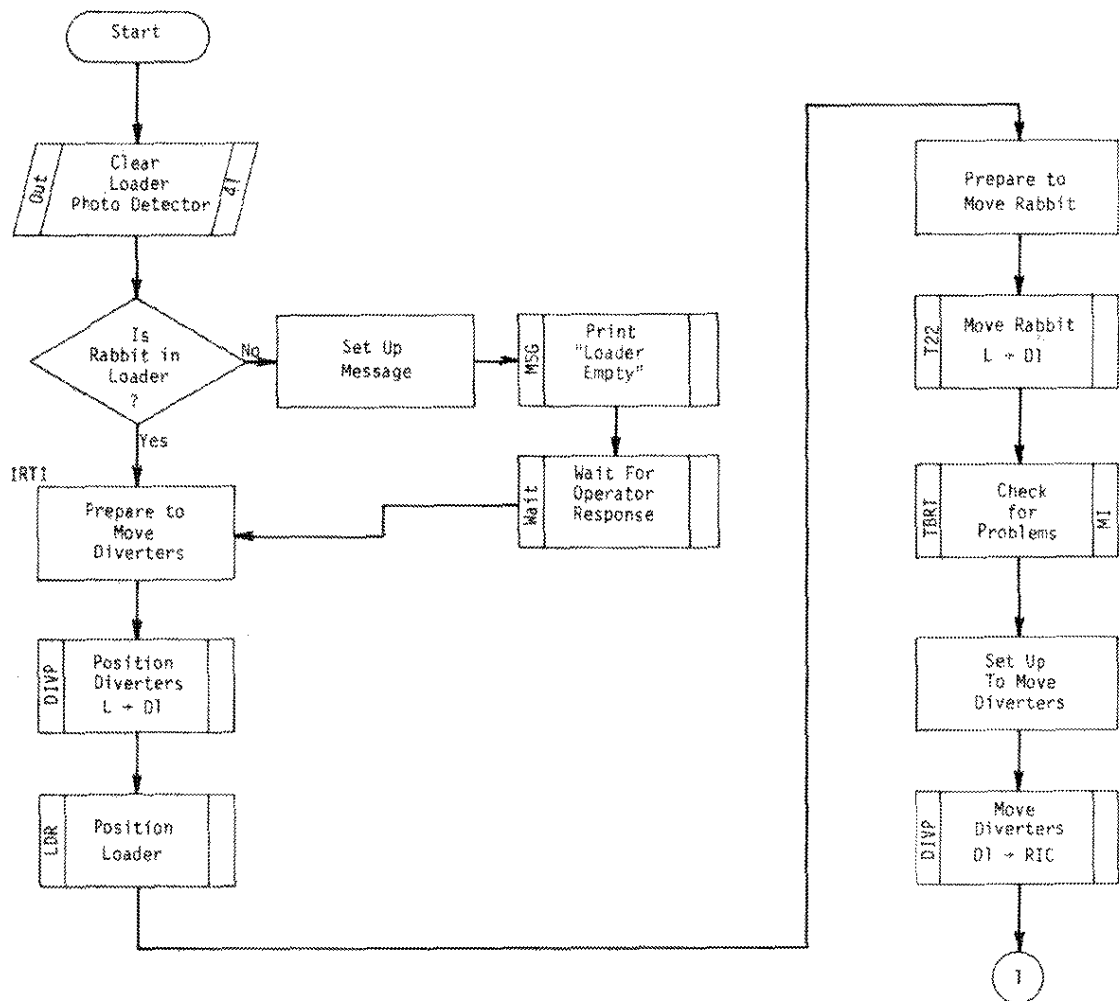


SUBROUTINE PDK2

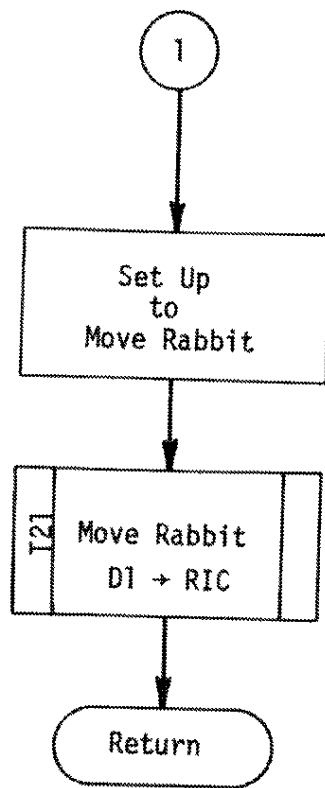
Check Photodetectors in CCM for Correct Actuation



SUBROUTINE IRRD
Move Rabbit from Loader into Reactor

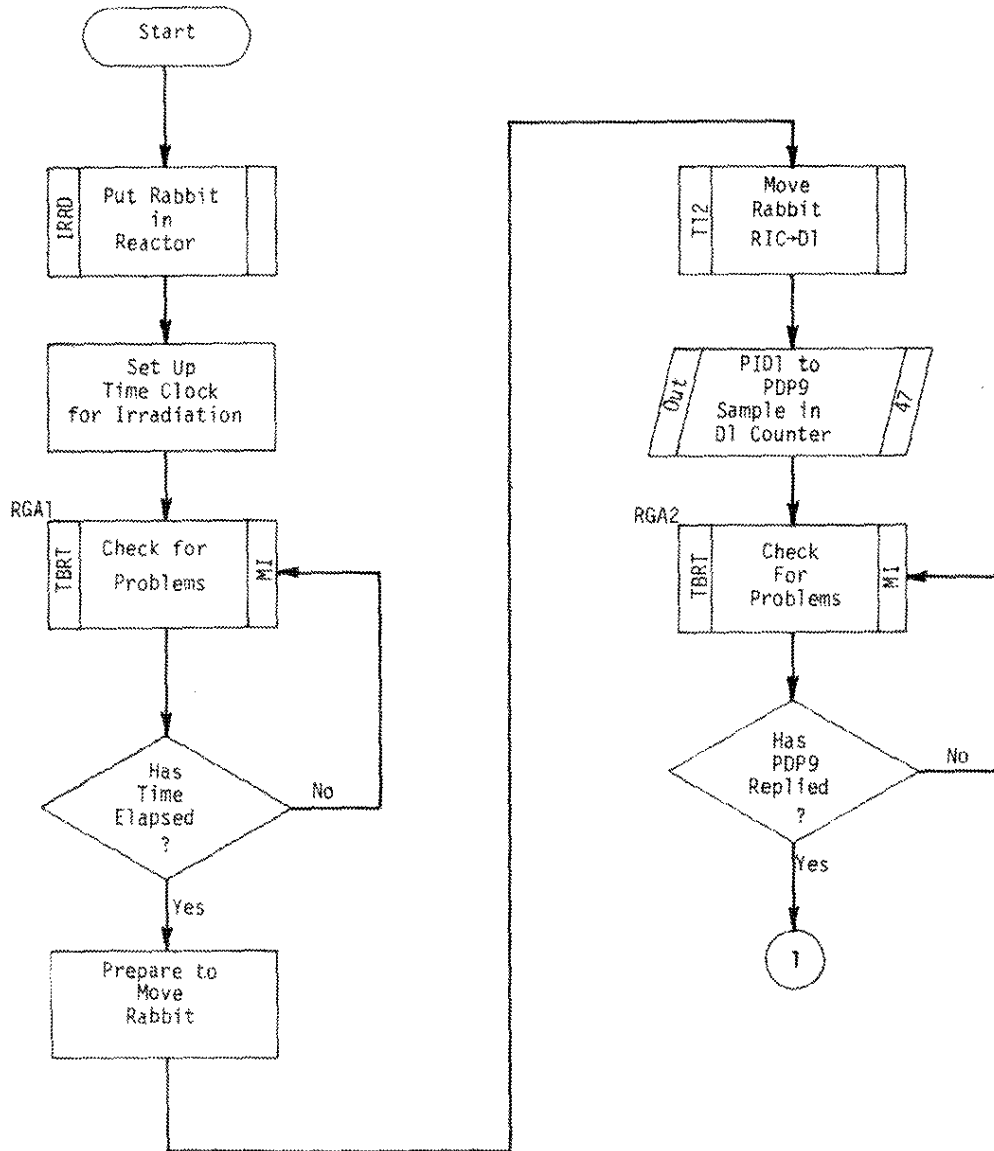


Subroutine IRRD (Continuation)

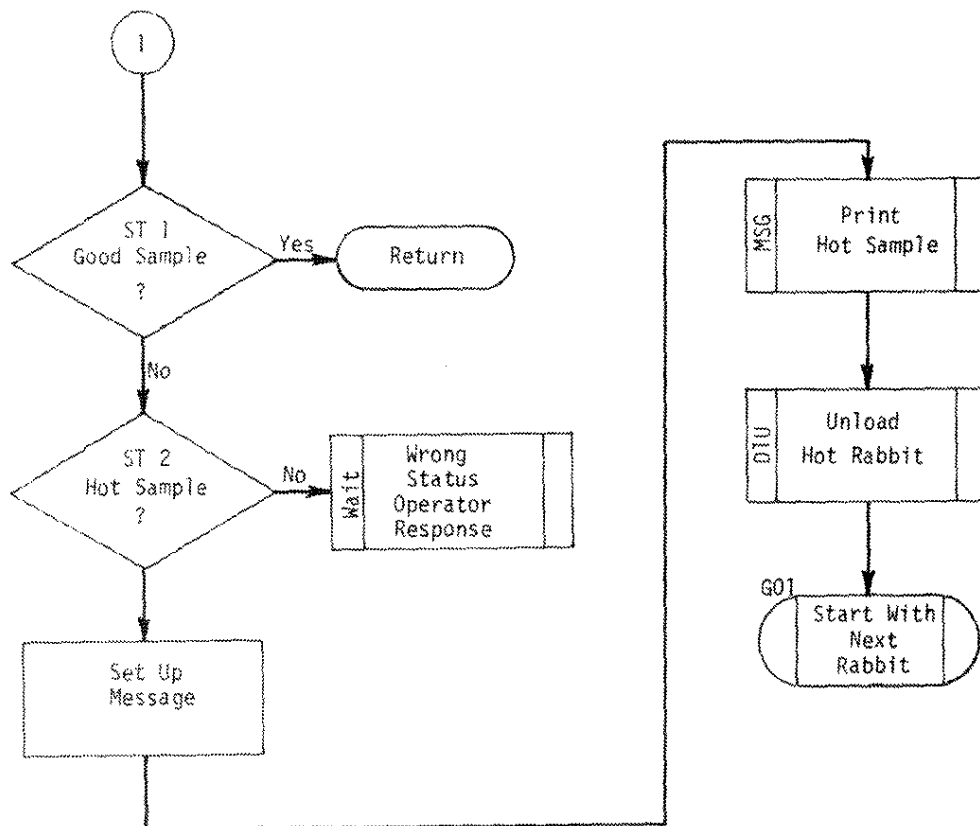


SUBROUTINE RGA

Regime A for Production Run. Give Sample Short Irradiation. Allow PDP9 to Count. If Activity too High, Reject Sample. Otherwise Continue With Analysis.

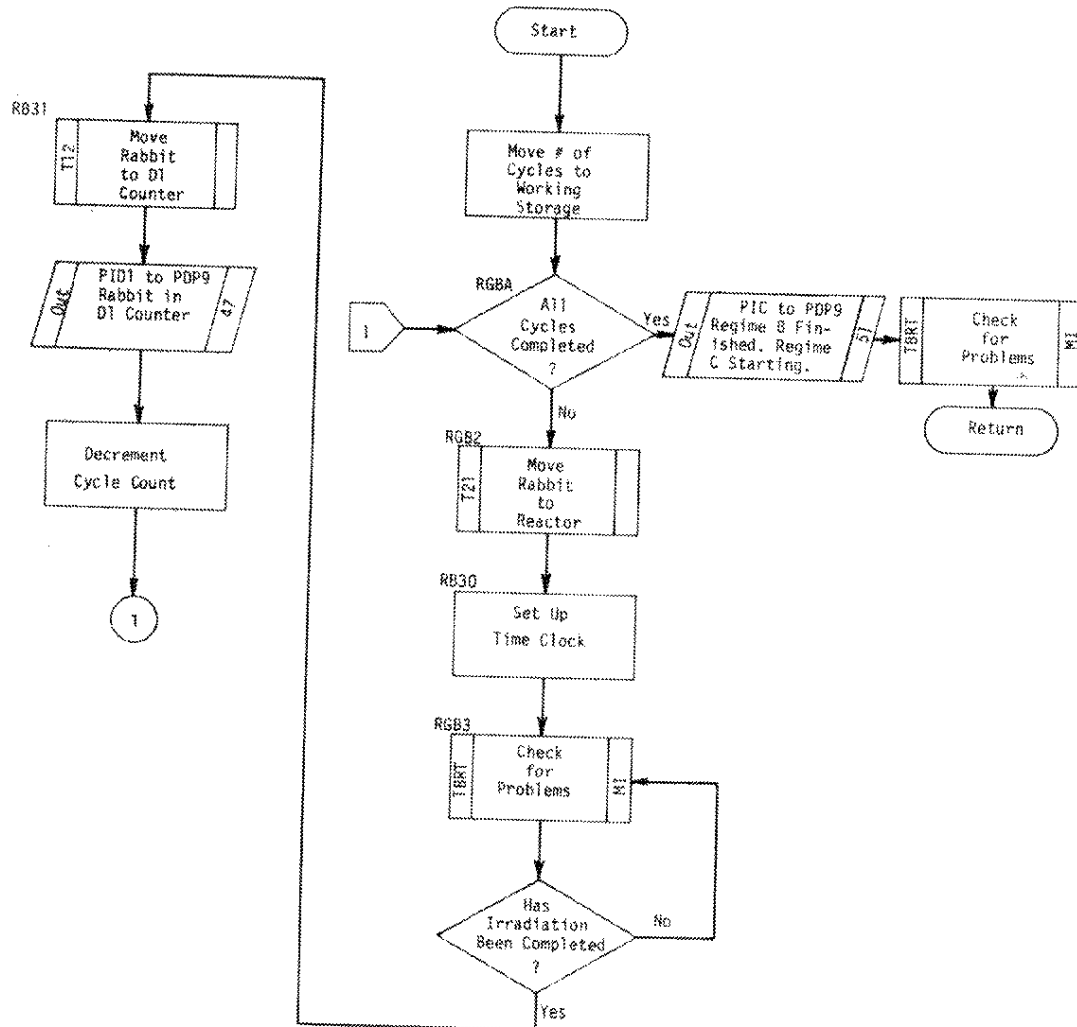


Subroutine RGA (Continuation)

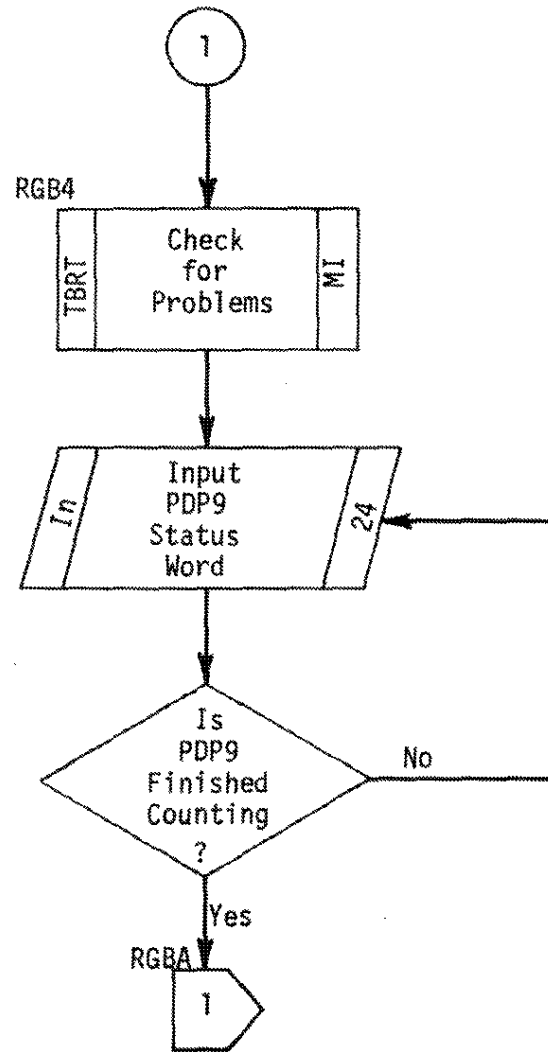


SUBROUTINE RGB

Regime B for Production Run. Cycle Sample Rabbit Through Specified Number of Irradiations and Counts.

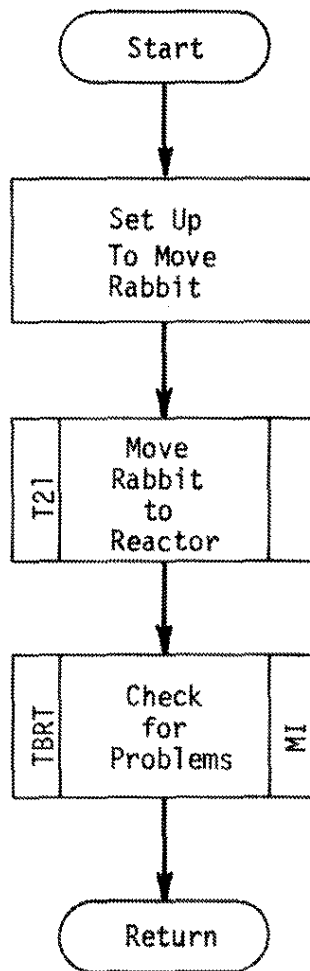


Subroutine RGB (Continuation)



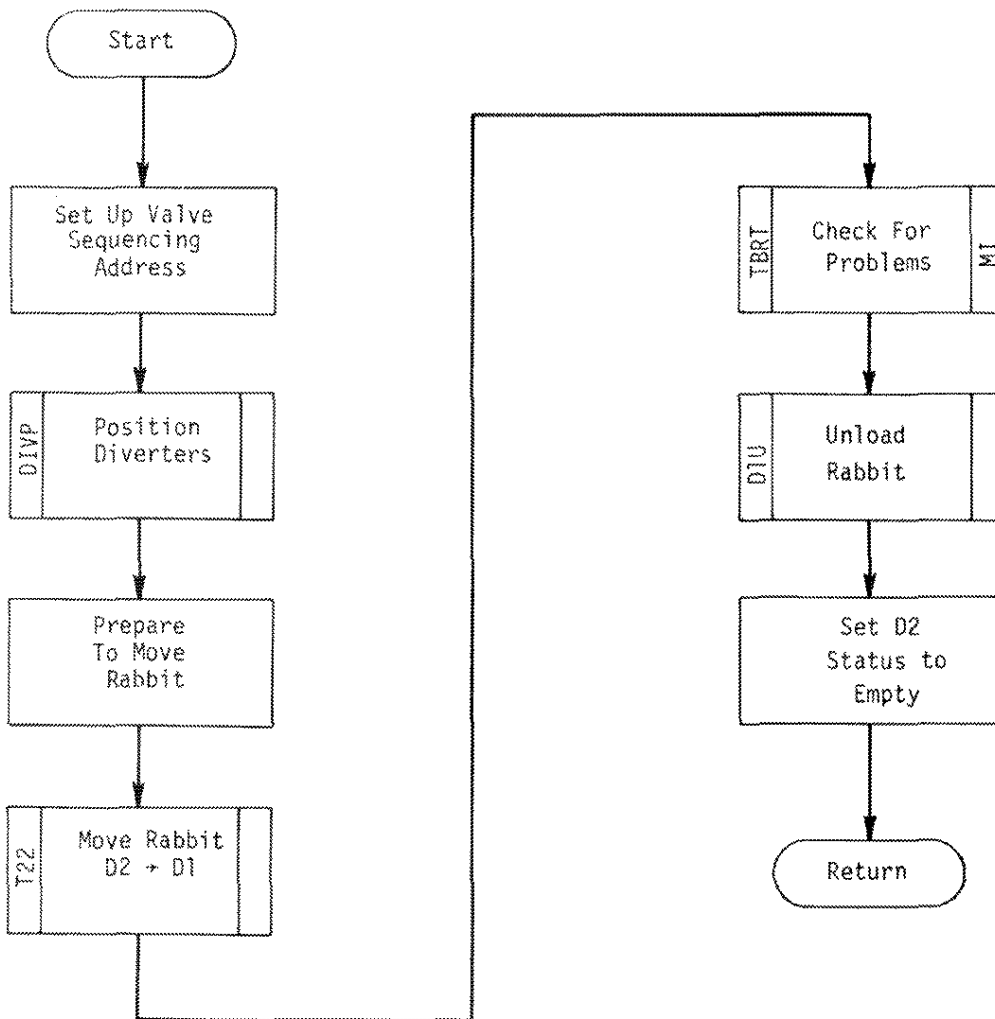
SUBROUTINE IRGC

Initiate Regime C for Production Run.
Leave Rabbit in Reactor Before Starting New Sample.



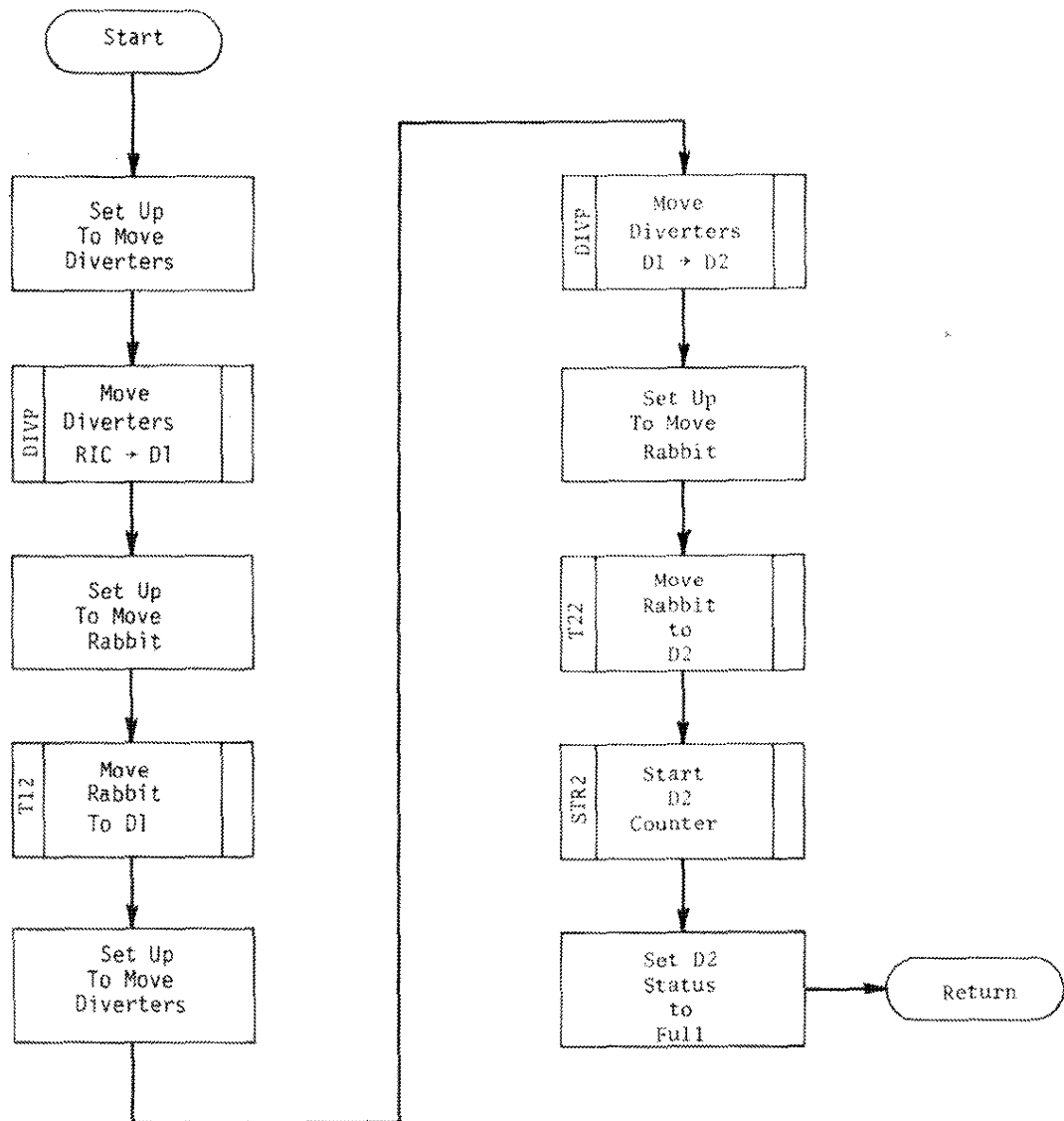
SUBROUTINE UND2

Unload GELI D2



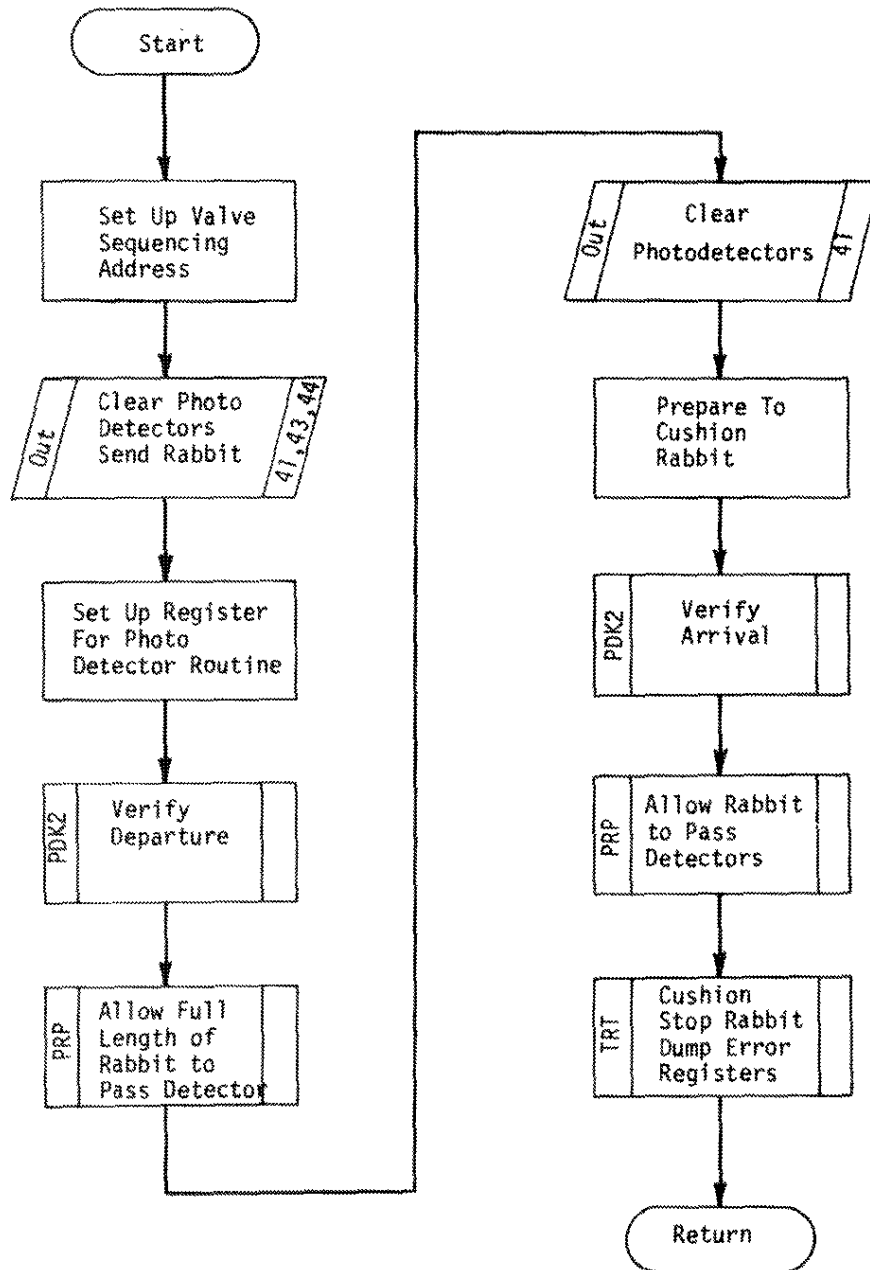
SUBROUTINE TRGC

Remove Rabbit from Reactor After Long Irradiation and Move to D2 Counter for Long Count on Canberra.



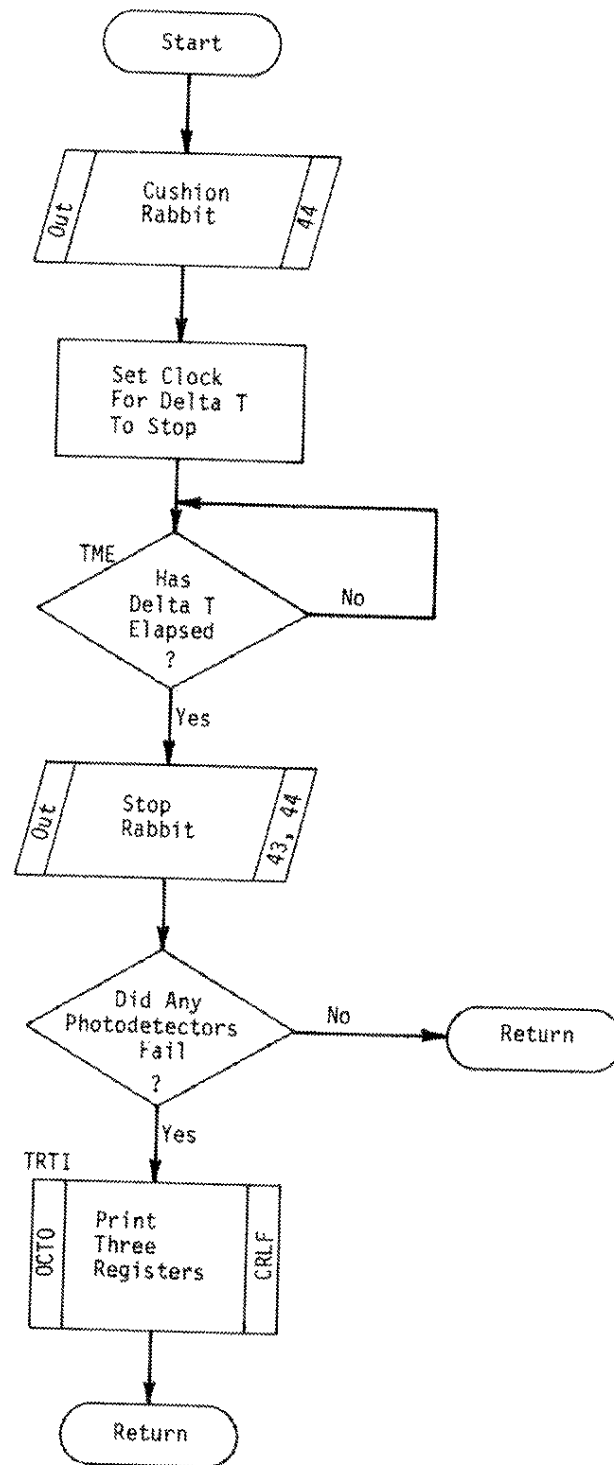
SUBROUTINE T22

Transport Rabbit Between Points Within the CCM



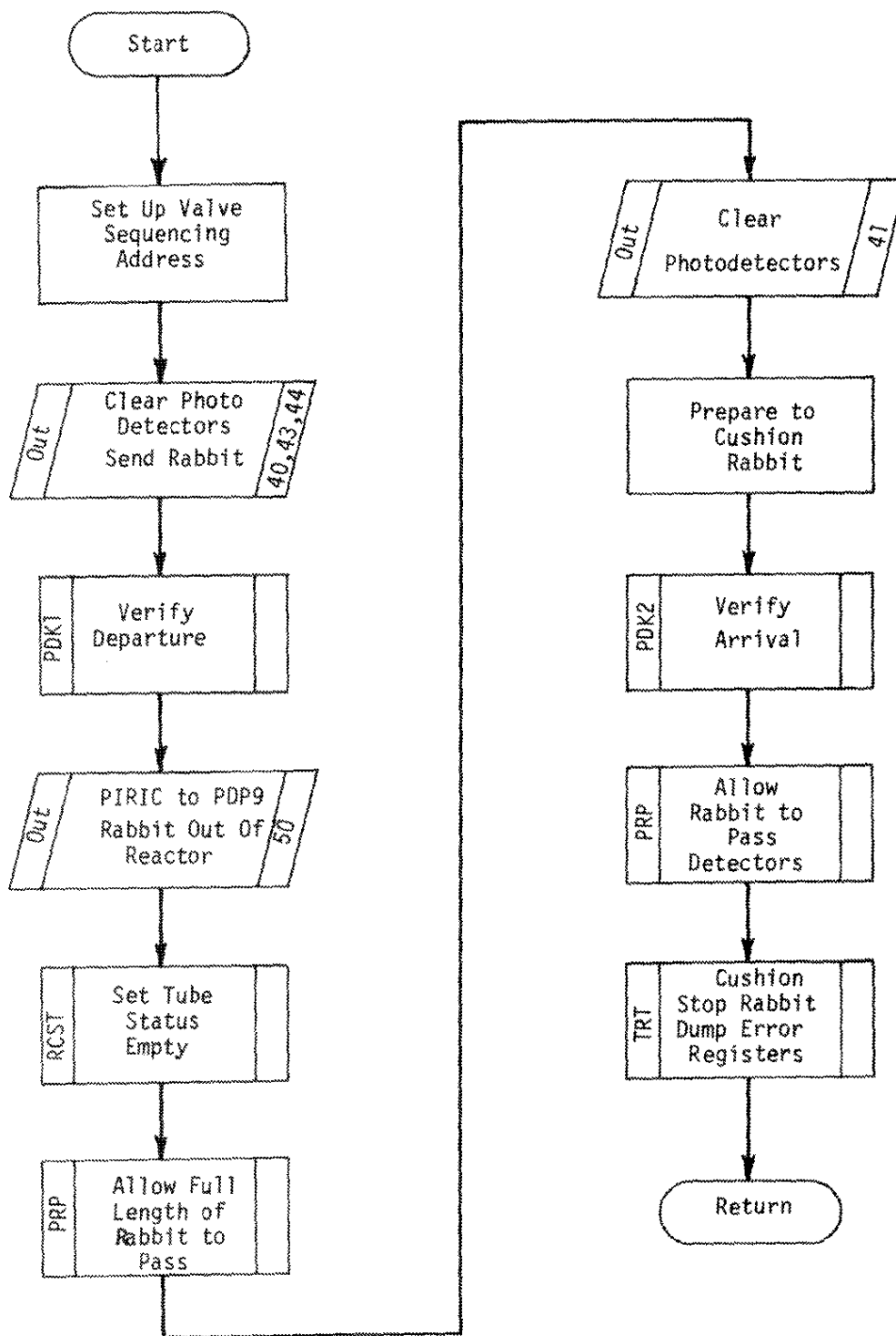
SUBROUTINE TRT

Terminate Transport Routines. Cushion and Stop Rabbit. Dump Error Registers if Photodetector Fails.



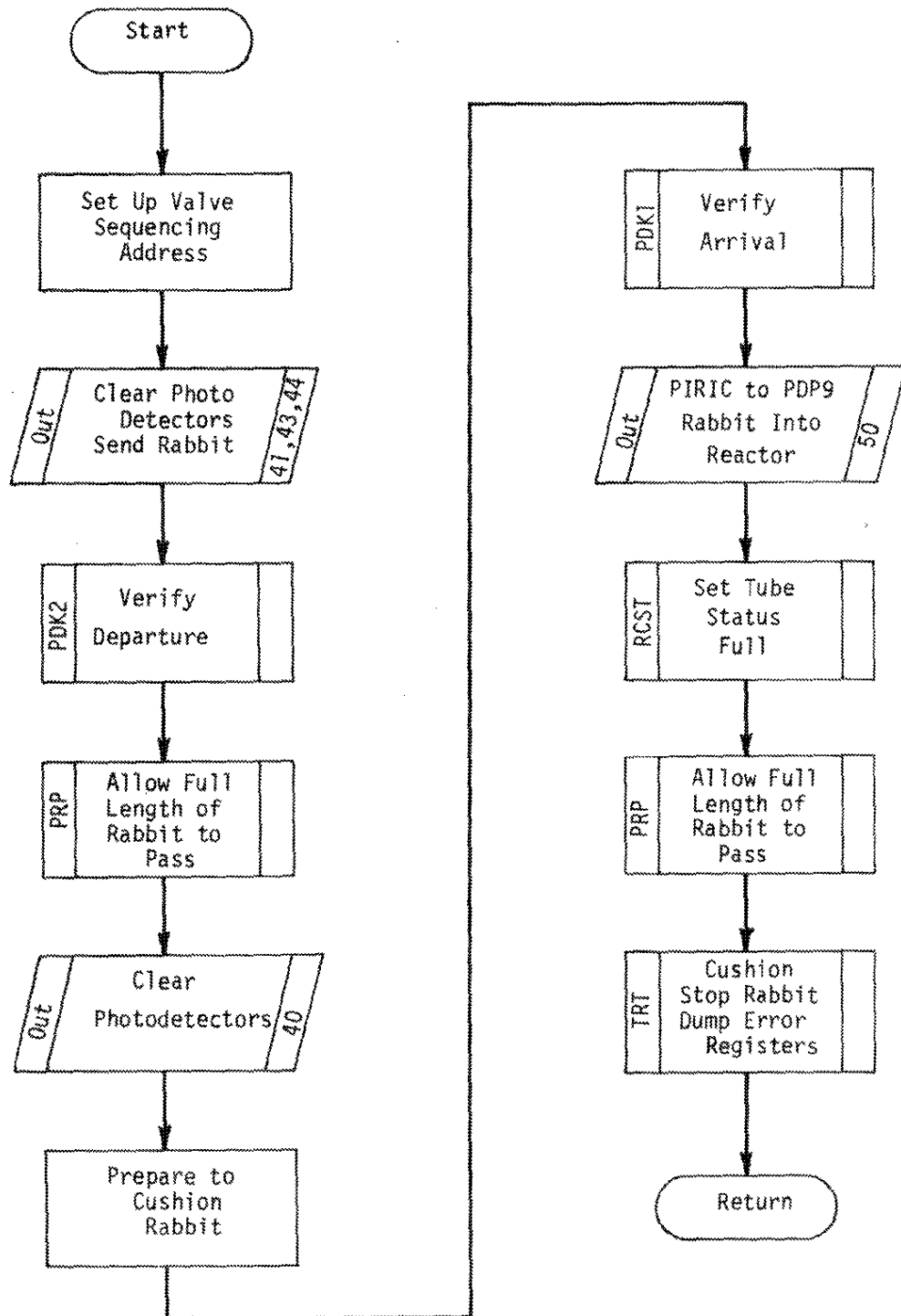
SUBROUTINE T12

Transport Rabbit From Reactor to CCM



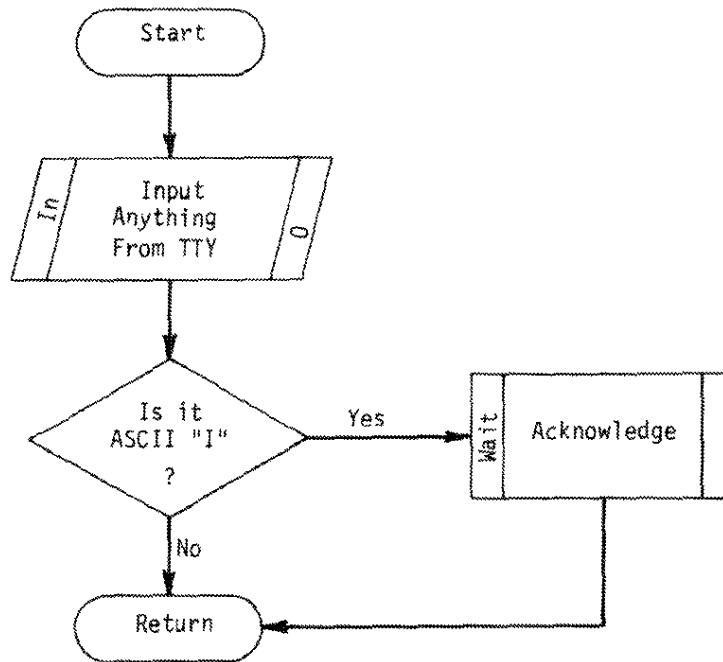
SUBROUTINE T21

Transport Rabbit to Reactor From CCM



SUBROUTINE MI

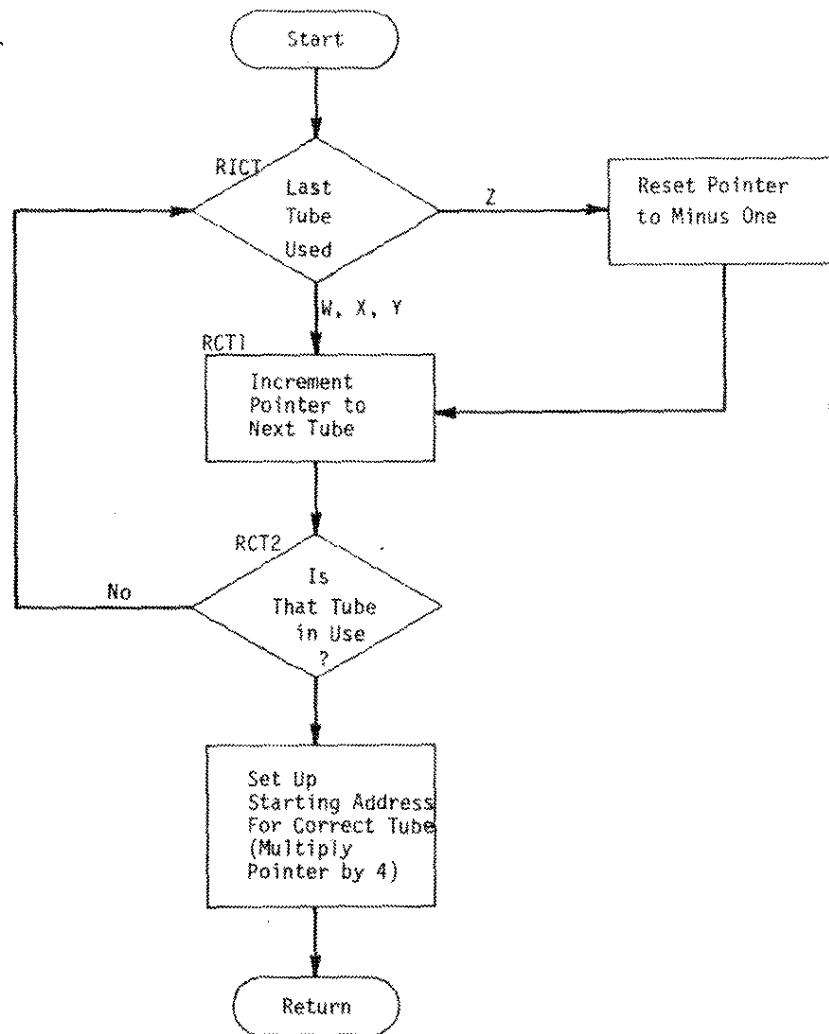
Monitor Teletype for Signal That Operator Wishes to Gain Control



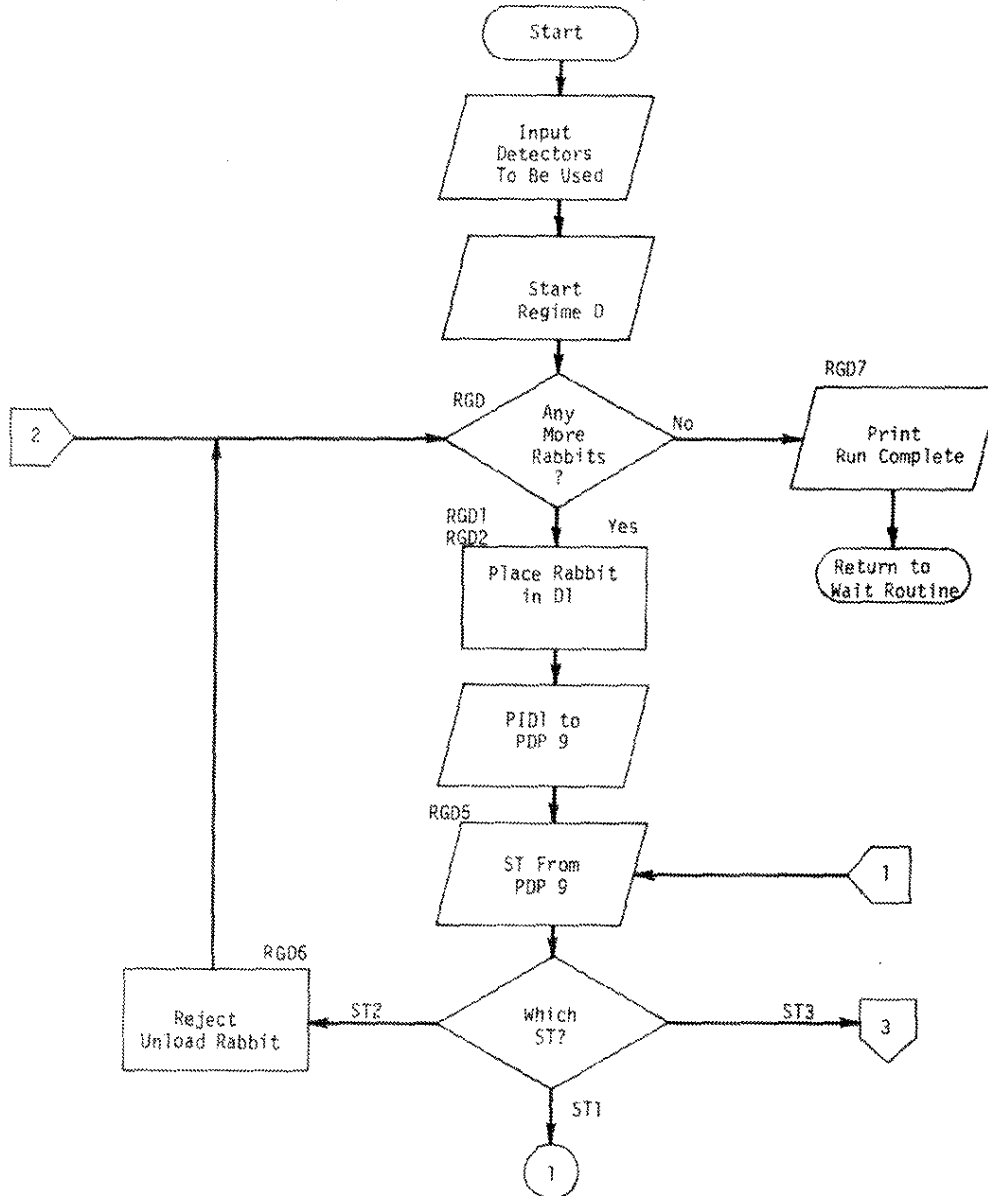
SUBROUTINE RICT
DETERMINES WHICH TUBE TO USE NEXT

RICP = Pointer

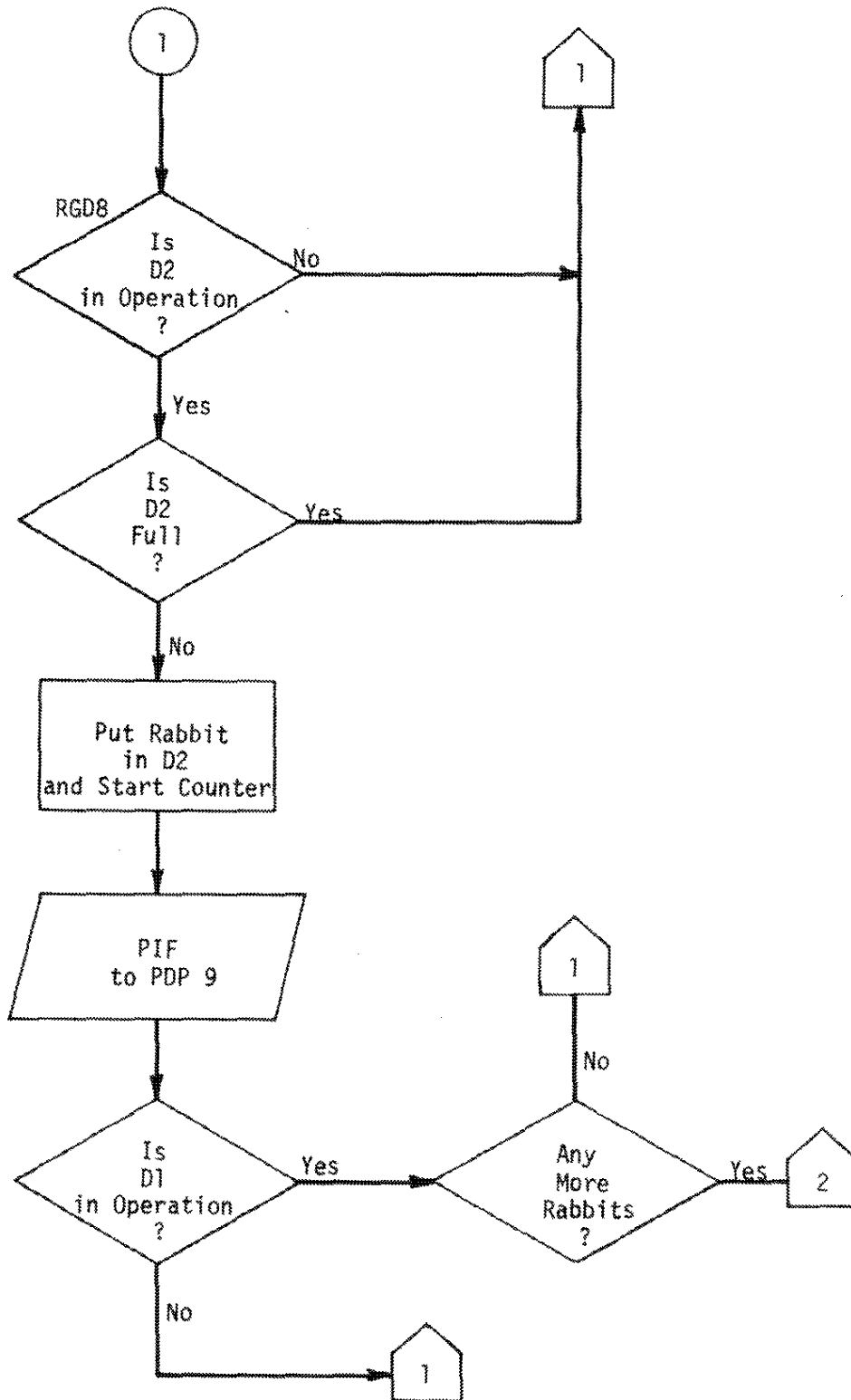
W = 0
X = 1
Y = 2
Z = 3



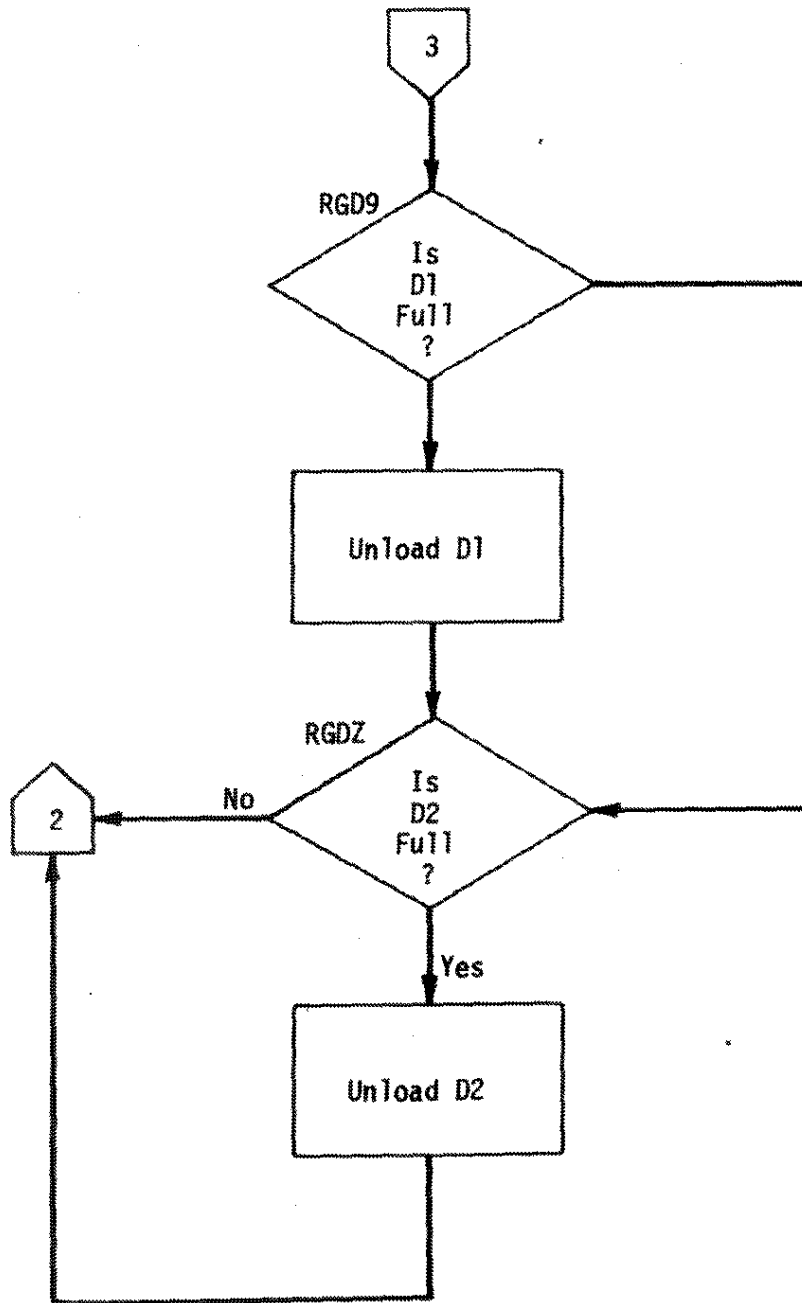
ROUTINE RGD
 Regime D of Production Run
 Move Samples to D1 and/or D2 for Long Counts, Then Unload



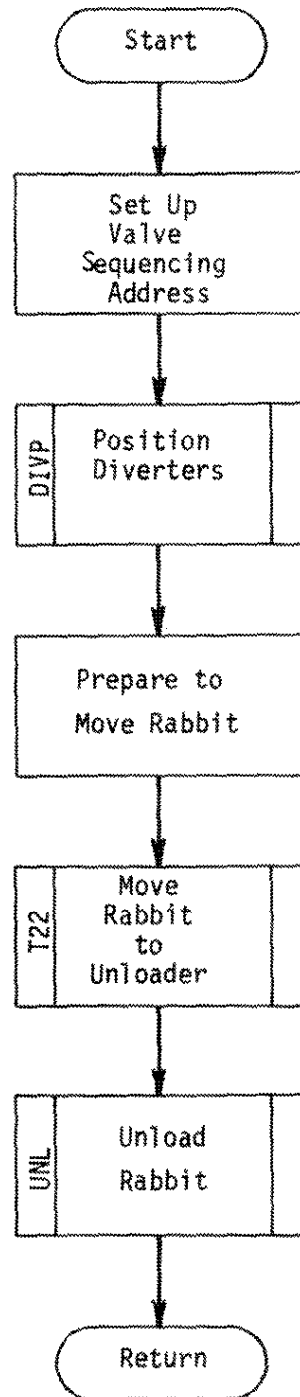
Routine RGD (Continuation)



Routine RGD (Continuation)

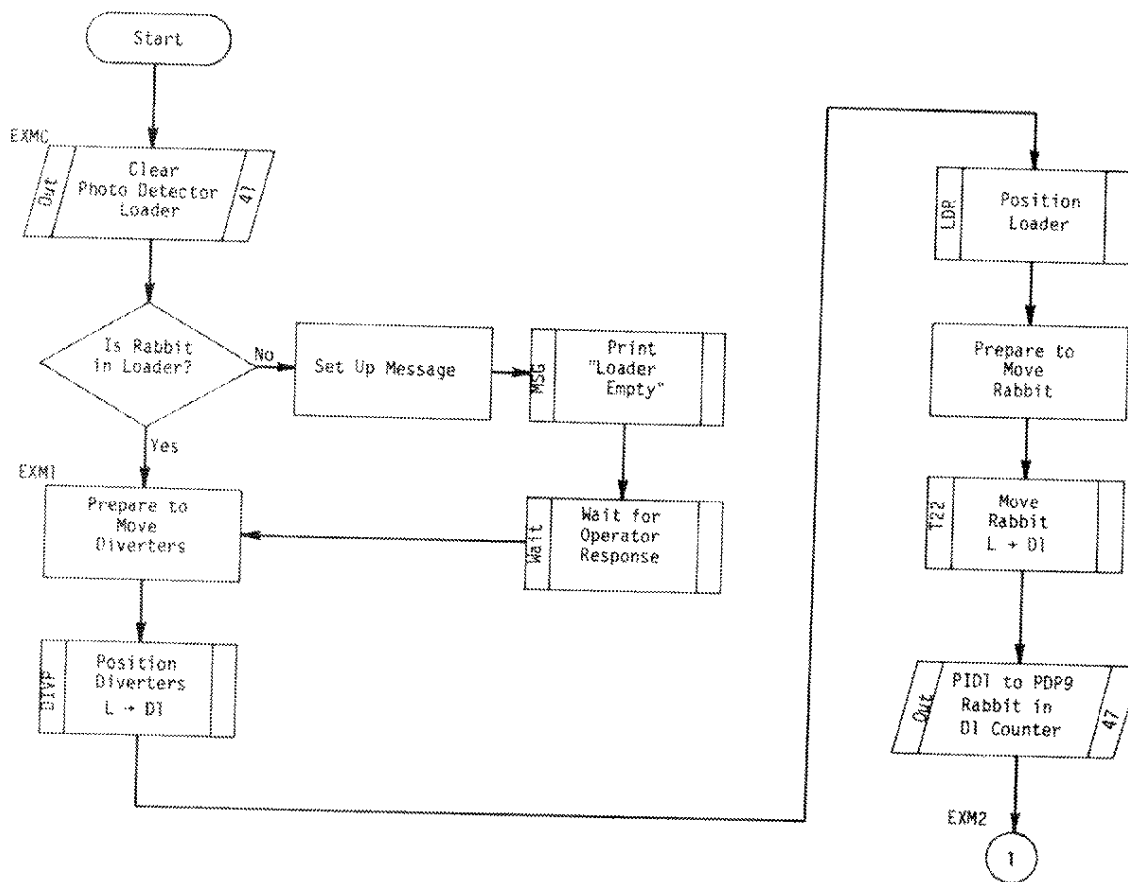


SUBROUTINE D1U
Unload Rabbit From D1

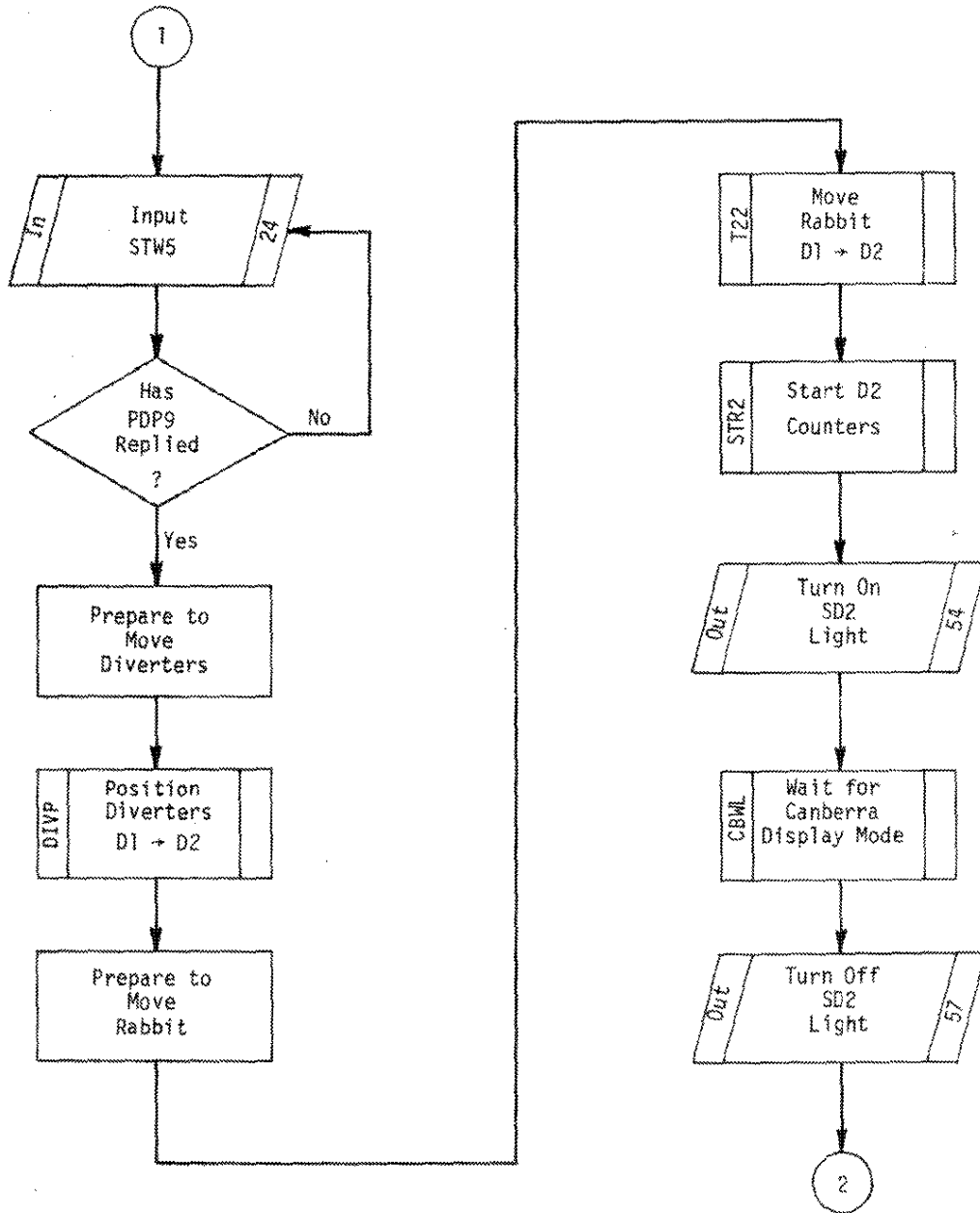


ROUTINE EXMC

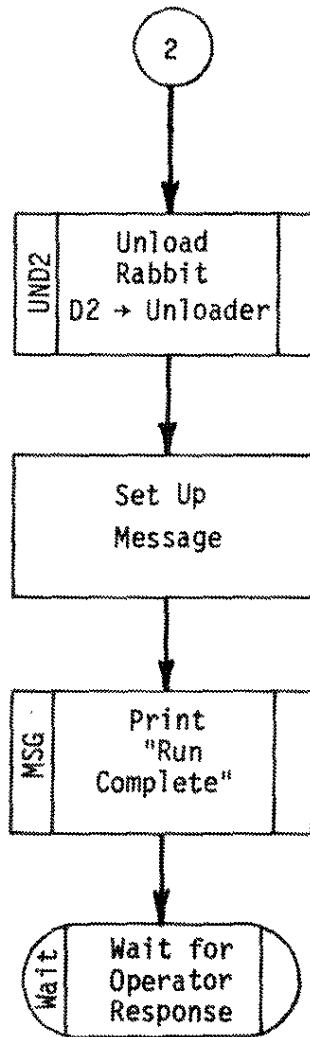
Move Rabbit from Loader to D1. Wait for PDP9 to Finish Counting. Move Rabbit to D2. Wait for Canberra to Finish Counting. Unload Rabbit.



Routine EXMC (Continuation)

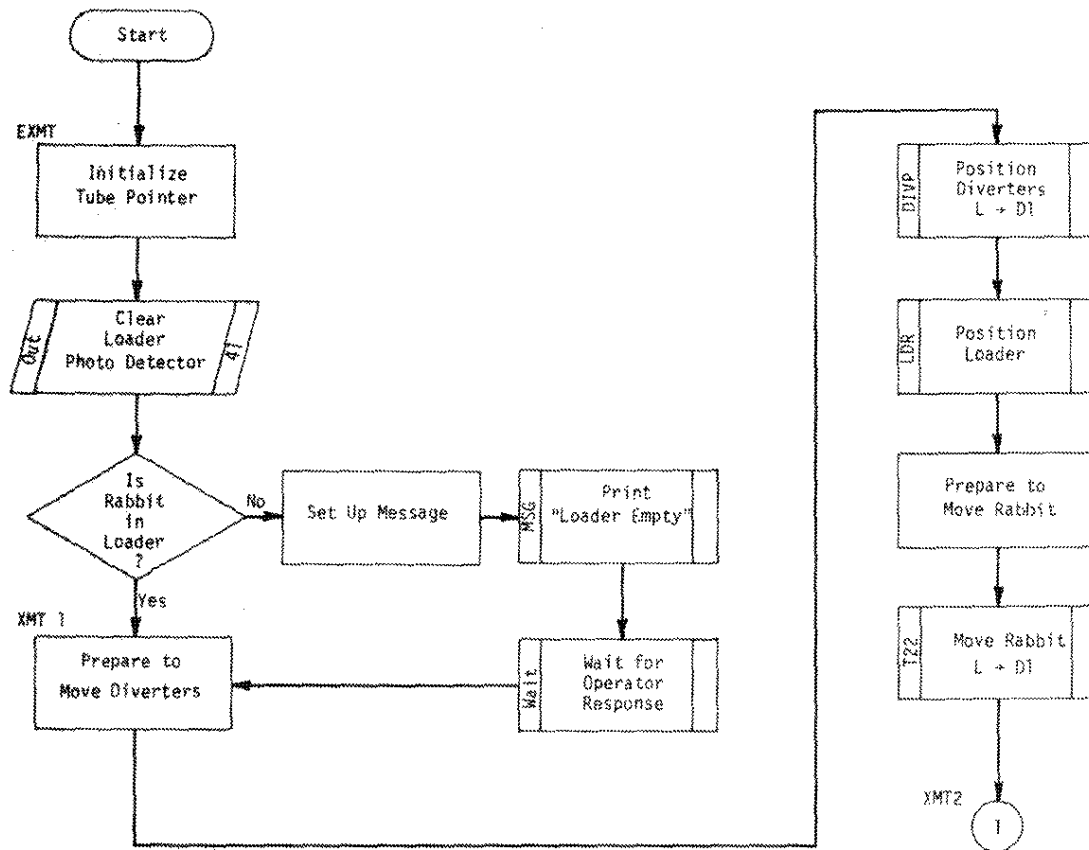


Routine EXMC (Continuation)

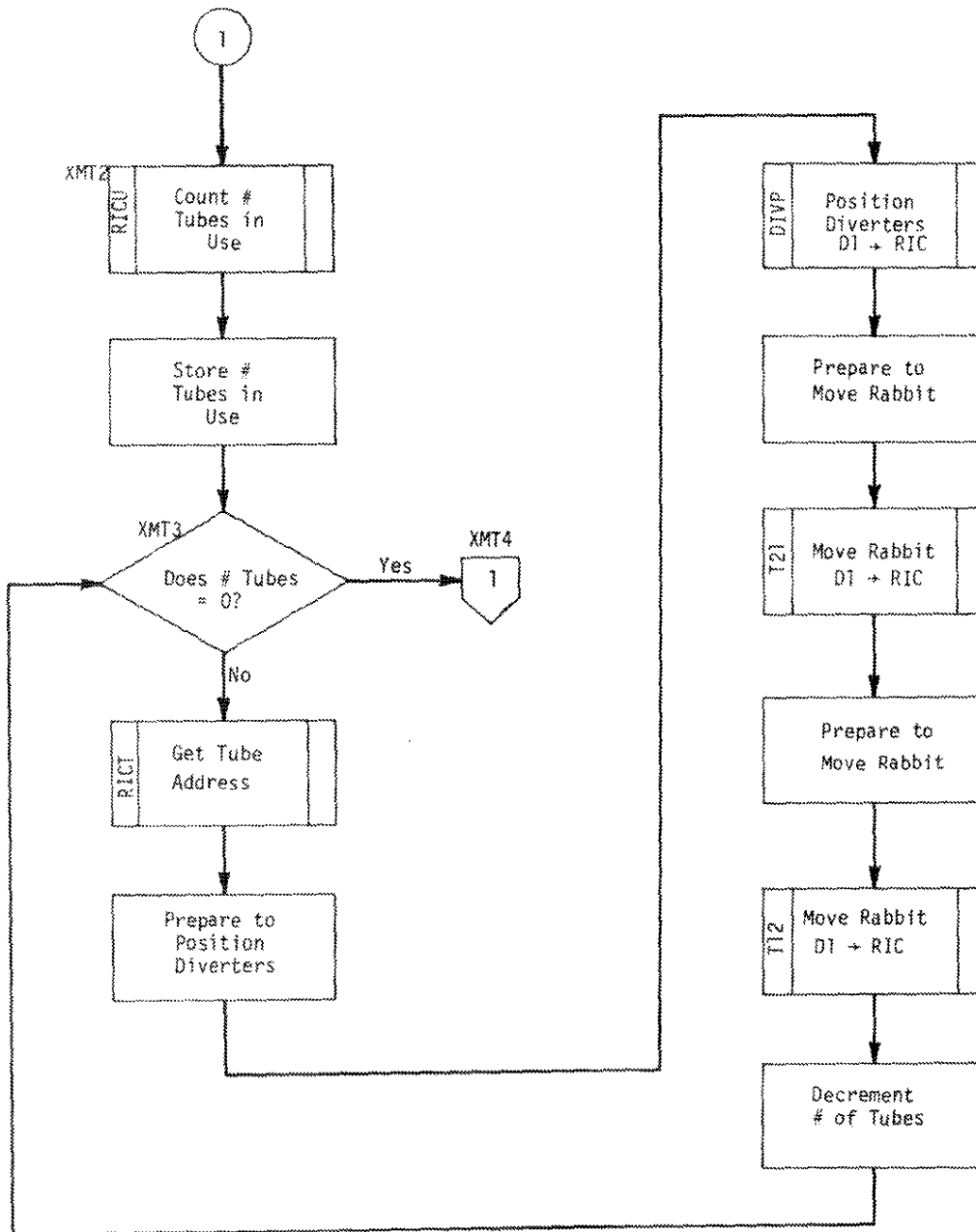


ROUTINE EXMT

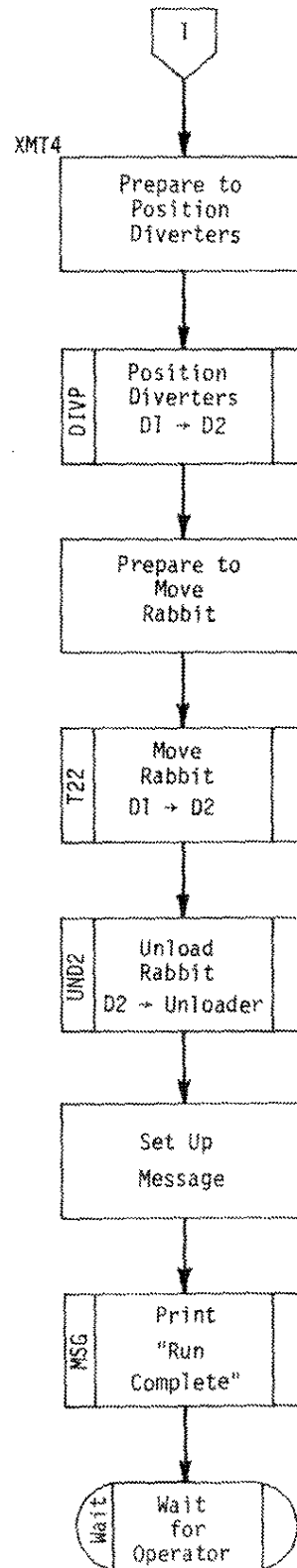
Move Rabbit Through all Possible Paths and Unload



Routine EXMT (Continuation)

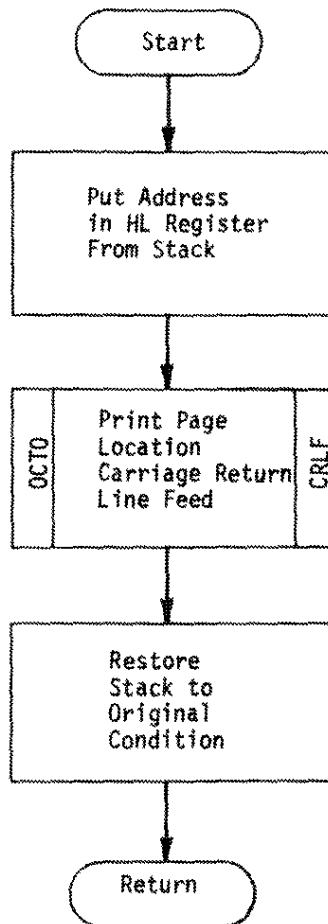


Routine EXMT (Continuation)

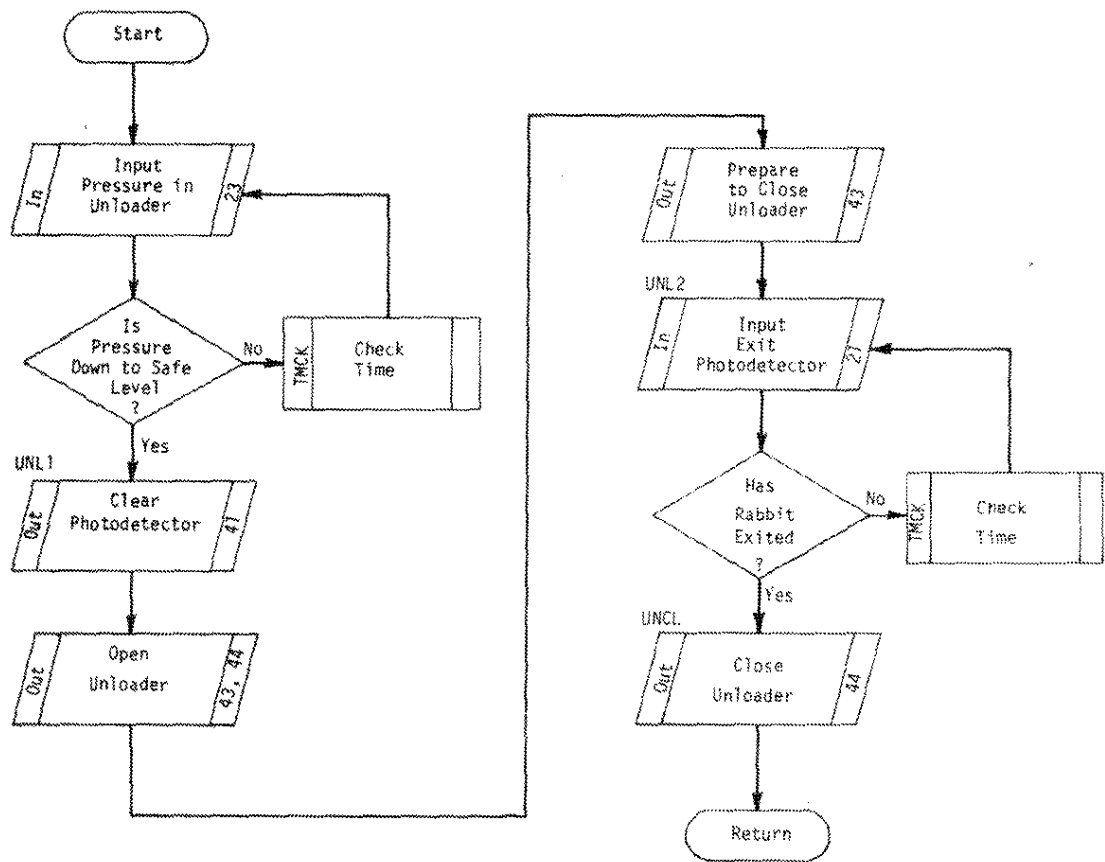


SUBROUTINE SPD

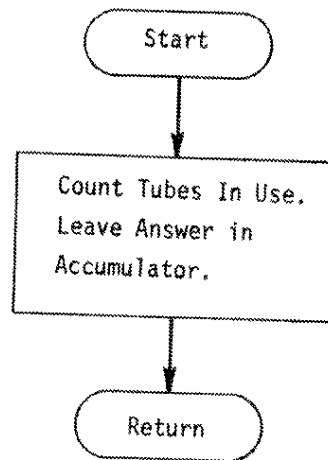
PRINTS ADDRESS TO WHICH ROUTINE CALLING
SPD WILL RETURN



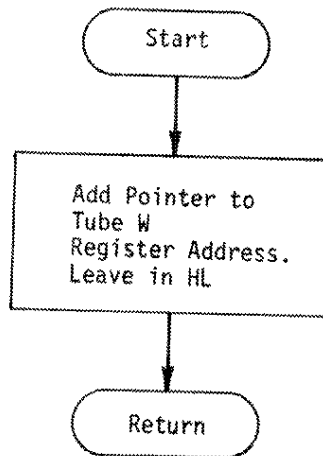
SUBROUTINE UNL
Operate Unloader to Unload Rabbit



SUBROUTINE RICU
COUNTS TOTAL NUMBER OF TUBES IN USE

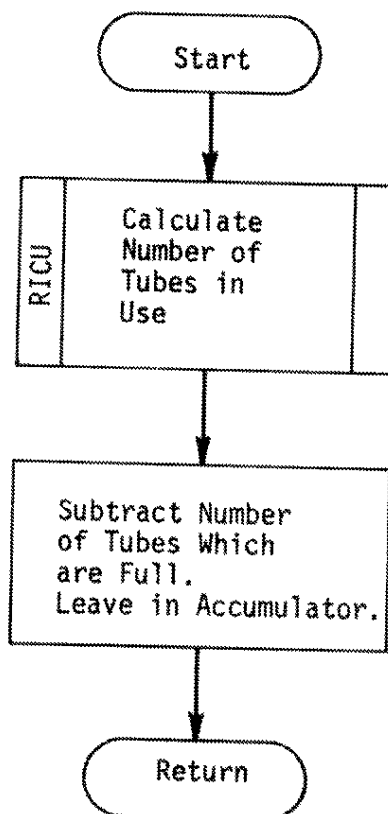


SUBROUTINE RCST
CALCULATES ADDRESS OF TUBE CONTENTS REGISTER



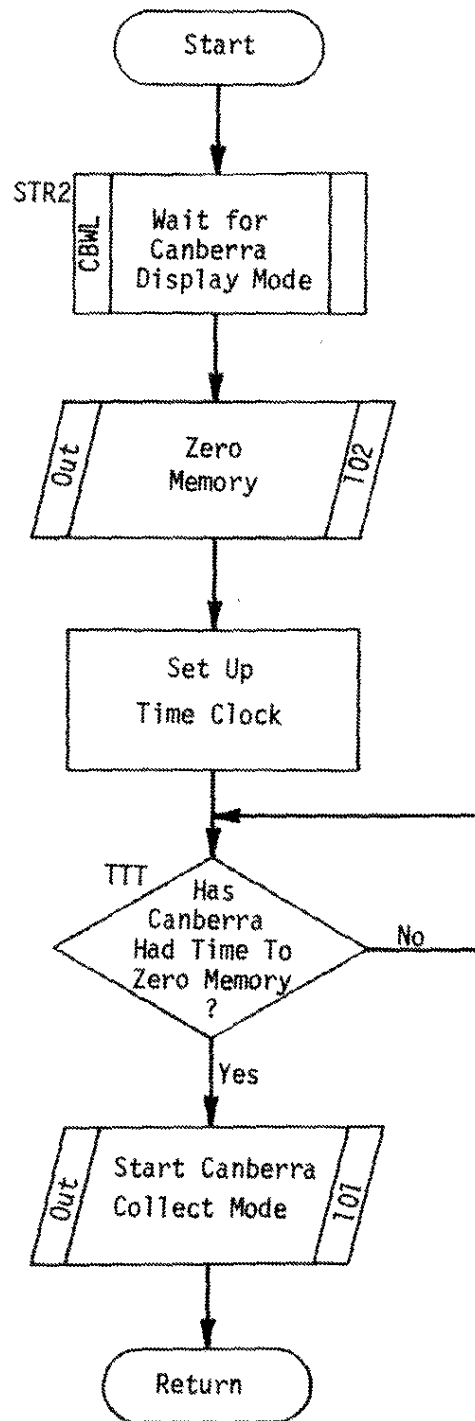
SUBROUTINE RICF

DETERMINES IF ALL TUBES IN USE CURRENTLY
HAVE RABBITS IN THEM



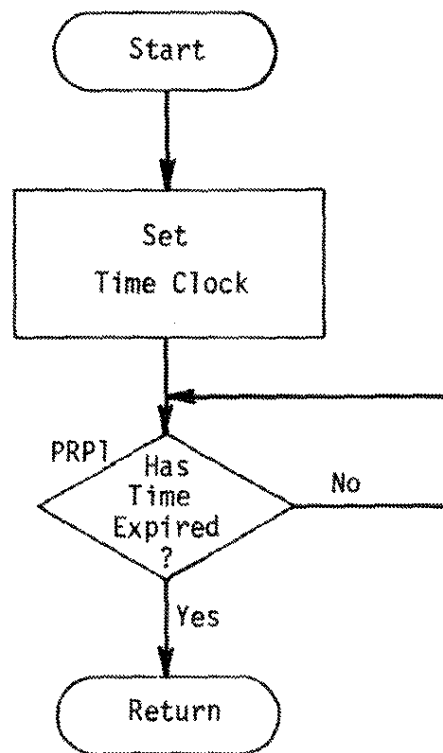
SUBROUTINE STR2

Perform Operations Required to Start Canberra Count at D2

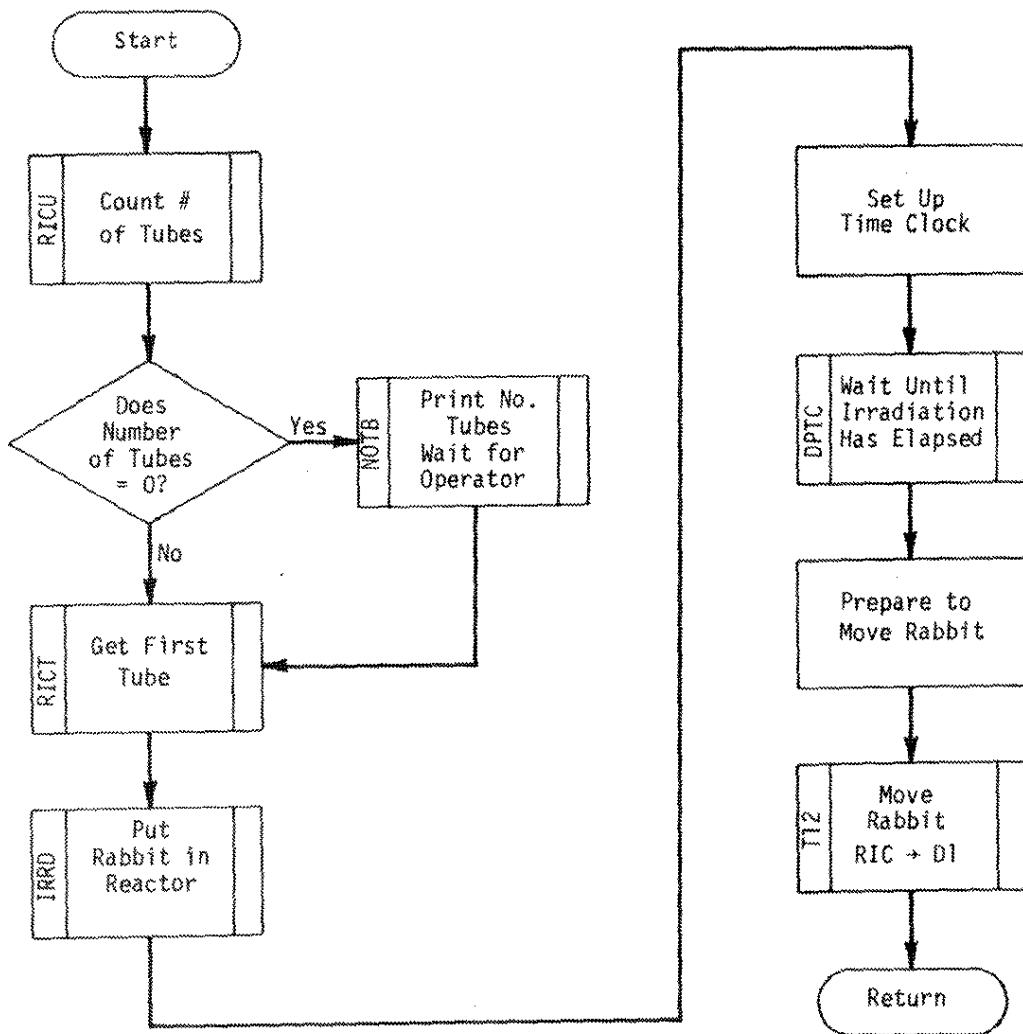


SUBROUTINE PRP

Allow Approximately 100 msec for Rabbit End
to Clear Photodetector Assembly.

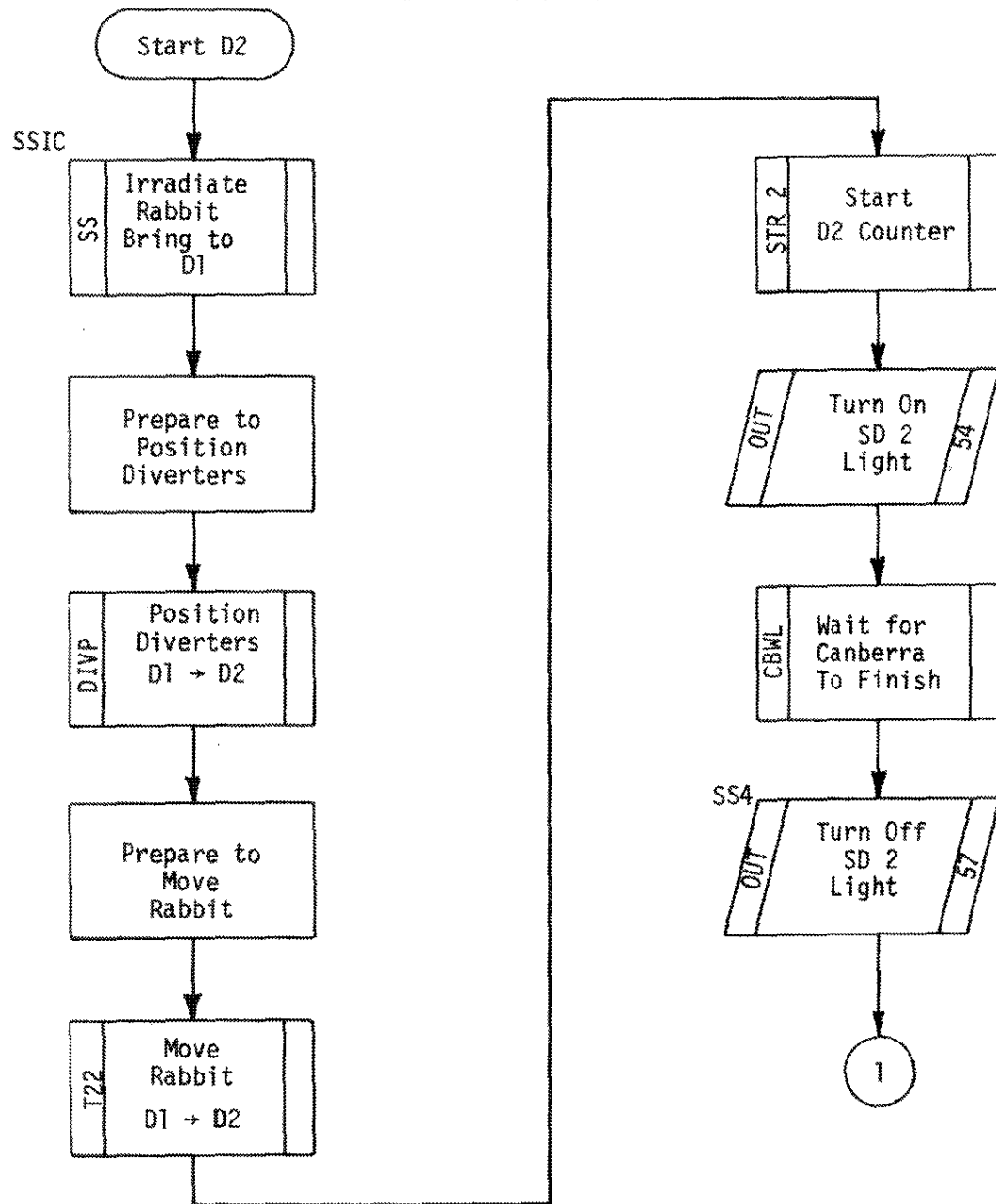


SUBROUTINE SS
Irradiate Rabbit and Move to D1

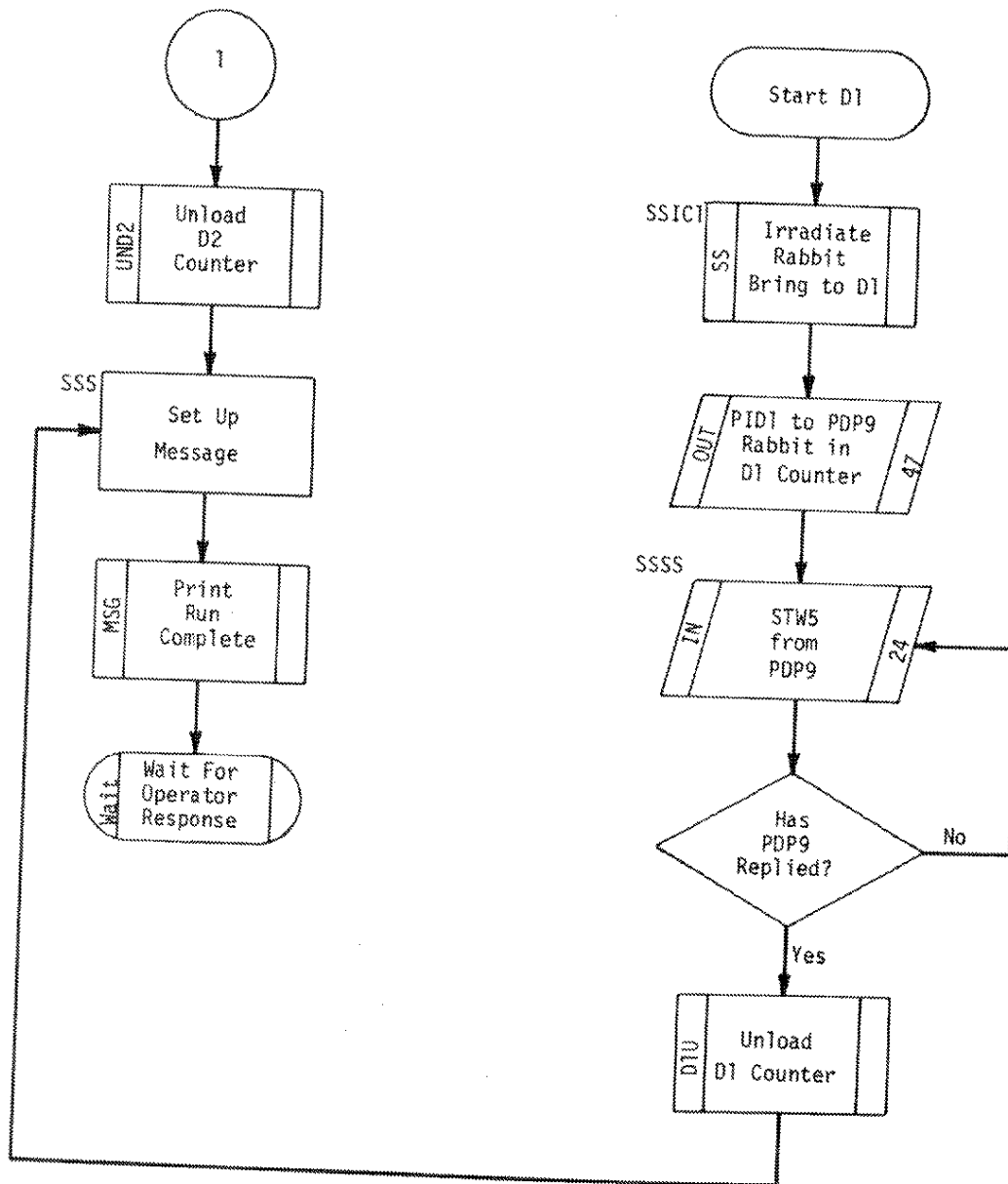


ROUTINE SSIC

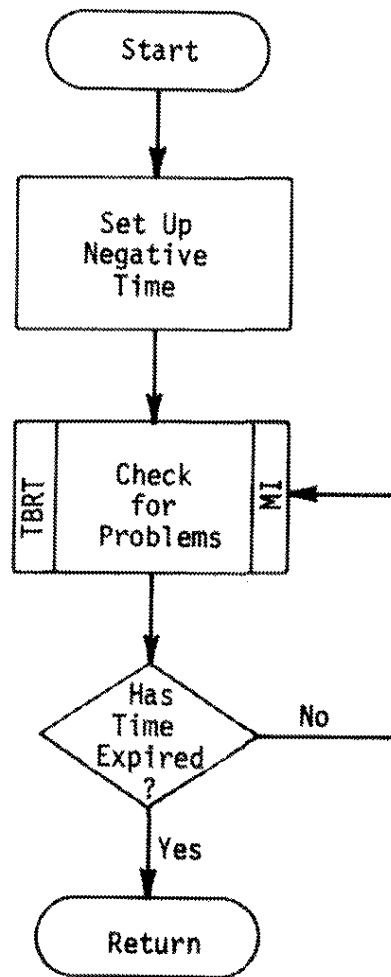
Single Sample Irradiation and Count
Count in D1 or D2



Routine SSIC (Continuation)

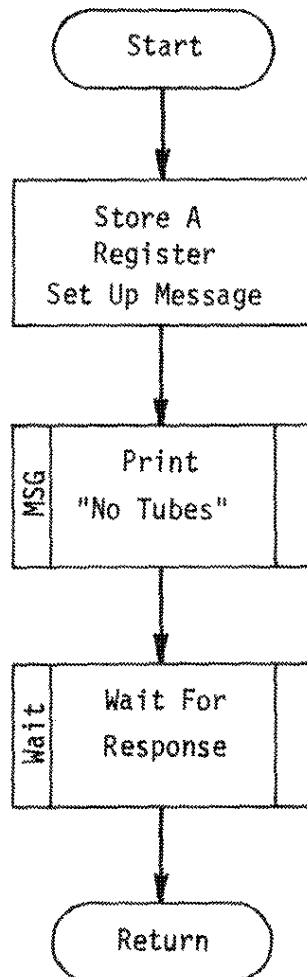


SUBROUTINE DPTC
Double Precision Time Clock
Return When Time Expires



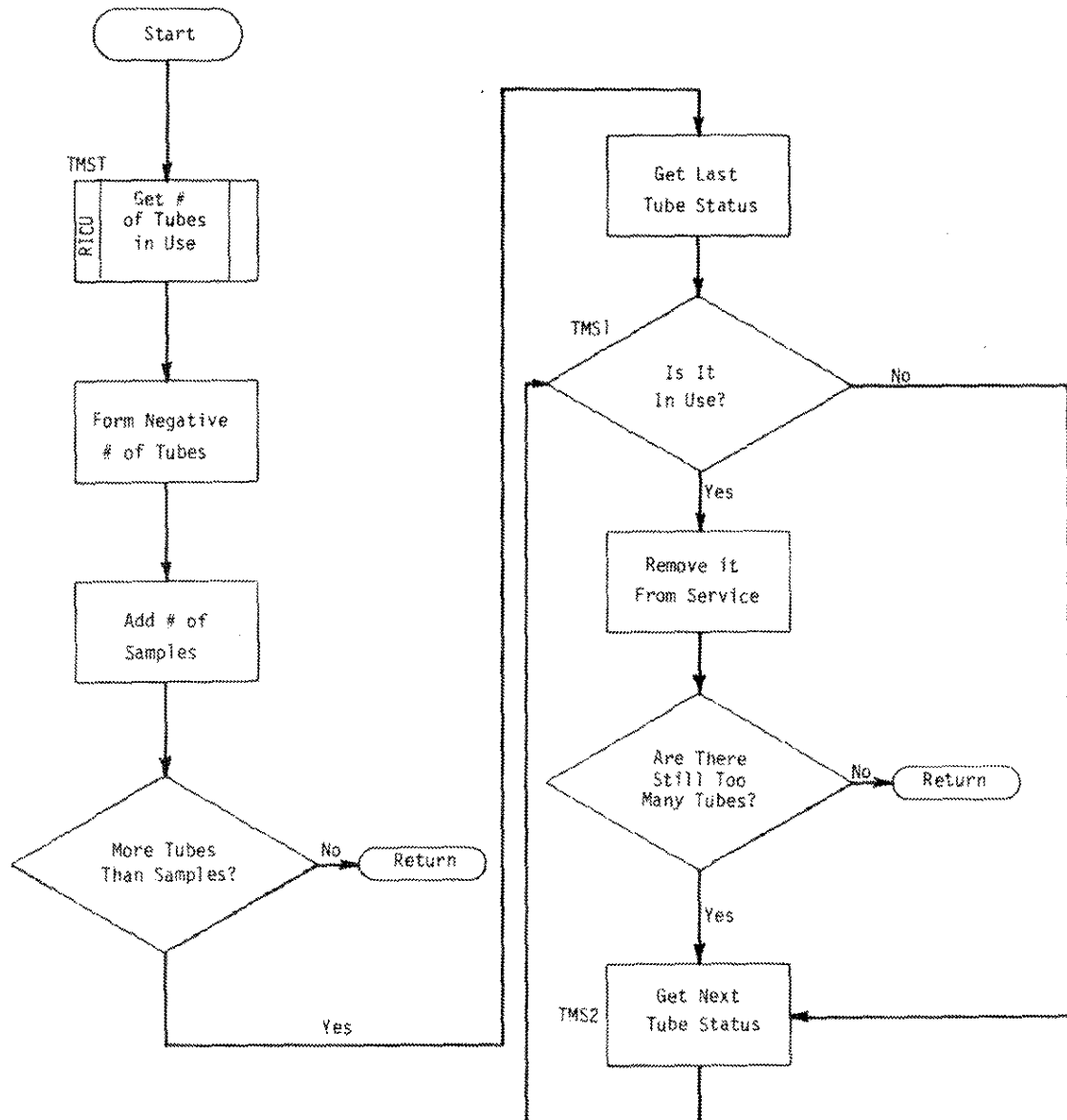
SUBROUTINE NOTB

Notify Operator that Program Was Started but no Tubes
Were Specified. Gives Option to Correct and Continue.



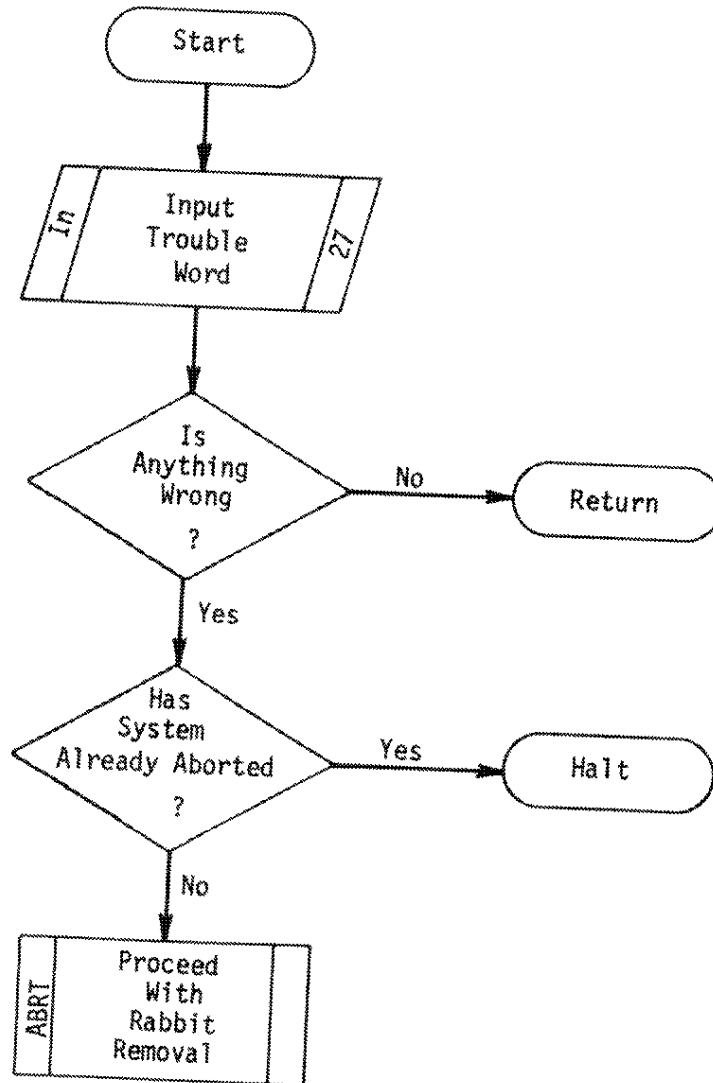
SUBROUTINE TMST

If # of Tubes is More Than # of Samples at Start, Force # of Tubes Equal to # of Samples.



SUBROUTINE TBRT

Monitor Trouble Word to Test for Conditions Warranting an Abort



APPENDIX B

PROGRAM LISTING FOR FIRMWARE IN THE NURE RABBIT CONTROLLER

The firmware program listing for the NURE Rabbit Controller is shown in this appendix. The program was written from Control Logic-M Series assembly language for Intel's 8080 microprocessor.^{2,3}

```

/ NURE RABBIT CONTROLLER RJS 16 JAN 76
000 076 ODT='76 0
021 077 CRLF='77 21
221 077 TTVO='77 231
157 077 OCTO='77 157
/ SYSTEM START UP 16 JAN 76
000 000 *'0 0
00 000 051 370 075 LXI SP '75 370 /INITIALIZE STACK POINTER
00 003 363 DI /DISABLE INTERRUPT
00 004 303 100 000 JMP '0 100 /START UP
010 000 *'0 10
00 010 303 200 000 JMP '0 200 /TIMER
020 000 *'0 20
00 020 303 000 004 JMP '4 0 /MAIN PROGRAM
030 000 *'0 30
00 030 303 000 076 JMP '76 0 /ODT DUMP
040 000 *'0 40
00 040 303 116 076 JMP '76 116 /ODT ?
/
100 000 *'0 100 /START UP
00 100 076 000 LAI 0
00 102 323 043 OUT 43 /NORMAL SOLENOID POSITIONS
00 104 323 044 OUT 44 /ACTIVATE
00 106 323 057 OUT 57 /CLIP P5PR
00 110 323 040 OUT 40 /CLPD1
00 112 323 041 OUT 41 /CLPD2
00 114 323 042 OUT 42 /CLTBL
00 116 323 024 INP 24 /CLSTWS
00 120 076 001 LAI 1
00 122 323 100 OUT 100 /FROSEL 0 1 HZ
00 124 076 375 LAI 375 /MASK INTERRUPTS FOR IRC
00 126 323 012 OUT 12
00 130 373 EI /ENABLE CLOCK
00 131 303 000 004 JMP '4 0
/
200 000 *'0 200 /TIMER
/ TIMER INTERRUPT SUBROUTINE
00 200 365 PSHX PSW /SAVE REGISTERS
00 201 305 PSHX BC
00 202 325 PSHX DE
00 203 345 PSHX HL
00 204 052 044 075 LDHL TIME
00 207 043 INX HL
00 210 042 044 075 STHL TIME
00 213 341 POPX HL /RESTORE REGISTERS
00 214 321 POPX DE
00 215 301 POPX BC
00 216 361 POPX PSW
00 217 373 EI
00 220 311 RET
/
/
/
300 000 *'0 300 /TTVI
00 300 315 317 000 ITVI,CAL REDT
00 303 062 056 075 STA NLI
00 306 315 231 077 CAL TTVO
00 311 072 056 075 LDA NLI

```

```

00 314 346 177      NDI 177
00 316 311          RET
00 317 315 250 070 REDT,CAL TBRT  /TROUBLE?
00 322 333 001      INP 1
00 324 037          RAR
00 325 323 103      OUT 103 /WAIT LIGHT
00 327 322 317 000 JFC REDT
00 332 257          XR A
00 333 323 011      OUT 11
00 335 333 000      INP 0
00 337 311          RET
000 004            * 4 0
/
MAIN PROGRAM      16 JAN 76
04 000 036 000      LLI 0
04 002 046 070      LHI 70
04 004 315 247 005 CAL MSG /TITLE
04 007 315 265 005 CAL WAIT      /WAIT FOR COMMAND
/
04 012 315 357 015 GO,CAL RICU    /CHECK FOR TUBES
04 015 376 000      CPI 0
04 017 314 264 016 CTZ NOTB      /NO TUBES
04 022 315 051 013 CAL RIDY      /FIND TUBE
04 025 052 014 075 GO1,LDHL SPL   /LOAD # SAMPLES
04 030 174          LA H
04 031 376 000      CPI 0 /CHECK FOR RABBITS GONE
04 033 302 044 004 JFZ DOR
04 036 175          LA L
04 037 376 000      CPI 0
04 041 312 175 004 JTZ RGN / RABBITS DONE
/
DEDUCT ONE RABBIT
04 044 026 377      DOR,LDI 377 /MINUS ONE
04 046 036 377      LEI 377
04 050 031          DADX DE
04 051 042 014 075 STAL SPL
/
04 054 323 052      GRXT,OUT 52 /PIF TO POP 9 WANT TO LOAD
/
04 056 315 016 013 GRX1,CAL MI /OPERATOR?
04 061 315 250 070 CAL TBRT /TROUBLE?
04 064 333 024      INP 24 /INPUT STWS FROM POP9
04 066 346 017      NDI 17
04 070 376 000      CPI 0
04 072 312 056 004 JTZ GRX1
04 075 376 001      CPI 1 /ST1 CONTINUE
04 077 312 120 004 JTZ GRX2
04 102 376 002      CPI 2 /ST2 SET SAMPLES TO 0
04 104 312 112 004 JTZ GRX3
04 107 315 265 005 CAL WAIT /ST3,ST4 - ERROR
/
04 112 041 000 000 GRX3,LXI HL 0 0 /SET TO 0
04 115 042 014 075 STAL SPL /STORE SAMPLES
/
04 120 315 266 010 GRX2,CAL RGA /CALL REGIME A
04 123 315 020 011 CAL RGB /REGIME B
04 126 315 232 011 CAL IRGC /INITIATE REGIME C
04 131 315 375 015 CAL RICE /R10 FULL
04 134 376 000      CPI 0
04 136 302 012 004 JFZ GO /NOT FULL
04 141 323 052      OUT 52 /SEND PIF TO POP9

```


04	143	072	037	075	D2.LDA D2ST	/IS D2 FULL
04	146	376	000		CPI 0	
04	150	312	164	004	JT2 TC	/EMPTY
/						
04	153	315	325	004	CAL CBWL	/WAIT FOR CANBERRA DISPLAY MODE
04	156	315	262	011	CAL UND2	/FULL, UNLOAD
04	161	315	030	007	CAL TM5	/5 SEC
04	164	315	051	013	TC, CAL RICT	/ FIND NEXT TUBE
04	167	315	334	011	CAL TRGC	/ TERMINATE REGIME C
04	172	303	025	004	JMP G01	
/						
/ RABBITS DONE						
04	175	072	032	075	RGN.LDA RICH	
04	200	376	000		CPI 0	
04	202	302	270	004	JF2 ABD2	/FULL
04	205	072	033	075	LDA RICK	
04	210	376	000		CPI 0	
04	212	302	270	004	JF2 ABD2	/
04	215	072	034	075	LDA RICV	
04	220	376	000		CPI 0	
04	222	302	270	004	JF2 ABD2	/
04	225	072	035	075	LDA RICZ	
04	230	376	000		CPI 0	
04	232	302	270	004	JF2 ABD2	/
04	235	072	037	075	LDA D2ST	/IS D2 FULL
04	240	376	000		CPI 0	
04	242	312	253	004	JT2 DONE	/EMPTY
04	245	315	325	004	CAL CBWL	/WAIT FOR CANBERRA DISPLAY MODE
04	250	315	262	011	CAL UND2	/FULL, UNLOAD
/ PROGRAM COMPLETE						
04	253	056	062		DONE, LLI 62	
04	255	046	070		LHI 70	
04	257	315	247	005	CAL MSG	/NOTIFY COMPLETE
04	262	315	265	005	CAL WAIT	/WAIT FOR INSTRUCTIONS
04	265	303	265	005	JMP WAIT	
/						
04	270	076	001		ABD2, LAT 1	/ TIME OUT FOR ABD2 TIME
04	272	323	100		OUT 100	/FROSEL RTC 0.1 HZ
04	274	076	000		LAT 0	
04	276	062	044	075	STA TIME	/ ZERO ABD2 TIMER
04	301	056	022		LCI CIRT	/SET UP C FINAL TIME
04	303	046	075		LHI CIRT	
/						
04	305	315	250	070	AB, CAL TBRT	/TROUBLE?
04	310	315	010	013	CAL MI	/OPERATOR?
04	313	072	044	075	LDA TIME	
04	316	226			SUI M	
04	317	372	305	004	JTS AB	
/						
04	322	303	143	004	JMP D2	
/						
/ CANBERRA STATUS 10 SEPT 75						
04	325	315	016	013	CBWL, CAL MI	
04	330	315	250	070	CAL TBRT	
04	332	333	024		INF 24	/SENSE CANBERRA MODE
04	335	246	060		NDI 60	
04	337	376	000		CPI 60	/DISPLAY MODE
04	341	302	325	004	JF2 CBWL	
04	344	311			RET	

```

/
/
/ SUBROUTINE BCD RJS      8 JULY 75
/ BCD TO BINARY CONVERSION
/
04 345 016 373 BCD LCI 373/INITIALIZE -5
04 347 046 000 LHI 0
04 351 056 000 LLI 0
04 353 026 000 LDI 0
04 355 036 000 LET 0
04 357 042 010 075 STHL DEC
04 362 042 012 075 STHL BIN
04 365 315 300 000 BCD1, CAL TTYI
04 370 376 072 CPI 72 /CHECK FOR DIGIT OR CR
04 372 362 062 005 JFS INVC
04 375 376 015 CPI 15
04 377 312 241 005 JNZ LNFD
05 002 326 060 SUI 60
05 004 372 062 005 JTS INVC
05 007 014 INC /INCREMENT DIGIT COUNTER
05 010 362 062 005 JFS INVC
05 013 107 LB R /SHIFT LEFT 4 PLACES
05 014 175 LA L
05 015 067 SETC
05 016 077 CMC
05 017 027 RAL
05 020 157 LL A
05 021 174 LA H
05 022 027 RAL
05 023 147 LH A
05 024 175 LA L
05 025 067 SETC
05 026 077 CMC
05 027 027 RAL
05 030 157 LL A
05 031 174 LA H
05 032 027 RAL
05 033 147 LH A
05 034 175 LA L
05 035 067 SETC
05 036 077 CMC
05 037 027 RAL
05 040 157 LL A
05 041 174 LA H
05 042 027 RAL
05 043 147 LH A
05 044 175 LA L
05 045 067 SETC
05 046 077 CMC
05 047 027 RAL
05 050 157 LL A
05 051 174 LA H
05 052 027 RAL
05 053 147 LH A
05 054 170 LA B
05 055 265 OR L /ADD NEW DIGIT
05 056 157 LL A
05 057 303 365 004 JMP BCD1 /GET NEXT DIGIT
/ INVALID CHARACTER
05 062 056 031 INVC, LLI 31

```

05 064 046 070	LHI 70	
05 066 315 247 005	CHL MS0	
05 071 303 345 004	JMP BCD	
/ CONVERT TO BINARY		
05 074 042 010 075	CONV, STHL DEC	
05 077 175	LA L	/MASK DIGIT
05 100 346 017	NDI 17	
05 102 137	LE A	/STORE DIGIT IN DE
05 103 026 000	LDI 0	
05 105 171	LA C	
05 106 306 004	ADI 4	
05 110 117	LC A	
05 111 006 000	LBI 0	
05 113 075 000	LAI 0	
/		
05 115 376 000	MA, CPI 0	
05 117 312 140 005	JTZ ADIT	/GO TO ADD #
/ MULTIPLY BY 10		
05 122 046 000	M10, LHI 0	
05 124 056 000	LLI 0	
05 126 031	DADX DE	/#1
05 127 051	DADX HL	/#2
05 130 051	DADX HL	/#4
05 131 031	DADX DE	/#5
05 132 051	DADX HL	/#10
05 133 353	DE<HL	/SWAP
05 134 075	DCA	
05 135 303 115 005	JMP MA	
/ ADD BINARY		
05 140 052 012 075	ADIT, LDHL BIN	
05 143 031	DADX DE	
05 144 042 012 075	STHL BIN	
05 147 170	LA B	/LAST DIGIT?
05 150 221	SU C	
05 151 310	RTZ	
05 152 052 010 075	LDHL DEC	/LOAD DECIMAL
05 155 174	LA H	/SHIFT RIGHT 4 PLACES
05 156 067	SETC	
05 157 077	CMC	
05 160 037	RAR	
05 161 147	LH A	
05 162 175	LA L	
05 163 037	RAR	
05 164 157	LL A	/
05 165 174	LA H	
05 166 067	SETC	
05 167 077	CMC	
05 170 037	RAR	
05 171 147	LH A	
05 172 175	LA L	
05 173 037	RAR	
05 174 157	LL A	/
05 175 174	LA H	
05 176 067	SETC	
05 177 077	CMC	
05 200 037	RAR	
05 201 147	LH A	
05 202 175	LA L	
05 203 037	RAR	
05 204 157	LL A	/

05 205 174	LA H
05 206 067	SETC
05 207 077	CMC
05 210 037	RAR
05 211 147	LH A
05 212 175	LA L
05 213 037	RAR
05 214 157	LL A
05 215 026 000	LDI 0 /STORE SHIFTED DEC
05 217 018 000	LET 0
05 221 353	DEC>HL
05 222 031	DAD& DE
05 223 042 010 075	STHL DEC
05 226 175	LA L /MASK DIGIT
05 227 346 017	NDI 17
05 231 137	LE A
05 232 026 000	LDI 0
05 234 004	INB
05 235 170	LA B
05 236 303 115 005	JMP MA
/	
05 241 315 021 077	LNFD, CAL CRLF
05 244 303 074 005	JMP CONV
/ MESSAGE ROUTINE	
/ 13 JUNE 75	
/	
05 247 315 021 077	MSG, CAL CRLF
05 252 176	MSG1, LA H
05 253 376 074	CPI 74 /CHECK FOR END OF STRINGC
05 255 310	RTZ / RETURN IF END
05 256 315 231 077	CAL TTYO
05 261 043	INX HL / OBTAIN NEXT CHARACTER
05 262 303 252 005	JMP MSG1
/	
/ SUBROUTINE WAIT 29 OCT 75 R. J. SAND	
05 265 056 050	WAIT, LLI 50
05 267 046 070	LHI 70
05 271 315 247 005	CAL MSG / TYPE WAITING
05 274 315 250 070	CAL TBRT / TEST FOR TROUBLE
05 277 315 224 015	CAL SPD / IDENTIFY CALLING ROUTINE
/	
05 302 315 300 000	CAL TTYI
05 305 376 107	CPI "G" / G, GO
05 307 312 232 006	JTZ GOOD
05 312 376 123	CPI "S" / S, NO. OF SAMPLES
05 314 302 333 005	JFZ W1
05 317 315 345 004	CAL BCD
05 322 052 012 075	LDHL BIN
05 325 042 014 075	STHL SPL
05 330 303 265 005	JMP WAIT
/	
05 333 376 124	W1, CPI "Y" / Y, TIME
05 335 312 245 006	JTZ IRT
/	
05 340 376 127	W2, CPI "W" / W, WHICH TUBES IN USE
05 342 302 354 005	JFZ W3
05 345 056 026	LLI WST
05 347 046 075	LHI "WST"
05 351 303 015 006	JMP ST

05 354 376 130	W3, CPI "X	/ X
05 356 302 370 005	JFZ W4	
05 361 056 027	LLI XST	
05 363 046 075	LHI "XST	
05 365 303 015 006	JMP ST	
/		
05 370 376 131	W4, CPI "Y	/ Y
05 372 302 004 006	JFZ W5	
05 375 056 030	LLI YST	
05 377 046 075	LHI "YST	
06 001 303 015 006	JMP ST	
/		
06 004 376 132	W5, CPI "Z	/ Z
06 006 302 060 006	JFZ W6	
06 011 056 031	LLI ZST	
06 013 046 075	LHI "ZST	
/		
06 015 315 300 000	ST, CAL TTYI	
06 020 376 060	CPI "0 / 0, NOT IN USE	
06 022 302 033 006	JFZ ONE	
06 025 076 000	LAI 0 / MAKE ZERO	
06 027 167	LM "A	
06 030 303 265 005	JMP WAIT	
/		
06 033 376 061	ONE, CPI "1	/ 1, IN USE
06 035 302 046 006	JFZ BDC / BAD CHARACTER	
06 040 076 001	LAI 1 / MAKE ONE	
06 042 167	LM "A	
06 043 303 265 005	JMP WAIT	
/		
06 046 056 031	BDC, LLI 31	
06 050 046 070	LHI 70	
06 052 315 247 005	CAL MSG	
06 055 303 265 005	JMP WAIT	
/		
06 060 376 102	W6, CPI "B	/ B REGIME B CYCLES
06 062 302 101 006	JFZ W7	
06 065 315 345 004	CAL BCD	
06 070 052 012 075	LDHL BIN	
06 073 042 051 075	STAL BCD	
06 076 303 265 005	JMP WAIT	
/		
06 101 376 103	W7, CPI "C	/ C CONTINUE
06 103 310	RTZ	
06 104 376 117	CPI "0 / 0 JUMP TO ODT	
06 106 312 000 076	JTZ ODT	
06 111 376 101	CPI "A / A ABORT	
06 113 312 242 007	JTZ ABRT	
06 116 376 104	CPI "D / SET DETECTORS IN USE	
06 120 312 375 006	JTZ DT1	
06 123 376 105	CPI "E / EXAMINE SYSTEM	
06 125 312 145 006	JTZ EXM	
06 130 376 060	CPI "0	
06 132 312 212 006	JTZ ZERO	
06 135 376 122	CPI "R / JUMP TO REGIME D	
06 137 312 154 013	JTZ RGD	
/ INSERT NEW COMMANDS BEFORE NEXT LINE		
/		
06 142 303 046 006	W8, JMP BDC	/ INVALID CHARACTERS
06 145 315 300 000	EXM, CAL TTYI	

06 150 376 103	CPI "C / EXAMINE COUNTERS
06 152 312 155 014	JT2 EXMC
06 155 376 124	CPI "T / EXAMINE TUBES
06 157 312 361 014	JT2 EXMT
06 162 376 122	CPI "R /EXAMINE IRRADIATION
06 164 312 172 006	JT2 DET
06 167 303 046 006	JMP BDC
/	
06 172 315 300 000	DET.CAL TTYI
06 175 376 061	CPI "1 /COUNT IN D1
06 177 312 213 016	JT2 SSIC1
06 202 376 062	CPI "2 /COUNT IN D2
06 204 312 160 016	JT2 SSIC
06 207 303 046 006	JMP BDC
/	
/ ZERO RAM	
06 212 056 010	ZERO, LLI 10
06 214 046 075	LHI 75
06 216 066 000	Z, LMI 0
06 220 054	INL
06 221 175	LA L
06 222 376 064	CPI 64
06 224 312 265 005	JT2 WAIT
06 227 303 216 006	JMP Z
/	
INITIALIZE R1CP AND GO	
06 232 076 003	G000, LAI 3
06 234 062 036 075	STA R1CP
06 237 315 301 016	CAL TMST /CORRECT FOR MORE TUBES THAN SAMPLES
06 242 303 012 004	JMP GO
/	
06 245 315 300 000	IRT.CAL TTYI /TIME
06 250 376 101	CPI "A /A TIME 255 DECIMAL MAX
06 252 302 271 006	JFZ IRT1
06 255 315 345 004	CAL BCD
06 260 052 012 075	LDHL BIN
06 263 042 016 075	STHL AIRT
06 266 303 265 005	JMP WAIT
/	
06 271 376 102	IRT1, CPI "B /B TIME 255 DECIMAL MAX
06 273 302 312 006	JFZ IRT2
06 276 315 345 004	CAL BCD
06 301 052 012 075	LDHL BIN
06 304 042 020 075	STHL BIRT
06 307 303 265 005	JMP WAIT
/	
06 312 376 103	IRT2, CPI "C /C TIME 255 DECIMAL MAX
06 314 302 333 006	JFZ IRT3
06 317 315 345 004	CAL BCD
06 322 052 012 075	LDHL BIN
06 325 042 022 075	STHL CIRT
06 330 303 265 005	JMP WAIT
/	
06 333 376 123	IRT3, CPI "S /SSIC TIME
06 335 302 354 006	JFZ IRT4
06 340 315 345 004	CAL BCD
06 343 052 012 075	LDHL BIN

07 127 220	SU B	
07 130 310	RTZ	/ BOTH PD OK
	/	
07 131 026 377	LDI 377	/PD PAIR TIME CONSTANT
07 133 333 020	PK11,	INP 20
07 135 220	SU B	
07 136 310	RTZ	/BOTH OK
07 137 025	DCD	
07 140 302 133 007	JF2	PK11
07 143 333 020	INP 20	
07 145 062 060 075	STA PDF1	/STORE FAILURE
07 150 311	RET	
	/	
07 151 315 157 007	TM, CAL TMCK	/ CHECK TIME
07 154 303 120 007	JMP IST1	/ RECHECK STATUS WORD
		SUBROUTINE TIME CHECK
	/	
07 157 056 043	TMCK, LLI TMK	/ LOAD TIME INTERVAL
07 161 046 075	LHI TMK	
07 163 072 044 075	LDA TIME	/ LOAD TIME
07 166 226	SU M	/
07 167 370	RTS	
07 170 056 150	LLI 150	/ NOTIFY TIME OUT
07 172 046 070	LHI 70	
07 174 315 247 005	CAL MSG	
07 177 315 047 007	CAL STDW	
07 202 315 224 015	CAL SPD	
07 205 315 265 005	CAL WHIT	
07 210 311	RET	
		SUBROUTINE DIVERTER POSITION
	/	
07 211 072 055 075	DIVP, LDA STAD	/ LOAD DIVERTER POSITION
07 214 323 043	OUT 43	/ SET DIVERTER POSITION
07 216 323 044	OUT 44	/ ACTIVATE DIVERTER VALVES
07 220 076 000	LAI 0	/ RESET TIMER
07 222 062 044 075	STA TIME	
	/	
07 225 333 025	DVPI, INP 25	/ INPUT PDT1
07 227 107	LB A	/ STORE IN B
07 230 333 022	INP 22	/ INPUT L53
07 232 220	SU B	
07 233 310	RTZ	/ RETURN IF IN POSITION
07 234 315 157 007	CAL TMCK	/ CHECK FOR ELAPSED TIME
07 237 303 225 007	JMP DVPI	
		SUBROUTINE ABORT 8 SEPT 75
	/	
07 242 076 377	ABRT, LAI 377	
07 244 062 047 075	STA ABTF	
07 247 056 110	LLI 110	
07 251 046 070	LAI 70	
07 253 315 247 005	CAL MSG	/ANNOUNCE ABORT
07 256 076 003	LAI 3	/INITIALIZE RICP
07 260 062 036 075	STA RICP	
07 263 315 357 015	CAL RICU	/# TUBES IN USE
07 266 376 000	CPI 0	
07 270 314 264 016	CTZ NOTB	/NO TUBES
07 273 137	LE A	/STORE #
	/	
07 274 315 051 013	AB1, CAL RICT	/CALCULATE UNLOAD ADDRESS
07 277 315 333 015	CAL RCST	/CALCULATE TUBE STATUS ADDRESS


```

07 302 176          LA M
07 303 376 001      CPI 1
07 305 312 324 007  JNZ AB3 /HAS RABBIT
/
07 310 173          AB2,LA E          /LOAD # TUBES
07 311 326 001      SUI 1 /DEDUCT ONE TUBE
07 313 137          LE A /STORE # TUBES
07 314 376 000      CPI 0
07 316 312 265 005  JNZ WAIT          /ALL TUBES CHECKED
07 321 303 274 007  JMP AB1 /NOT FINISHED YET
/
07 324 072 055 075  AB3, LDA STAD     /SET UP UNLOAD ADDRESS
07 327 306 027      ADI 27
07 331 062 055 075  STA STAD
07 334 315 030 007  CAL TMS /5 SEC
07 337 315 211 007  CAL DIVP          /POSITION DIVERTER RIC>DI
07 342 072 055 075  LDA STAD
07 345 074          INH
07 346 062 055 075  STA STAD
07 351 072 272 070  LDA DEL3
07 354 062 046 075  STA DELT          /DELTA T
07 357 315 236 012  CAL T12 /MOVE RABBIT RIC>DI
07 362 303 310 007  JMP AB2
/
/
/

```

SUBROUTINE LOADER SET UP 13 JULY 75

```

07 365 315 250 070  LDR, CAL T0RT /TROUBLE?
07 370 315 016 013  CAL MI /OPERATOR?
07 373 076 001      LAI 1
07 375 323 043      OUT 43 / SET UP LOADER
07 377 323 044      OUT 44 / ACTIVATE LOADER
10 001 076 000      LAI 0
10 003 062 044 075  STA TIME          / ZERO TIMER
/
10 006 333 023      LDR1, INP 23 / INPUT LS4 LIMIT SWITCH LOADER
10 010 346 002      NDI 2
10 012 376 002      CPI 2
10 014 310          RTZ / CONTINUE IF IN POSITION
10 015 315 157 007  CAL TACK / CHECK TIME
10 020 303 006 010  JMP LDR1
/
/
/

```

SUBROUTINE PHOTODETECTOR CHECK 2 16.2 JULY 75

```

10 023 173          PDR2,LA E
10 024 376 000      CPI 0
10 026 302 041 010  JF2 PK23
10 031 076 000      LAI 0
10 033 062 061 075  STA PDF2
10 036 303 046 010  JMP PK24
10 041 076 000      PK23, LAI 0
10 043 062 062 075  STA PDF3
10 046 062 044 075  PK24, STA TIME
10 051 333 026      INP 26 / INPUT TEST WORD PDT2
10 053 107          LB A
/
10 054 333 021      IST2, INP 21 / INPUT STATUS WORD PD2
10 056 346 337      NDI 337 /MASK OUT LOADER BIT 5
10 060 376 000      CPI 0

```

```

10 062 312 125 010 JTZ TM1 / CHECK TIME OUT
10 065 220 SU B
10 066 310 RTZ / BOTH PD OK
10 067 026 377 LDI 377 / PD PHIR TIME CONSTANT
/
10 071 333 021 PK21, INP 21
10 073 346 337 NDI 337 / MASK OUT LOADER BIT 5
10 075 220 SU B
10 076 310 RTZ / BOTH OK
10 077 025 DCD
10 100 302 071 010 JFZ PK21
10 103 173 LA E
10 104 376 000 CPI 0
10 106 302 117 010 JFZ PK22
10 111 333 021 INP 21
10 113 062 061 075 STA PDF2 / STORE FIRST FAILURE
10 116 311 RET
/
10 117 333 021 PK22, INP 21
10 121 062 062 075 STA PDF3 / STORE SECOND FAILURE
10 124 311 RET
/
10 125 315 157 007 TM1, CAL TMCK / CHECK TIME
10 130 303 054 010 JMP IST2 / RECHECK STATUS WORD
/
/ SUBROUTINE IRRD 14 AUGUST 75
/
10 133 323 041 IRRD, OUT 41 / CLPD2
10 135 333 021 INP 21 / LOAD PD2
10 137 346 040 NDI 40 / PD 18 BIT 5
10 141 376 040 CPI 40
10 143 312 160 010 JTZ IRD1
10 146 056 170 LLI 170 / SET UP EMPTY MESSAGE
10 150 046 070 LHI 70
10 152 315 247 005 CAL MSG
10 155 315 265 005 CAL WAIT
/
10 160 076 003 IRD1, LAI 3 / SET UP L->D1
10 162 062 055 075 STA STAD
10 165 315 030 007 CAL TM5 / 5 SEC
10 170 315 211 007 CAL DIVP / POSITION DIVERTERS
10 173 315 030 007 CAL TM5 / 5 SEC
10 176 315 365 007 CAL LDR / LOAD LOADER
10 201 072 055 075 LDA STAD
10 204 074 INA
10 205 062 055 075 STA STAD / SET UP PLA ADDRESS
10 210 072 270 070 LDA DEL1
10 213 062 046 075 STA DELT / SETUP DELTA T
10 216 315 036 012 CAL T22 / MOVE RABBIT L -> D1
10 221 315 250 070 CAL TBRT / TROUBLE?
10 224 315 016 013 CAL RI / OPERATOR?
10 227 072 050 075 LDA PLAR / FIND TUBE
10 232 306 007 ADI 7
10 234 062 055 075 STA STAD / POSITION DIVERTERS D1 -> RIC
10 237 315 030 007 CAL TM5 / 5 SEC
10 242 315 211 007 CAL DIVP
10 245 072 055 075 LDA STAD
10 250 074 INA
10 251 062 055 075 STA STAD / SET UP ADDRESS

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10 254 072 271 070 LDA DEL2
10 257 062 046 075 STA DELT / DELTA Y
10 262 315 326 012 CAL T21 / MOVE RABBIT D1 -> RIC
10 265 311 RET
/
/
/ SUBROUTINE REGIME A 12 SEPT 75
/
10 266 315 133 010 RGA, CAL IRRD /PUT RABBIT IN REACTOR
10 271 056 016 LLI AIRT /SET UP TIME
10 273 046 075 LHI 'AIRT
10 275 075 004 LAI 4 /10 HZ
10 277 323 100 OUT 100 /FROSEL RTC
10 301 076 000 LAI 0
10 303 062 044 075 STA TIME /ZERO TIMER
/
10 306 315 016 013 RGA1, CAL MI /OPERATOR?
10 311 315 250 070 CAL TBRT /TROUBLE?
10 314 072 044 075 LDA TIME
10 317 276 CP M
10 320 372 306 010 JTS RGA1
10 323 072 055 075 LDA STAD
10 326 306 016 ADI 16
10 330 062 055 075 STA STAD /
10 333 072 272 070 LDA DEL3
10 336 062 046 075 STA DELT /
10 341 315 236 012 CAL T12 / MOVE RABBIT RIC -> D1
10 344 323 047 OUT 47 / SET UP PID1 TO FDP9
/
10 346 315 250 070 RGA2, CAL TBRT /TROUBLE?
10 351 315 016 013 CAL MI /OPERATOR?
10 354 333 024 INF 24 / BRING IN WORD STW5
10 356 346 017 NDI 17
10 360 376 000 CPI 0
10 362 312 346 010 JT2 RGA2
10 365 376 001 CPI 1 / RETURN IF ST 1
10 367 310 RT2
10 370 376 002 CPI 2 / REJECT SAMPLE IF ST 2
10 372 312 003 011 JT2 RGA3
10 375 315 265 005 CAL WAIT
11 000 303 265 005 JMP WAIT
/
11 003 056 210 RGA3, LLI 210
11 005 046 070 LHI 70
11 007 315 247 005 CAL MSG / ANNOUNCE HOT SAMPLE
11 012 315 113 014 CAL DIU /UNLOAD RABBIT DISU
11 015 303 025 004 JMP G01
/
/ SUBROUTINE REGIME B 24 SEPT 75
/
11 020 052 051 075 RGB, LDHL BCY / SET UP B CYCLE COUNTER
11 023 042 053 075 STHL BCYM
/
11 026 174 RGBR, LA H
11 027 376 000 CPI 0
11 031 302 053 011 JFZ RGB2 / IF NOT DONE CONTINUE RGB2
11 034 175 LA L
11 035 376 000 CPI 0
11 037 302 053 011 JFZ RGB2

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11 042 323 051      OUT 51 / PIC TO PDP9
/
11 044 315 250 070 CAL TBRT /TROUBLE?
11 047 315 016 013 CAL MI /OPERATOR?
11 052 311          RET
/
11 053 072 055 075 RGB2, LDA STAD
11 056 326 022      SUI 22
11 060 062 055 075 STA STAD          / SET UP PLA ADDRESS
11 063 072 271 070 LDA DEL2
11 066 062 046 075 STA DELT          / SET UP DELTA T
11 071 315 326 012 CAL T21 / MOVE RABBIT DISRIC
11 074 076 000      LAI 0
11 076 062 056 075 STA HLI
/
11 101 056 020      RB30, LLI BIRT /SET UP TIME
11 103 046 075      LHI /BIRT
11 105 076 004      LAI 4 /10 HZ
11 107 323 100      OUT 100 /FRQSEL RTC
11 111 076 000      LAI 0
11 113 062 044 075 STA TIME          /ZERO TIMER
/
11 116 315 016 013 RGB3, CAL MI      /OPERATOR?
11 121 315 250 070 CAL TBRT          /TROUBLE?
11 124 072 044 075 LDA TIME
11 127 276          CP M
11 130 372 116 011 JFS RGB3
11 133 072 056 075 LDA HLI
11 136 376 000      CPI 0
11 140 302 153 011 JFZ RB31
11 143 076 001      LAI 1 /DO IT TWICE
11 145 062 056 075 STA HLI
11 150 303 101 011 JMP RB30
/
11 153 072 055 075 RB31, LDA STAD
11 156 306 016      ADI 16
11 160 062 055 075 STA STAD
11 163 072 272 070 LDA DEL3
11 166 062 046 075 STA DELT
11 171 315 236 012 CAL T12 / MOVE RABBIT RIC>D1
11 174 323 047      OUT 47 / PID1 TO PDP9
11 176 052 053 075 LDHL BCYW
11 201 053          DCX HL
11 202 042 053 075 STLH BCYW
/
11 205 315 250 070 RGB4, CAL TBRT /TROUBLE?
11 210 315 016 013 CAL MI /OPERATOR?
11 213 333 024      INP 24 / CHECK FOR ST3
11 215 346 017      NDI 17
11 217 376 004      CPI 4
11 221 302 205 011 JFZ RGB4
11 224 052 053 075 LDHL BCYW
11 227 303 026 011 JMP RGBA          / CONTINUE
/
SUBROUTINE INITIATE REGIME C 4 SEPT 1975
/
11 232 072 055 075 IRGC, LDA STAD
11 235 326 022      SUI 22
11 237 062 055 075 STA STAD
11 242 072 271 070 LDA DEL2

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11 245 062 046 075 STA DELT
11 250 315 326 012 CAL T21 / MOVE RABBIT D1->RIC
11 253 315 250 070 CAL TBRT /TROUBLE?
11 256 315 016 013 CAL MI /OPERATOR?
11 261 311 RET

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SUBROUTINE UNLOAD DELT D2 8 SEPT 75

```

11 262 076 053 UNDC. LAI 53 / SET UP DIVERTER POSITION
11 264 062 055 075 STA STAD
11 267 315 030 007 CAL TMS /5 SEC
11 272 315 211 007 CAL DIVP / POSITION DIVERTERS
11 275 072 055 075 LDA STAD
11 300 074 INA
11 301 062 055 075 STA STAD / SET UP PLA ADDRESS
11 304 072 274 070 LDA DEL5
11 307 062 046 075 STA DELT / SET UP DELTA Y
11 312 315 036 012 CAL T22 / MOVE RABBIT TO D1
11 315 315 250 070 CAL TBRT /TROUBLE?
11 320 315 016 013 CAL MI /OPERATOR?
11 323 315 113 014 CAL D1U /D1 TO UNLOAD
11 326 076 000 LAI 0
11 330 062 037 075 STA D2ST / CLEAR D2 STATUS
11 333 311 RET

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SUBROUTINE TERMINATE REGIME C 4 SEPT 75

```

11 334 072 055 075 TRGC. LDA STAD
11 337 306 027 ADI 27
11 341 062 055 075 STA STAD
11 344 315 030 007 CAL TMS /5 SEC
11 347 315 211 007 CAL DIVP / POSITION DIVERTERS RIC->D1
11 352 072 055 075 LDA STAD
11 355 074 INA
11 356 062 055 075 STA STAD
11 361 072 272 070 LDA DEL3
11 364 062 046 075 STA DELT
11 367 315 236 012 CAL T12 / MOVE RABBIT RIC->D1
11 372 076 047 LAI 47
11 374 062 055 075 STA STAD
11 377 315 030 007 CAL TMS /5 SEC
12 002 315 211 007 CAL DIVP / POSITION DIVERTERS D1->D2
12 005 072 055 075 LDA STAD
12 010 074 INA
12 011 062 055 075 STA STAD
12 014 072 273 070 LDA DEL4
12 017 062 046 075 STA DELT
12 022 315 036 012 CAL T22 / MOVE RABBIT TO D2
12 025 315 014 016 CAL STR2 /START D2 COUNTER
12 030 076 001 LAI 1
12 032 062 037 075 STA D2ST / SET D2 STATUS TO FULL
12 035 311 RET

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LOCAL TRANSPORT SUBROUTINE 14 AUGUST 1975

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12 036 072 055 075 T22. LDA STAD
12 041 323 043 OUT 43 / STAD SET UP PLA STARTING ADDRESS
12 043 323 041 OUT 41 / CLEAR PHOTODETECTORS 2

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12 045 315 030 007	CAL TMS /5 SEC	
12 050 323 044	OUT 44 / ACTIVATE VALVES ACTV	
12 052 076 000	LAI 0	
12 054 062 060 075	STA PDF1	
12 057 036 000	LEI 0 /FIRST PDK2	
12 061 315 023 010	CAL PDK2 / VERIFY DEPARTURE	
12 064 315 055 016	CAL PRP /PAUSE FOR RABBIT PASSAGE	
12 067 323 041	OUT 41 / CLEAR PHOTODETECTORS 2	
12 071 315 030 007	CAL TMS /5 SEC	
12 074 072 055 075	LDA STAD	
12 077 074	INA / INCREMENT ADDRESS	
12 100 062 055 075	STA STAD	
12 103 323 043	OUT 43	
12 105 036 001	LEI 1 /SECOND PDK2	
12 107 315 023 010	CAL PDK2 / VERIFY ARRIVAL	
12 112 315 055 016	CAL PRP /PAUSE FOR RABBIT PASSAGE	
	/	
12 113 315 121 012	CAL TRT /TERMINATE TRANSPORT	
12 120 311	RET	
	/	
	TERMINATE TRANSPORT SUBROUTINES 16.2 JULY 75	
12 121 323 044	TRT, OUT 44 / ACTIVATE VALVES	
12 123 076 010	LAI 10 /100 HZ	
12 125 323 100	OUT 100 /FRQSEL RTC	
12 127 076 000	LAI 0	
12 131 062 044 075	STA TIME / RESET TIMER	
12 134 056 046	LLI DELT / LOAD DELTA T	
12 136 046 075	LAI 'DELT	
	/	
12 140 072 044 075	TME, LDA TIME / LOAD TIME	
12 143 226	SU M	
12 144 372 140 012	JTS TME / TEST LOOP	
12 147 072 055 075	LDA STAD	
12 152 074	INA / INCREMENT PLA ADDRESS	
12 153 062 055 075	STA STAD	
12 156 323 043	OUT 43 / SET UP NORMAL VALVE POSITION	
12 160 323 044	OUT 44 / ACTIVATE VALVES	
12 162 072 060 075	LDA PDF1 /PD FAILURE REGISTER	
12 165 376 000	CPI 0	
12 167 302 210 012	JFZ TRT1 /DUMP IF FAILURE	
12 172 072 061 075	LDA PDF2	
12 175 376 000	CPI 0	
12 177 302 210 012	JFZ TRT1	
12 202 072 062 075	LDA PDF3	
12 205 376 000	CPI 0	
12 207 310	RTZ	
	/	
12 210 072 060 075	TRT1, LDA PDF1	
12 213 315 157 077	CAL OCT0 /DUMP PD1	
12 216 072 061 075	LDA PDF2	
12 221 315 157 077	CAL OCT0 /DUMP PD2 FIRST	
12 224 072 062 075	LDA PDF3	
12 227 315 157 077	CAL OCT0 /DUMP PD2 SECOND	
12 232 315 021 077	CAL CRLF	
12 235 311	RET	
	/	
	/CROSSCOUNTRY TRANSPORT SUBROUTINE 4 SEPT 75	

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12 236 072 055 075 T12, LDA STAD
12 241 323 043 OUT 43 / STAD SET UP PLA STARTING ADDRESS
12 243 323 040 OUT 40 / CLEAR PHOTODETECTORS 1
12 245 315 030 007 CAL TH5 /5 SEC
12 250 323 044 OUT 44 / ACTIVATE VALVES ACTV
12 252 315 105 007 CAL PDK1 / VERIFY DEPARTURE
12 255 323 050 OUT 50 / PIRIC TO POP9
12 257 315 333 015 CAL RCST /CLEAR TUBE STATUS
12 262 066 000 LMI 0
12 264 315 055 016 CAL PRP /PAUSE FOR RABBIT PASSAGE
12 267 323 041 OUT 41 / CLEAR PHOTODETECTORS 2
12 271 315 030 007 CAL TH5 /5 SEC
12 274 072 055 075 LDA STAD
12 277 074 INA / INCREMENT ADDRESS
12 300 062 055 075 STA STAD
12 303 323 043 OUT 43
12 305 076 000 LAI 0
12 307 062 062 075 STA PDF3
12 312 036 000 LEI 0
12 314 315 023 010 CAL PDK2 / VERIFY ARRIVAL
12 317 315 055 016 CAL PRP /PAUSE FOR RABBIT PASSAGE
12 322 315 121 012 CAL TRT /TERMINATE TRANSPORT
12 325 311 RET
/
/CROSS COUNTRY TRANSPORT SUBROUTINE 4 SEPT 75
/

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```

12 326 072 055 075 T21, LDA STAD
12 331 323 043 OUT 43 / STAD SET UP PLA STARTING ADDRESS
12 333 323 041 OUT 41 / CLEAR PHOTODETECTORS 2
12 335 315 030 007 CAL TH5 /5 SEC
12 340 323 044 OUT 44 / ACTIVATE VALVES ACTV
12 342 076 000 LAI 0
12 344 062 062 075 STA PDF3
12 347 036 000 LEI 0
12 351 315 023 010 CAL PDK2 / VERIFY DEPARTURE
12 354 315 055 016 CAL PRP /PAUSE FOR RABBIT PASSAGE
12 357 323 040 OUT 40 / CLEAR PHOTODETECTORS 2
12 361 315 030 007 CAL TH5 /5 SEC
12 364 072 055 075 LDA STAD
12 367 074 INA / INCREMENT ADDRESS
12 370 062 055 075 STA STAD
12 373 323 043 OUT 43
12 375 315 105 007 CAL PDK1 / VERIFY ARRIVAL
13 000 323 050 OUT 50 /PIRIC TO POP9
13 002 315 333 015 CAL RCST /SET TUBE STATUS
13 005 066 001 LMI 1
13 007 315 055 016 CAL PRP /PAUSE FOR RABBIT PASSAGE
13 012 315 121 012 CAL TRT /TERMINATE TRANSPORT
13 015 311 RET
/
/
/
/

```

MANUAL INTERRUPT SUBROUTINE 19 JUNE 75

```

13 016 333 000 MI, INP 0 /INPUT ANYTHING FROM TTY
13 020 376 311 CPI 311 /CHECK FOR I INTERRUPT
13 022 312 026 013 JNZ MI1
13 025 311 RET
13 026 341 MI1, POPX HL
13 027 174 LA H

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13	211	376	040	CPI 40	
13	213	312	230	013	JT2 RGD2
13	216	056	170		LLI 170
13	220	046	070		LAI 70
13	222	315	247	005	CAL MSG /EMPTY MESSAGE
13	225	315	265	005	CAL WAIT
13	230	076	003		RGD2, LAI 3 /SET UP LSDI
13	232	062	055	075	STA STAD
13	235	315	030	007	CAL TMS /5 SEC
13	240	315	211	007	CAL DIVP /POSITION DIVERTER
13	243	315	030	007	CAL TMS /5 SEC
13	246	315	365	007	CAL LDR /LOAD LOADER
13	251	072	055	075	LDA STAD
13	254	074			INA
13	255	062	055	075	STA STAD /SET UP PLA ADDRESS
13	260	072	270	070	LDA DEL1
13	263	062	046	075	STA DELT /SET UP DELTA T
13	266	315	036	012	CAL T22 /MOVE RABBIT L>D1
13	271	076	001		LAI 1
13	273	062	040	075	STA D1ST /SET D1 TO FULL
13	276	323	047		OUT 47 /PI01 TO PDP 9
13	300	315	016	013	RGD5, CAL MI /OPERATOR?
13	303	333	024		INP 24 /INPUT STWS FROM PDP9
13	305	346	017		NDI 17
13	307	376	000		CPI 0
13	311	312	300	013	JT2 RGD5
13	314	376	002		CPI 2 /ST2 REJECT REMOVE RABBIT
13	316	312	336	013	JT2 RGD6
13	321	376	001		CPI 1 /ST1 COUNT THIS RABBIT
13	323	312	376	013	JT2 RGD8
13	326	376	004		CPI 4 /ST3 COUNT COMPLETE REMOVE RABBITS
13	330	312	055	014	JT2 RGD9
13	333	315	265	005	CAL WAIT
13	336	315	113	014	RGD6, CAL D1U /D1>UNLOAD
13	341	303	154	013	JMP RGD
13	344	072	037	075	RGD7, LDA D2ST /CHECK IF D2 FULL
13	347	376	000		CPI 0
13	351	312	364	013	JT2 RGD0 /D2 NOT FULL
13	354	315	325	004	CAL CBWL /WAIT FOR CANBERRA DISPLAY MODE
13	357	323	057		OUT 57 /TURN OFF SD2 LIGHT
13	361	315	262	011	CAL UND2 /UNLOAD D2
13	364	056	062		RGD0, LLI 62 /RUN COMPLETE
13	366	046	070		LAI 70
13	370	315	247	005	CAL MSG
13	373	303	265	005	JMP WAIT
13	376	072	042	075	RGD8, LDA D20 /IS D2 IN OPERATION
14	001	376	000		CPI 0
14	003	312	300	013	JT2 RGD5
14	006	072	037	075	LDA D2ST /IS D2 FULL
14	011	376	001		CPI 1
14	013	312	300	013	JT2 RGD5 /NO
14	016	315	306	014	CAL LSD2
14	021	323	052		OUT 52 /PIF TO PDP9
14	023	072	041	075	LDA D10 /IS D1 IN OPERATION
14	026	376	000		CPI 0
14	030	312	300	013	JT2 RGD5 /NO

14 033 052 014 075	LDHL SPL	/ANY MORE RABBITS
14 036 174	LA H	
14 037 376 000	CPI 0	
14 041 302 173 013	JF2 RGD1	/MORE
14 044 175	LA L	
14 045 376 000	CPI 0	
14 047 312 300 013	JT2 RGD5	/NO MORE
14 052 303 173 013	JMP RGD1	/MORE
/		
14 055 072 040 075	RGD9, LDA D1ST	/IS D1 FULL
14 060 376 000	CPI 0	
14 062 312 070 014	JT2 RGDZ	/NOT FULL
14 065 315 113 014	CAL D1U	/FULL UNLOAD D1
/		
14 070 072 037 075	RGDZ, LDA D2ST	/IS D2 FULL
14 073 376 000	CPI 0	
14 075 312 154 013	JT2 RGD	/NOT FULL
14 100 315 325 004	CAL CBWL	/WAIT FOR CANBERRA DISPLAY MODE
14 103 323 057	OUT 57	/TURN OFF SD2 LIGHT
14 105 315 262 011	CAL UND2	/UNLOAD D2
14 110 303 154 013	JMP RGD	
/		
/		
/ D1>UNLOAD 27 AUGUST 75		
/		
14 113 076 057	D1U, LAI 57	/SET UP D1 > U
14 115 062 055 075	STA STAD	
14 120 315 030 007	CAL TM5 /5 SEC	
14 123 315 211 007	CAL DIVP	/DIVERTERS
14 126 072 055 075	LDA STAD	
14 131 074	INA	
14 132 062 055 075	STA STAD	
14 135 072 275 070	LDA DEL6	
14 140 062 046 075	STA DELT	
14 143 315 036 012	CAL T22	/MOVE RABBIT D1>U
14 146 315 030 007	CAL TM5 /5 SEC	
14 151 315 254 015	CAL UNL	
14 154 311	RET	
/		
/		
/ ROUTINE EXAMINE COUNTERS 29 OCT 75		
14 155 323 041	EXMC, OUT 41	/CLPD2
14 157 333 021	INP 21	/LOAD PD2
14 161 346 040	NDI 40	/PD 18 BIT 5
14 163 376 040	CPI 40	
14 165 312 202 014	JT2 EXMI	
14 170 056 170	LLI 170	/EMPTY MESSAGE
14 172 046 070	LAI 70	
14 174 315 247 005	CAL MSG	
14 177 315 265 005	CAL WAIT	
/		
14 202 076 003	EXMI, LAI 3	/SET UP L>D1
14 204 062 055 075	STA STAD	
14 207 315 030 007	CAL TM5 /5 SEC	
14 212 315 211 007	CAL DIVP	/POSITION DIVERTERS
14 215 315 030 007	CAL TM5 /5 SEC	
14 220 315 365 007	CAL LDR	/LOAD LOADER
14 223 072 055 075	LDA STAD	
14 226 074	INA	
14 227 062 055 075	STA STAD	/SET UP PLA ADDRESS

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14 232 072 270 070 LDA DEL1
14 235 062 046 075 STA DELT /SET UP DELTA T
14 240 315 036 012 CAL T22 /MOVE RABBIT L>D1
14 243 323 047 OUT 47 /PDI TO PDP9
/
14 245 333 024 EXM2, INP 24 /STM5 FROM PDP9
14 247 346 017 NDI 17
14 251 376 000 CPI 0
14 253 312 245 014 JT2 EXM2
14 256 315 306 014 CAL LSD2 /LOAD AND START D2
/
14 261 315 325 004 CAL CBWL /WAIT FOR CANBERRA DISPLAY MODE
14 264 323 057 OUT 57 /TURN OFF SD2 LIGHT
14 266 315 262 011 CAL UND2 /UNLOAD D2
14 271 056 062 LLI 62
14 273 046 070 LHI 70
14 275 315 247 005 CAL MSG /RUN COMPLETE
14 300 315 265 005 CAL WAIT
14 303 303 265 005 JMP WAIT
/
/LOAD AND START D2 30 OCT 75
/
/
14 306 076 000 LSD2, LAI 0
14 310 062 040 075 STA D1ST /SET D1 TO EMPTY
14 313 076 047 LAI 47
14 315 062 055 075 STA STAD /POSITION DIVERTER D1>D2
14 320 315 030 007 CAL TMS 75 SEC
14 323 315 211 007 CAL DIVP
14 326 072 055 075 LDA STAD
14 331 074 INA
14 332 062 055 075 STA STAD
14 335 072 273 070 LDA DEL4
14 340 062 046 075 STA DELT
14 343 315 036 012 CAL T22 /MOVE RABBIT D1>D2
14 346 315 014 016 CAL STR2 /START D2 COUNTERS
14 351 323 054 OUT 54 /TURN ON SD2 LIGHT
14 353 076 001 LAI 1
14 355 062 037 075 STA D2ST /SET D2 TO FULL
14 360 311 RET
/
/
/ ROUTINE EXAMINE TUBES 29 OCT 75 RJ5
/
14 361 076 003 EXMT, LAI 3
14 363 062 036 075 STA R1CP /INITIALIZE POINTER
14 366 323 041 OUT 41 /CLPD2
14 370 333 021 INP 21 /LOAD PD2
14 372 346 040 NDI 40 /PD 10 BIT 5
14 374 376 040 CPI 40
14 376 312 013 015 JT2 XMY1
15 001 056 170 LLI 170
15 003 046 070 LHI 70
15 005 315 247 005 CAL MSG /EMPTY MESSAGE
15 010 315 265 005 CAL WAIT
/
15 013 076 003 XMY1, LAI 3 /SET UP L>D1
15 015 062 055 075 STA STAD
15 020 315 030 007 CAL TMS 75 SEC

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15 231 174	LA H	/ROUTINE WOULD HAVE RETURNED
15 232 346 077	NDI 77	
15 234 315 157 077	CAL OCTO	
15 237 175	LA L	
15 240 315 157 077	CAL OCTO	/WRITE PAGE, LOCATION
15 243 345	PSHX HL	
15 244 052 056 075	LDHL HL1	
15 247 345	PSHX HL	
15 250 315 021 077	CAL CRLF	
15 253 311	RET	
/		
/		
/ UNLOADER SUBROUTINE 10 JULY 75		
15 254 333 023	UNL, INP 23	/INPUT PRESSURE IN UNLOADER
15 256 346 004	NDI 4	
15 258 376 004	CPI 4	
15 262 312 273 015	JT2 UNL1	/UNLOAD RABBIT IF PRESSURE IS DOWN
15 265 315 157 007	CAL TMCK	/CHECK FOR ELAPSED TIME
15 270 303 254 015	JMP UNL	
/		
15 273 323 041	UNL1, OUT 41	/CLEAR EXIT PHOTO DETECTOR
15 275 076 063	LAI 63	/SET UP UNLOADER INSTRUCTION
15 277 323 043	OUT 43	
15 301 323 044	OUT 44	/ACTIVATE SOLENOID
15 303 074	INA	
15 304 323 043	OUT 43	/SET UP FOR CLOSING
15 306 315 030 007	CAL TM5	
/		
15 311 333 021	UNL2, INP 21	/INPUT PHOTODETECTOR UNLOADER EXIT
15 313 346 100	NDI 100	
15 315 376 100	CPI 100	
15 317 312 330 015	JT2 UNLC	/CLOSE IF OUT
15 322 315 157 007	CAL TMCK	
15 325 303 311 015	JMP UNL2	
/		
15 330 323 044	UNLC, OUT 44	/CLOSE
15 332 311	RET	
/		
/		
/ RIC TUBE STATUS SUBROUTINE 10 SEPT 75		
15 333 171	RCST, LA C	
15 334 062 056 075	STA HL1	
15 337 056 032	LLI RICW	/LOAD RIC TUBE CONTENTS
15 341 046 075	LHI 'RICW	
15 343 072 036 075	LDA RICP	
15 346 117	LC A	
15 347 006 000	LBI 0	
15 351 011	DDX BC	/CALCULATE ADDRESS OF
15 352 072 056 075	LDA HL1	
15 355 117	LC A	
15 356 311	RET	/CURRENT RIC STATUS
/		
/		
/ RIC IN USE SUBROUTINE 13 JUNE 75		
15 357 056 026	RICU, LLI WST	/W IN USE
15 361 046 075	LHI 'WST	
15 363 076 000	LAI 0	

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15 365 206      AD M
15 366 043      INX HL /X IN USE
15 367 206      AD M
15 370 043      INX HL /Y IN USE
15 371 206      AD M
15 372 043      INX HL /Z IN USE
15 373 206      AD M
15 374 311      RET
/
/
/
15 375 315 357 015 RICF,CAL RICU /# TUBES IN USE          13 JUNE 75
16 000 056 032   LLI RICW /N FULL
16 002 046 075   LHI /RICW
16 004 226       SU M
16 005 043      INX HL /X FULL
16 006 226       SU M
16 007 043      INX HL /Y FULL
16 010 226       SU M
16 011 043      INX HL /Z FULL
16 012 226       SU M /ZERO FULL + NOT FULL
16 013 311      RET
/
/
/
/
START D2 COUNTER          10 SEPT 75
/
16 014 315 323 004 STR2,CAL CBWL /WAIT FOR CANBERRA DISPLAY MODE
16 017 076 000   LAI 0
16 021 062 044 075 STA TIME
16 024 323 102   OUT 102 /ZERO MEMORY
16 026 076 015   LAI 15 /130 MSEC
16 030 062 043 075 STA TMK
16 033 076 010   LAI 10 /100 HZ
16 035 323 100   OUT 100 /FRQSEL RTC
16 037 056 043   LLI TMK
16 041 046 075   LHI /TMK
16 043 072 044 075 TTT, LDA TIME
16 046 226       SU M
16 047 372 043 016 JTS TTT
16 052 323 101   OUT 101 /START D2
16 054 311      RET
/
/
/
/PAUSE FOR RABBIT TO PASS DETECTOR 14 AUGUST 75
/
/
16 055 076 010   PRP,LAI 10 /100 HZ
16 057 323 100   OUT 100 /SET RTC
16 061 076 366   LAI 366 /-100 MSEC
16 063 062 044 075 STA TIME
16 066 072 044 075 PRP1,LDA TIME
16 071 376 000   CPI 0
16 073 302 066 016 JPZ PRP1
16 076 311      RET
/
/
/

```

/SINGLE SAMPLE IRRADIATION AND COUNT 29 OCT 75

```

/
16 077 315 357 015 SS,CAL RICO /CHECK FOR TUBES
16 102 376 000 CPI 0
16 104 314 264 016 CT2 NOTB /NO TUBES
16 107 315 051 013 CAL RICT /GET ACTIVE TUBE
16 112 315 133 010 CAL IRRD /PUT RABBIT IN REACTOR
/
16 115 076 002 LHI 2 /1 HZ
16 117 323 100 OUT 100 /SET RTC
16 121 076 000 LHI 0
16 123 147 LH A
16 124 157 LL H
16 125 042 044 075 STHL TIME /ZERO TIME
16 130 052 024 075 LDHL SIRT
16 133 315 237 016 CAL DPTC
/
16 136 072 035 075 SS2,LDA STAD
16 141 306 016 ADI 16
16 143 062 035 075 STA STAD
16 146 072 272 070 LDA DEL3
16 151 062 046 075 STA DELT
16 154 315 236 012 CAL T12 /RIC>D1
16 157 311 RET
/
16 160 315 077 016 SSIC,CAL 55
16 163 315 306 014 CAL LSD2 /LOAD AND START D2
/
16 166 315 325 004 CAL CBWL /WAIT FOR CANBERRA DISPLAY MODE
/
16 171 323 057 SS4,OUT 57 /TURN OFF SD2 LIGHT
16 173 315 262 011 CAL UND2 /UNLOAD D2
16 176 056 062 SSS,LLI 62
16 200 046 070 LHI 70
16 202 315 247 005 CAL MSG /RUN COMPLETE
16 205 315 265 005 CAL WAIT
16 210 303 265 005 JMP WAIT
/
16 213 315 077 016 SSIC1,CAL 55
16 216 323 047 OUT 47 /PID1 TO PDP9
/
16 220 333 024 SSSS,INP 24 /STW5 FROM PDP9
16 222 346 017 NDI 17
16 224 376 000 CPI 0
16 226 312 220 016 JT2 SSSS
16 231 315 113 014 CAL D1U
16 234 303 176 016 JMP 555
/
/
16 237 174 DPTC,LA H /TWO'S COMPLEMENT H + L 25 AUGUST 75
16 240 057 CMA
16 241 107 LB A
16 242 175 LA L
16 243 057 CMA
16 244 117 LC A
16 245 003 INX BC

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70 007 102	
70 010 102	
70 011 111	
70 012 124	
70 013 040	
70 014 103	
70 015 117	
70 016 116	
70 017 124	
70 020 122	
70 021 117	
70 022 114	
70 023 114	
70 024 105	
70 025 122	
70 026 015	
70 027 012	
70 030 074	TEXT 4 <?
70 031 077	
70 032 015	
70 033 012	
70 034 074	TEXT 13 <NO TUBES
70 035 116	
70 036 117	
70 037 040	
70 040 124	
70 041 125	
70 042 102	
70 043 105	
70 044 123	
70 045 015	
70 046 012	
70 047 074	TEXT 1 <
050 070	*70 50
70 050 127	TEXT 11 WAITING
70 051 101	
70 052 111	
70 053 124	
70 054 111	
70 055 116	
70 056 107	
70 057 015	
70 060 012	
70 061 074	TEXT 17 <RUN COMPLETE
70 062 122	
70 063 125	
70 064 116	
70 065 040	
70 066 103	
70 067 117	
70 070 115	
70 071 120	
70 072 114	
70 073 105	
70 074 124	
70 075 105	
70 076 015	
70 077 012	
70 100 074	TEXT 1 <
110 070	*70 110

70 110 101	TEXT 7 ABORT
70 111 102	
70 112 117	
70 113 122	
70 114 124	
70 115 015	
70 116 012	
70 117 074	TEXT 1 <
150 070	*70 150
70 150 124	TEXT 12 TIME OUT
70 151 111	
70 152 115	
70 153 105	
70 154 040	
70 155 117	
70 156 125	
70 157 124	
70 160 015	
70 161 012	
70 162 074	TEXT 1 <
170 070	*70 170
70 170 114	TEXT 16 LOADER EMPTY
70 171 117	
70 172 101	
70 173 104	
70 174 105	
70 175 122	
70 176 040	
70 177 105	
70 200 115	
70 201 120	
70 202 124	
70 203 131	
70 204 015	
70 205 012	
70 206 074	TEXT 1 <
210 070	*70 210
70 210 110	TEXT 14 HOT SAMPLE
70 211 117	
70 212 124	
70 213 040	
70 214 123	
70 215 101	
70 216 115	
70 217 120	
70 220 114	
70 221 105	
70 222 015	
70 223 012	
70 224 074	TEXT 1 <
250 070	*70 250
	SUBROUTINE TEST ABORT 10 SEPT 75
70 250 333 027	TBRT, INP 27 /TEST FOR TBL ABORT CONDITION
70 252 376 000	CPI 0
70 254 310	RTZ
70 255 072 047 075	LDA ABTF
70 260 376 377	CPI 377
70 262 302 242 007	JFZ ABRT

70 265 303 000 076 JMP ODT

/

/

/

/

/

/

70 270 012 DEL1.#1 12 /DELTA T1 FOR TRANSPORT ROUTINE

70 271 012 DEL2.#1 12

70 272 012 DEL3.#1 12

70 273 000 DEL4.#1 0

70 274 012 DEL5.#1 12

70 275 000 DEL6.#1 0

/

010 075

*75 10 /VARIABLE RANDOM ACCESS 29 OCT 75

75 010 000 000 DEC.#2 /BINARY CODED DECIMAL STORAGE

75 012 000 000 BIN.#2 /BINARY STORAGE

75 014 000 000 SPL.#2 /# OF SAMPLES

75 016 000 000 AIRT.#2 /A IRRADIATION TIME

75 020 000 000 BIRT.#2 /B IRRADIATION TIME

75 022 000 000 CIRT.#2 /C IRRADIATION TIME

75 024 000 000 SIRT.#2 /SSIC IRRADIATION TIME

75 026 000 WST.#1 /TUBE STATUS 1 IN USE 0 OUT OF USE

75 027 000 XST.#1

75 030 000 YST.#1

75 031 000 ZST.#1

75 032 000 RICH.#1 /TUBE CONTENTS 1 FULL 0 EMPTY

75 033 000 RICK.#1

75 034 000 RICV.#1

75 035 000 RICZ.#1

75 036 000 RICP.#1 /TUBE POINTER

75 037 000 D2ST.#1 /D2 STATUS 1 FULL 0 EMPTY

75 040 000 D1ST.#1 /D1 STATUS 1 FULL 0 EMPTY

75 041 000 D1O.#1 /D2 OPERATION 1 IN USE 0 OUT OF USE

75 042 000 D2O.#1 /D2 OPERATION 1 IN USE 0 OUT OF USE

75 043 000 TMK.#1 /TIME CHECK TIME INTERVAL

75 044 000 000 TIME.#2 /RESETTABLE TIMER ACCESSSED BY INTERRUPT

75 046 000 DELT.#1 /DELTA T FOR TRANSIT SEQUENCING

75 047 000 ABTF.#1 /ABORT FLAG 377=ABORTED

75 050 000 PLAA.#1 /PLA ADDRESS

75 051 000 000 BCY.#2 /B CYCLE TIMES

75 053 000 000 BCYM.#2 /B CYCLE COUNTER

75 055 000 STAD.#1 /PLA STARTING ADDRESS

75 056 000 000 HL1.#2 /TEMP 2 BYTE STORAGE

75 060 000 PDF1.#1 /PD1 FAILURE STORAGE

75 061 000 PDF2.#1 /PD2 FIRST FAILURE STORAGE

75 062 000 PDF3.#1 /PD2 SECOND FAILURE STORAGE

75 063 000 000 D2CT.#2 /CANBERRA COUNT TIME

/

\$

ODT	0 000 000 076
CRLF	0 000 021 077
TTY0	0 000 231 077
UCT0	0 000 157 077
TTY1	0 000 300 000
REDT	0 000 317 000
GO	0 000 012 004
GDI	0 000 023 004
DOR	0 000 044 004
GRX1	0 000 054 004
GRX1	0 000 056 004
GRX3	0 000 112 004
GRX2	0 000 120 004
DZ	0 000 143 004
TC	0 000 164 004
RGN	0 000 175 004
DONE	0 000 253 004
ABD2	0 000 270 004
AB	0 000 305 004
CBWL	0 000 325 004
BCD	0 000 345 004
BCD1	0 000 365 004
INVC	0 000 062 005
CONV	0 000 074 005
MA	0 000 115 005
MIB	0 000 122 005
ADIT	0 000 140 005
LNFD	0 000 241 005
MSG	0 000 247 005
MSG1	0 000 252 005
WAIT	0 000 265 005
W1	0 000 333 005
W2	0 000 340 005
W3	0 000 354 005
W4	0 000 370 005
W5	0 000 004 006
ST	0 000 015 006
ONE	0 000 033 006
BDC	0 000 046 006
W6	0 000 060 006
W7	0 000 101 006
W8	0 000 142 006
EXM	0 000 145 006
DET	0 000 172 006
ZERO	0 000 212 006
Z	0 000 218 006
G000	0 000 232 006
IRT	0 000 245 006
IRT1	0 000 271 006
IRT2	0 000 312 006
IRT3	0 000 333 006
IRT4	0 000 354 006
DT1	0 000 375 006
DT2	0 000 014 007
TMS	0 000 030 007
SDM	0 000 047 007
PDK1	0 000 105 007
IST1	0 000 120 007
PK11	0 000 133 007

TM	0 000 151 007
TMCK	0 000 157 007
DIYP	0 000 211 007
DVP1	0 000 225 007
ABR1	0 000 242 007
AB1	0 000 274 007
AB2	0 000 310 007
AB3	0 000 324 007
LDR	0 000 365 007
LDR1	0 000 006 010
PDK2	0 000 023 010
PK23	0 000 041 010
PK24	0 000 046 010
IST2	0 000 054 010
PK21	0 000 071 010
PK22	0 000 117 010
TH1	0 000 125 010
IRRD	0 000 133 010
IRD1	0 000 160 010
RGA	0 000 266 010
RGH1	0 000 306 010
RGH2	0 000 346 010
RGH3	0 000 003 011
RGB	0 000 020 011
RGBH	0 000 026 011
RGB2	0 000 053 011
RGB3	0 000 101 011
RGB3	0 000 116 011
RGB4	0 000 205 011
TRGC	0 000 232 011
UND2	0 000 262 011
TRGC	0 000 334 011
T22	0 000 036 012
TRT	0 000 121 012
TME	0 000 140 012
TRT1	0 000 210 012
T12	0 000 236 012
T21	0 000 326 012
MI	0 000 016 013
MI1	0 000 026 013
RICT	0 000 051 013
RCY1	0 000 063 013
RCY2	0 000 111 013
WRIC	0 000 132 013
XRIC	0 000 140 013
VRIC	0 000 146 013
RGD	0 000 154 013
RGD1	0 000 173 013
RGD2	0 000 230 013
RGD3	0 000 300 013
RGD6	0 000 336 013
RGD7	0 000 344 013
RGD8	0 000 364 013
RGD8	0 000 376 013
RGD9	0 000 055 014
RGDZ	0 000 070 014
D1U	0 000 113 014
EXMC	0 000 155 014
EXM1	0 000 202 014

EXH2	0 000 245 014
LSD2	0 000 306 014
EXMT	0 000 361 014
XMT1	0 000 013 015
XMT2	0 000 054 015
XMT3	0 000 060 015
XMT4	0 000 154 015
SPD	0 000 224 015
UNL	0 000 254 015
UNL1	0 000 273 015
UNL2	0 000 311 015
UNLC	0 000 330 015
RCST	0 000 333 015
RICU	0 000 357 015
RICF	0 000 375 015
STR2	0 000 014 016
TTT	0 000 043 016
PRP	0 000 055 016
PRP1	0 000 066 016
SS	0 000 077 016
SS2	0 000 136 016
SSIC	0 000 160 016
SS4	0 000 171 016
SSS	0 000 176 016
SSIC1	0 000 213 016
SSSS	0 000 220 016
DPTC	0 000 237 016
TC61	0 000 246 016
NOTE	0 000 264 016
TMST	0 000 301 016
TM51	0 000 327 016
TM52	0 000 337 016
TBRT	0 000 250 070
DEL1	0 000 270 070
DEL2	0 000 271 070
DEL3	0 000 272 070
DEL4	0 000 273 070
DEL5	0 000 274 070
DEL6	0 000 275 070
DEC	0 000 010 075
BTW	0 000 012 075
SPL	0 000 014 075
RIRT	0 000 016 075
BIRT	0 000 020 075
CIRT	0 000 022 075
SIRT	0 000 024 075
WST	0 000 026 075
XST	0 000 027 075
VST	0 000 030 075
ZST	0 000 031 075
RICW	0 000 032 075
RICX	0 000 033 075
RICY	0 000 034 075
RICZ	0 000 035 075
RICP	0 000 036 075
D2ST	0 000 037 075
D1ST	0 000 040 075
D10	0 000 041 075
D20	0 000 042 075
TMK	0 000 043 075

TIME	0 000 044 075
DELT	0 000 046 075
ABTF	0 000 047 075
PLAA	0 000 050 075
BCY	0 000 051 075
BCYM	0 000 053 075
STAD	0 000 055 075
HL1	0 000 056 075
PDF1	0 000 060 075
PDF2	0 000 061 075
PDF3	0 000 062 075
D2CT	0 000 063 075

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